

# Space Debris Research at JAXA



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**2019.2.18**

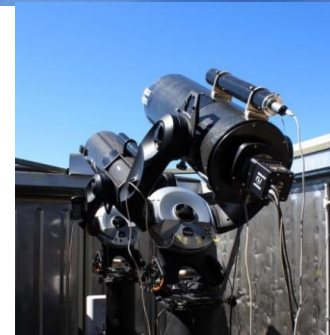
**JAXA**

- Observation
- Modeling
- In-Situ Measurement of Small Debris
- Active Debris Removal (ADR)
- Ground Testing
- Related Topics

(1) **Remote observation** site in Australia

3 20-cm class telescopes were installed at Siding Spring Observatory in **Australia**. GEO and LEO observations are possible.

**Collaborative observation with CNES was carried out.**

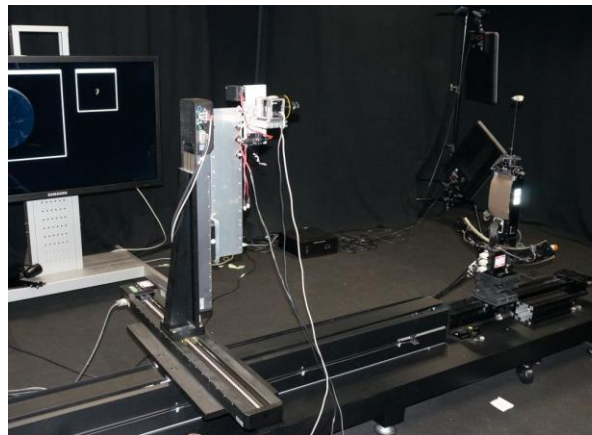


Remote observation site in Australia

(2) **Light curve simulation for ADR**

Optical simulator of JAXA was modified to **simulate light curve of ADR targets**.

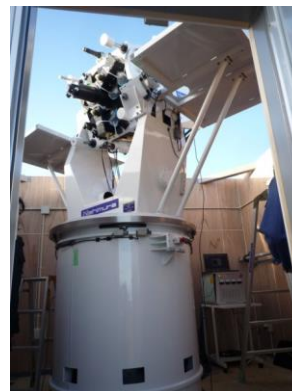
Technologies of motion and attitude estimation will be developed using scale model of the targets.



Optical simulator set for artificial light curve

(3) **Direct imaging of ADR targets**

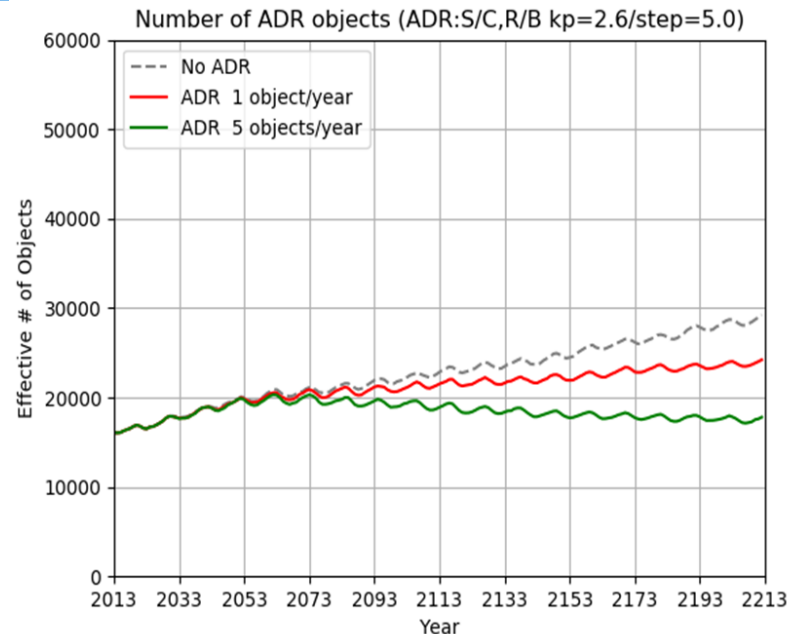
The 60cm telescope at Mt.Nyukasa Observatory was modified for **direct imaging of ADR targets**. Shack-Hartmann sensor was installed to monitor the atmospheric condition of the site, which will be used to develop the optimum **adaptive optics system**.



60cm telescope for direct imaging of ADR targets

## (1) Debris evolutionary model

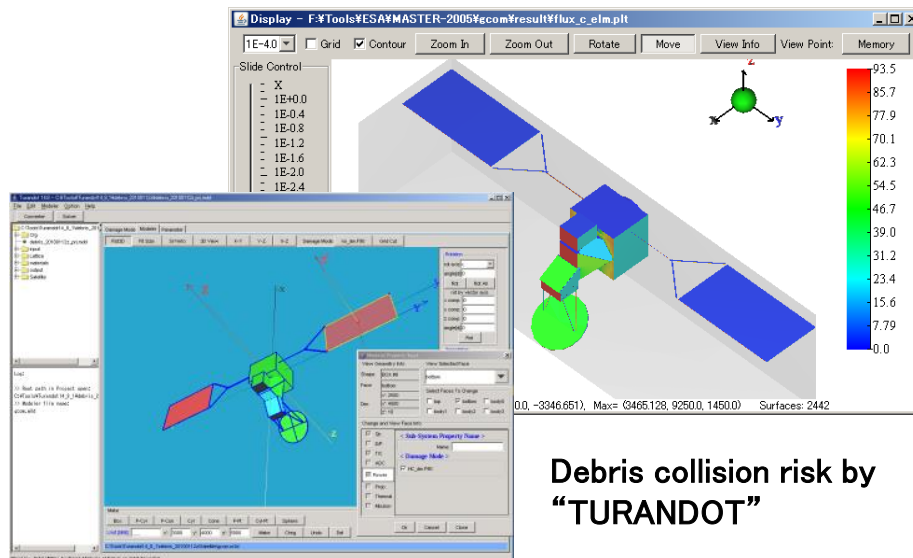
- **NEODEEM** (Near-Earth Orbital Debris Environment Evolutionary Model) developed in collaboration with Kyushu University
- **To evaluate effective mitigation measures**
- **To select active debris removal targets**



Debris population prediction by “NEODEEM”

## (2) Debris collision risk assessment tool

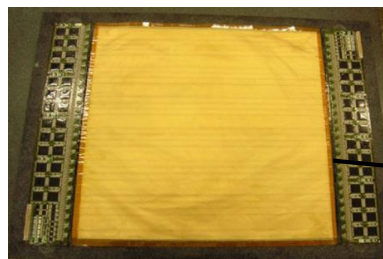
- **Turandot** (Tactical Utilities for Rapid Analysis of Debris on Orbit Terrestrial)
- **To predict spacecraft damage probability by collisional debris** including shielding effect of the spacecraft itself
- Users can choose MASTER-2009 or ORDEM 3.0 as database of debris flux



Debris collision risk by “TURANDOT”

## In-situ measurement

- **SDM** (Film-perforation type debris sensor) was developed for in-situ measurement of MMOD.
- Flight demonstration of SDM was conducted on **HTV-5/ISS**.
- In-flight SDM detected a debris of 100 $\mu$ m in size.



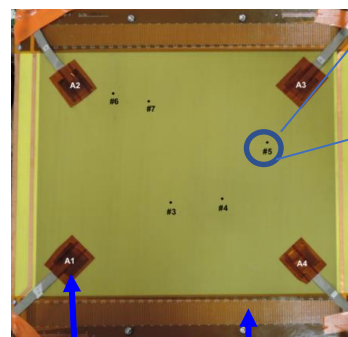
SDM



HTV-5

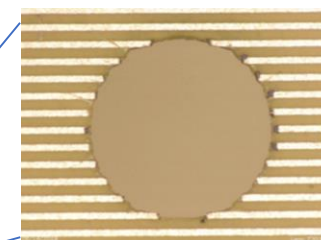
## International Collaboration

- **By combining JAXA's sensor and NASA's sensor, it was confirmed it can be a system to measure collision frequency, size, direction, speed, mass, etc. of debris**



NASA Sensor  
(Acoustic sensor)

JAXA Sensor



Perforation hole.  
(projectile: Al, 1060 $\mu$ m)



(1) **Rendezvous technology** to non-cooperative space debris

➤ Onboard real-time image navigation

**Robust onboard real-time navigation** using deep learning based pose estimation.

**High fidelity ground test environment** for onboard image navigation.

(2) **Capture technology** for non-cooperative large intact space debris

➤ Dedicated capture mechanism

Mechanism to capture slowly **rotating rocket upper stage**.

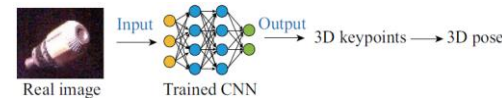
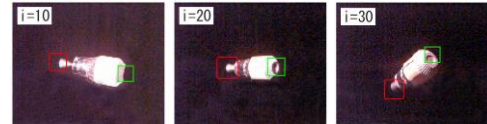
**High fidelity ground test facility.**

(3) **Efficient propulsion system** to remove large intact space debris

➤ Efficient electric propulsion

Novel efficient electric propulsion to transfer large intact space debris into graveyard or reentry orbits.

Deep learning based pose estimation



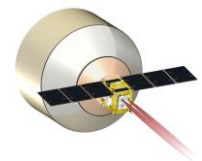
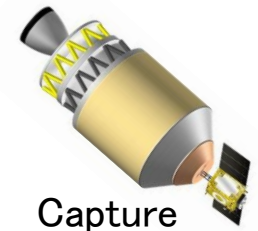
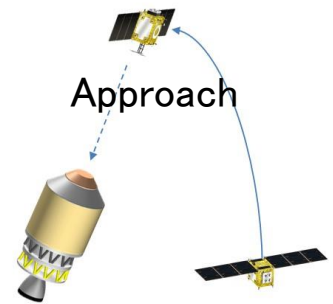
Mechanism to capture payload attachment Fitting (PAF) of upper stages



Efficient electric propulsion system such as hall effect thruster



Mission concept



Removal

## Rendezvous Technology

- Fault Tolerant System Design
- Safe Trajectory Design
- Operational Consideration



**HTV-7  
Rendezvous  
2018.9.27**

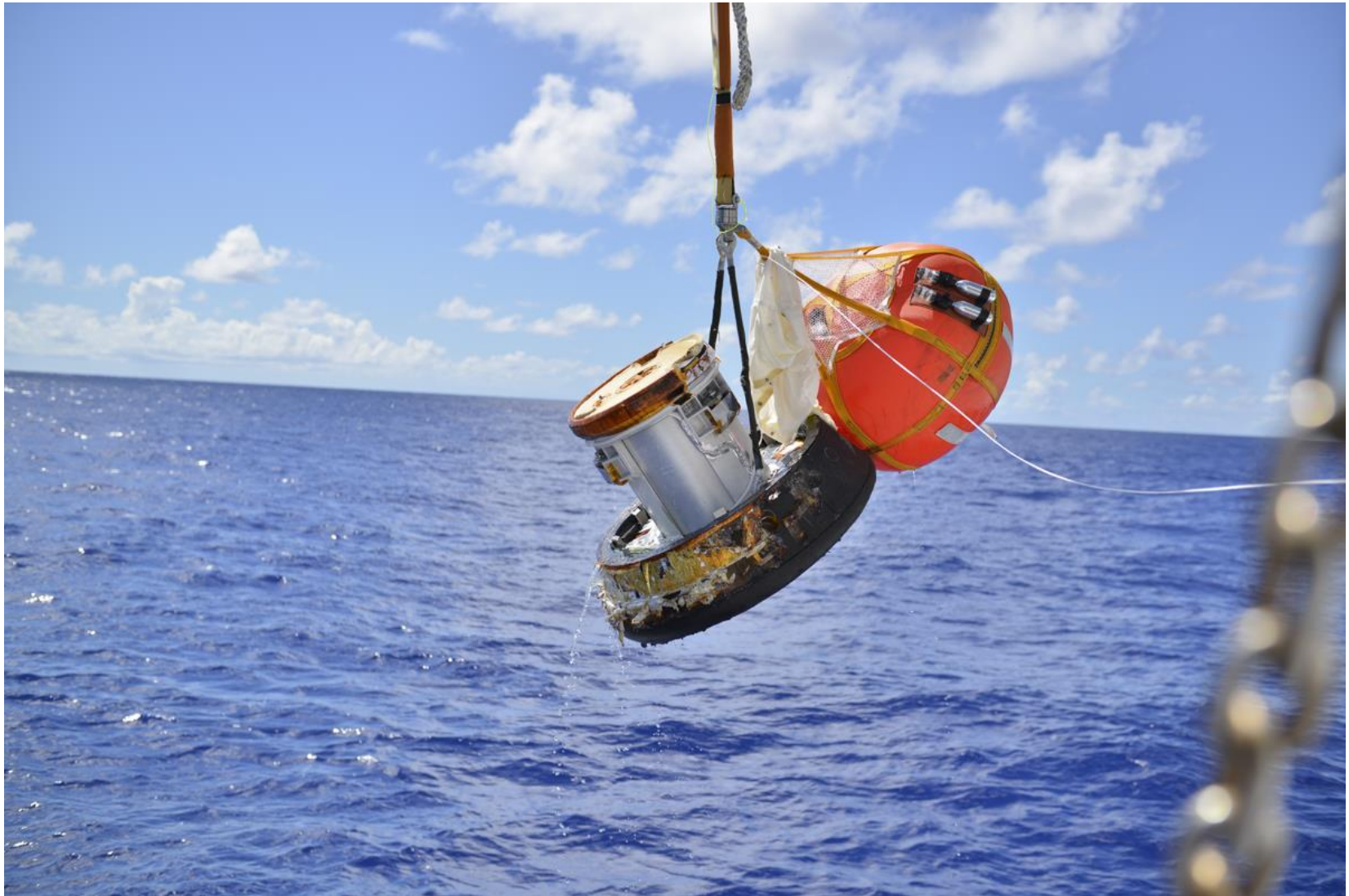
## Safe Departure and Reentry Technology

- Separation
- Departure
- Deorbit
- Reentry



**HTV-7**  
**Departure and**  
**Reentry**  
**2018.11.11**





HTV7 Reentry Capsule, 2018.11.11





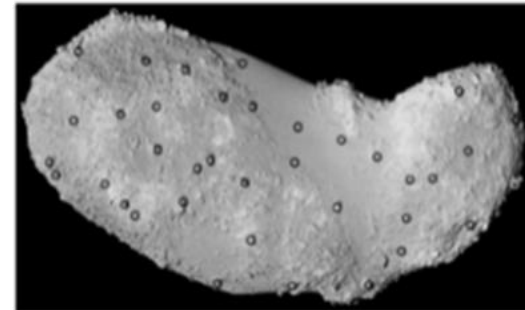
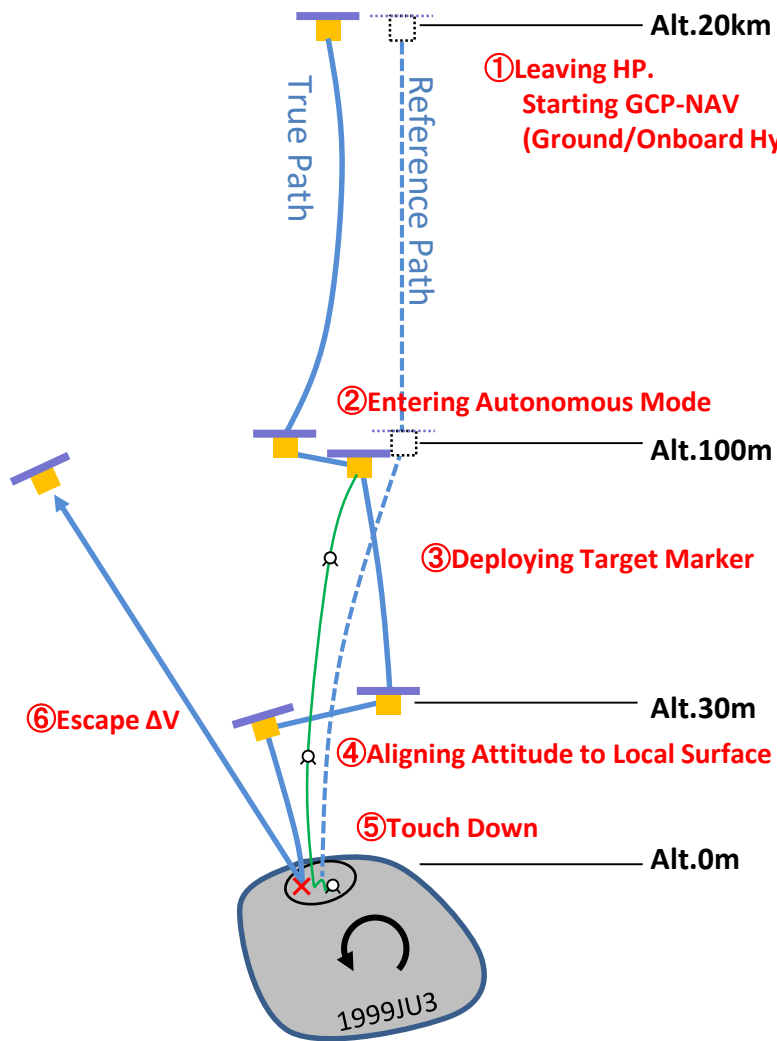
# Hayabusa2 – Sample Return and Kinetic Impact Mission to Near-Earth Asteroid Ryugu



*Ascentics*

*Ascentics*

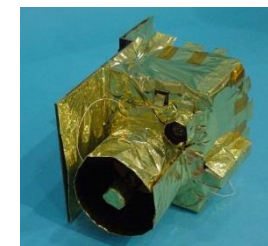
# Hayabusa-2 Proximity Operation



“GCP” Landmark based navigation



ONC



LIDAR

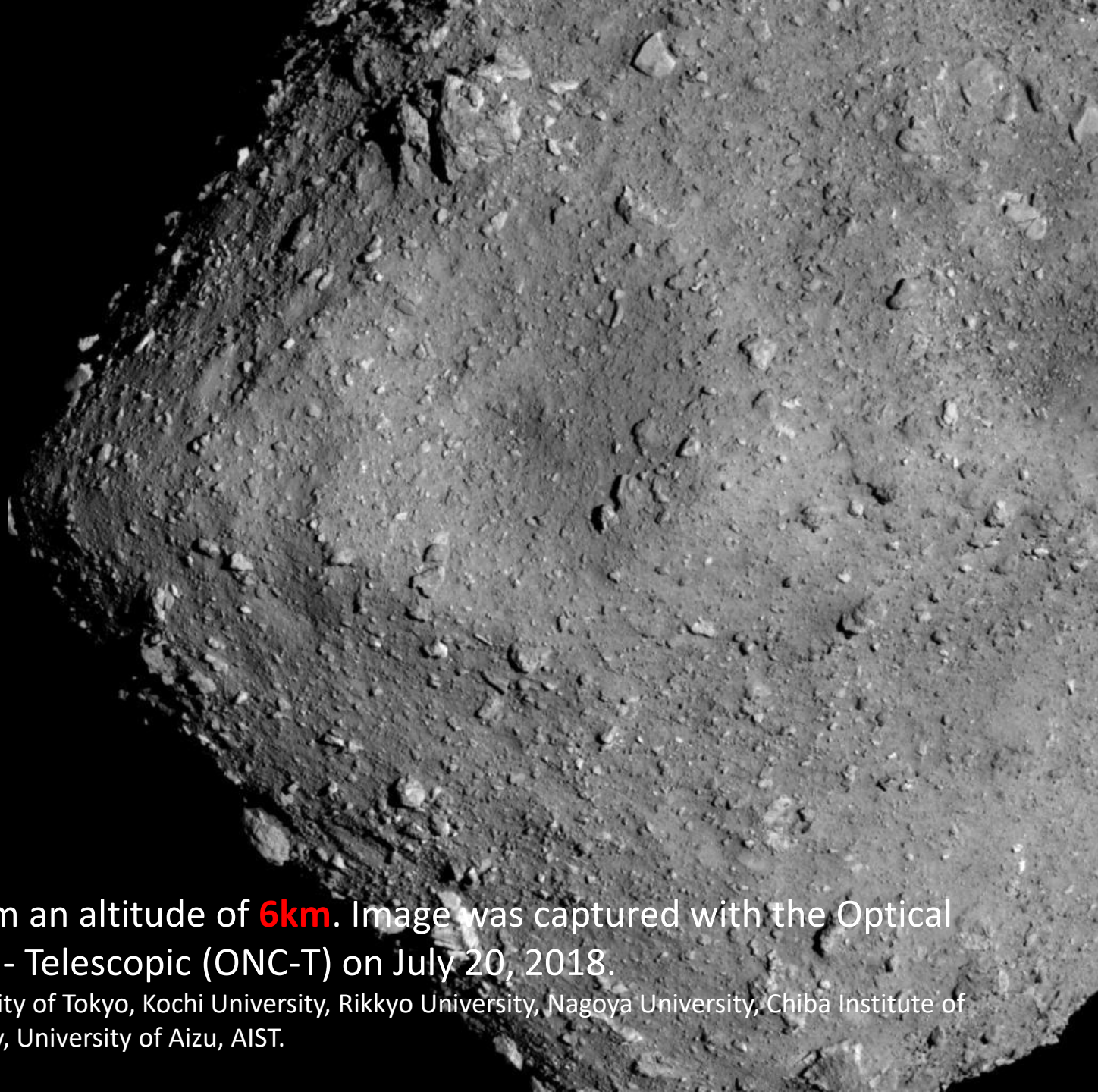


Target Markers & FLASH



LRF

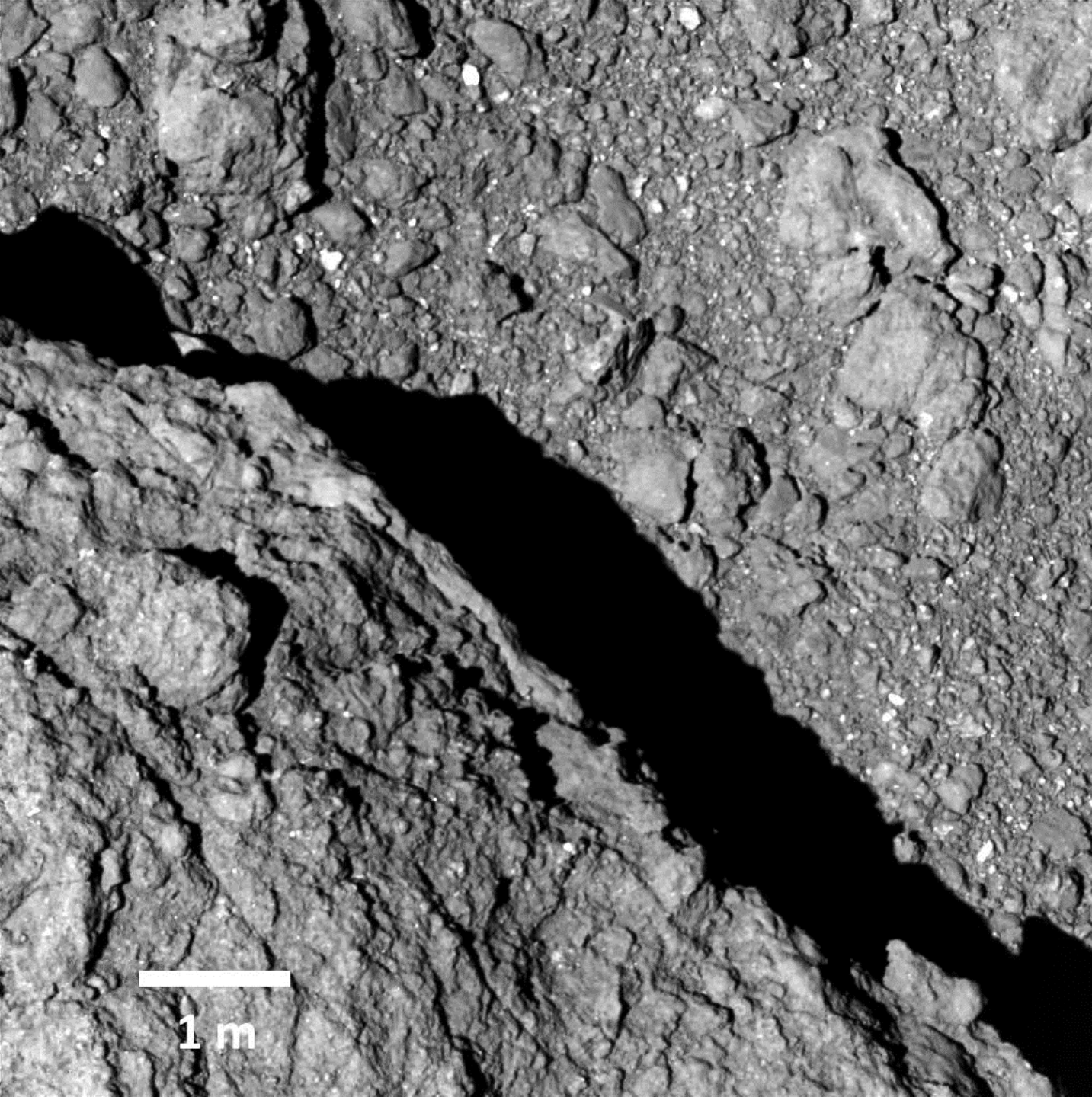




Asteroid Ryugu from an altitude of **6km**. Image was captured with the Optical Navigation Camera - Telescopic (ONC-T) on July 20, 2018.

Image credit: JAXA, University of Tokyo, Kochi University, Rikkyo University, Nagoya University, Chiba Institute of Technology, Meiji University, University of Aizu, AIST.





Altitude about **210 feet (64 meters)**

Sept. 21, 2018

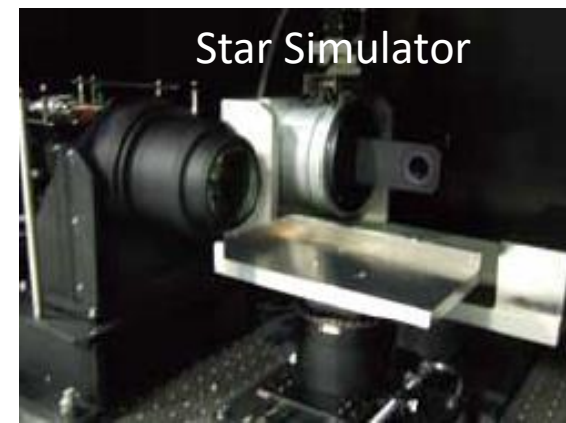
*Credit: JAXA, University of Tokyo, Kochi University, Rikkyo University, Nagoya University, Chiba Institute of Technology, Meiji University, Aizu University, AIST*

# Ground Test Facility





# Ground Test Facilities (Cont'd)





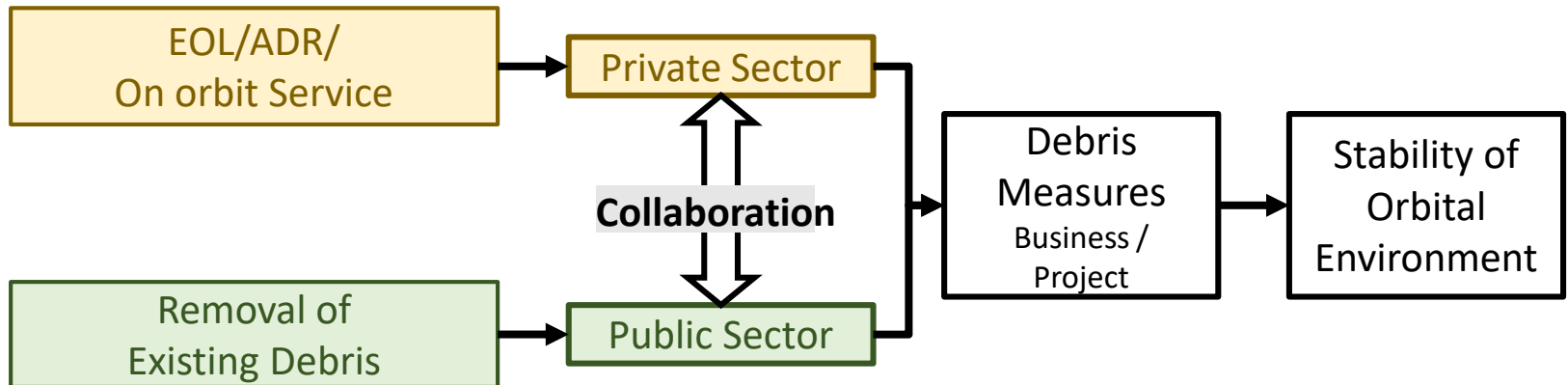
# Orbit



# Ground

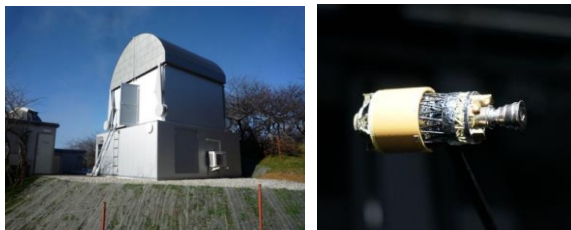


- Continue researches for removing large space debris.
- Partner with private sectors; by joint programs including research, ground testing, demonstration in orbit and so on.

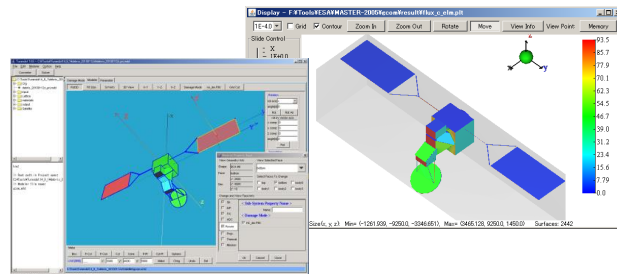


Project	ADR Project Target; Debris from JAXA
System Demonstration	ADR System Demonstration
Key Technology	R&D Rendezvous / Observation, etc

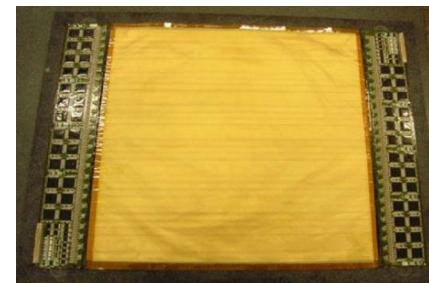
## Observation



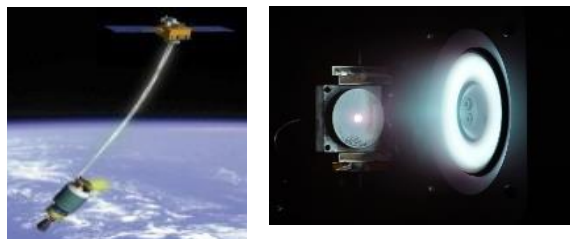
## Modeling



## In-Situ Measurement



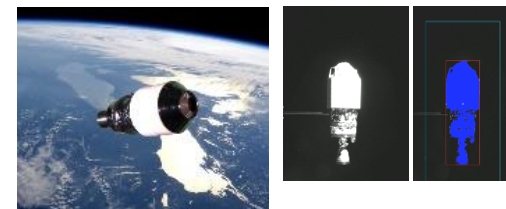
## Propulsion



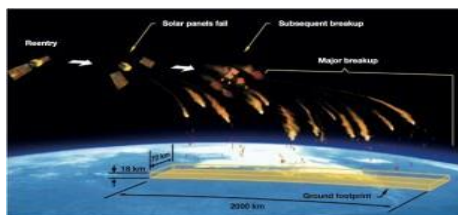
## Capture



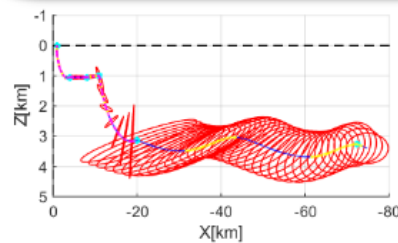
## Rendezvous



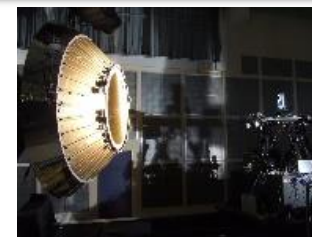
## Deorbit & Safe Reentry



## Numerical Simulation



## Ground Testing



- **JAXA continues researches on both technical and non-technical aspects.**
- **JAXA contributes continuously to the cooperation with international partners.**
- **JAXA will partner with private sectors in joint programs including research, ground testing, demonstration in orbit etc. utilizing JAXA's experience and lessons learned.**