

GNSS Timing monitoring with calibrated receivers at ESA

ESA ESTEC

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Background and Objectives

(multi-)GNSS calibration is required for

- System level: Generation of System Time Offsets (GGTOs), UTC-GNSS parameters ...etc...
- User level: GNSS-Time transfer and dissemination at the few ns level, traceability...

Multi-GNSS Timing Monitoring is required for

- Consistency check/assessment of system timing performance (GGTO, UTC, DCB...)
- Estimation of inter-system biases for e.g. interoperability

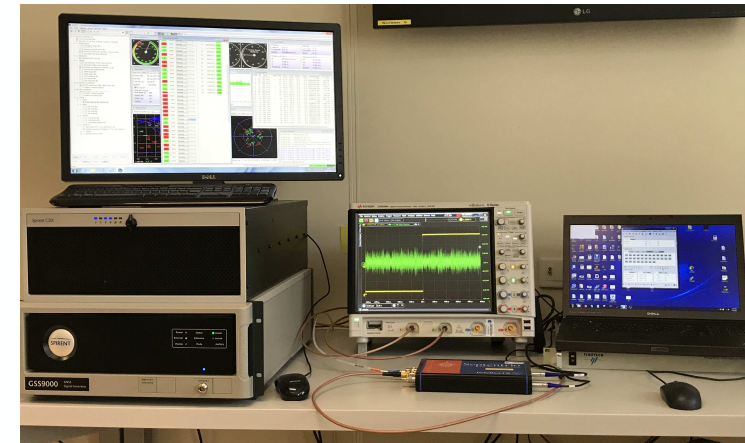
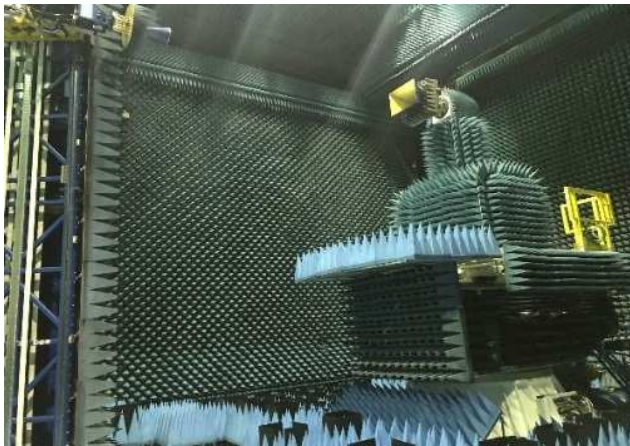
Objectives:

To have independent capabilities (equipment, tools, processes, know-how...) for the continuous monitoring of multi-GNSS timing performance at the ~ns level

Multi-GNSS Calibration

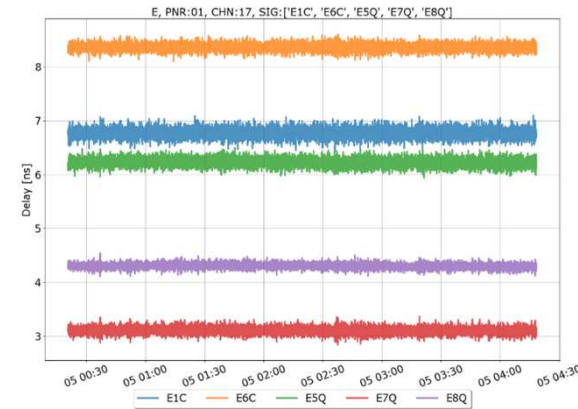
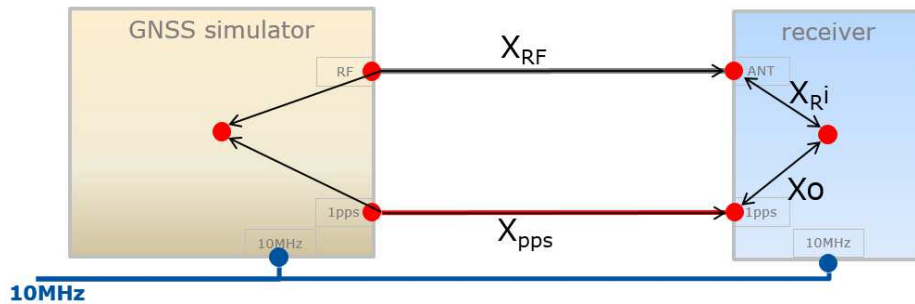
Based on consistent measurement/processing of absolute delay measurement:

- Antenna: Group-Delay measurement in anechoic chamber
- Antenna Cable: Vector Network Analyser
- Receiver: GNSS Simulator



Multi-GNSS Calibration

Receiver absolute Calibration:



Receiver Delay for signal component i:

$$X_{Ri} = (PR_i - D_{sim})/c - (X_{RF} - X_{pps})_i + X_0$$

PR_i: measured pseudorange

D_{sim}: Simulated pseudorange

X_{RF}, X_{pps}: cable delays

Constellation/Signals covered:

- GPS: L1C/A, L1P, L2P, L5
- GAL: E1, E6, E5a, E5b, E5
- GLO: L1C, L2C, L1P, L2P
- BDS2: B2i, B3I, B1i
- BDS3: B2a, B2b, B3I, B1C
- NavIC: L5 → **New**

Multi-GNSS Calibration



Uncertainty Budget, Test and Validation:

- Detailed uncertainty budget
- Several test campaign conducted
- Several Receiver types/brands tested
- Validation campaign with CNES absolute calibration*
- Validation campaign against relative calibration
- Overall agreement/consistency at the 1~2ns level

Uncertainty	Type	Description	Value (ps)
Sim_noise	A	Measurement Noise (std over 16 runs/PRNs)	50 to 350
Sim_resol	B	Oscilloscope Resolution (10GSps)	100
Sim_trigger	B	Oscilloscope Trigger error (specs)	15
Sim_config	B	Simulator output power effects (tests)	100
Sim_filter	B	Correlator low-pass filter effects (test)	100
PR_noise	A	Pseudorange Noise (std of the PR differences)	10 to 155
PR_icb	B	Receiver inter-channel biases (test)	10
PR_agc	B	Receiver AGC-dependant biases (test)	100
PR_temp*	B	Thermal effects on receiver (test)	200
LD	A	LD measurement noise (conservative assumption)	40
LD	B	Receiver autocalibration (test)	300
TOTAL:			418 to 564

* IEEE IFCS-EFTF 2019, “Cross-calibrations of multi-GNSS Receiver Chains”, ESA, CNES



Multi-GNSS Calibration

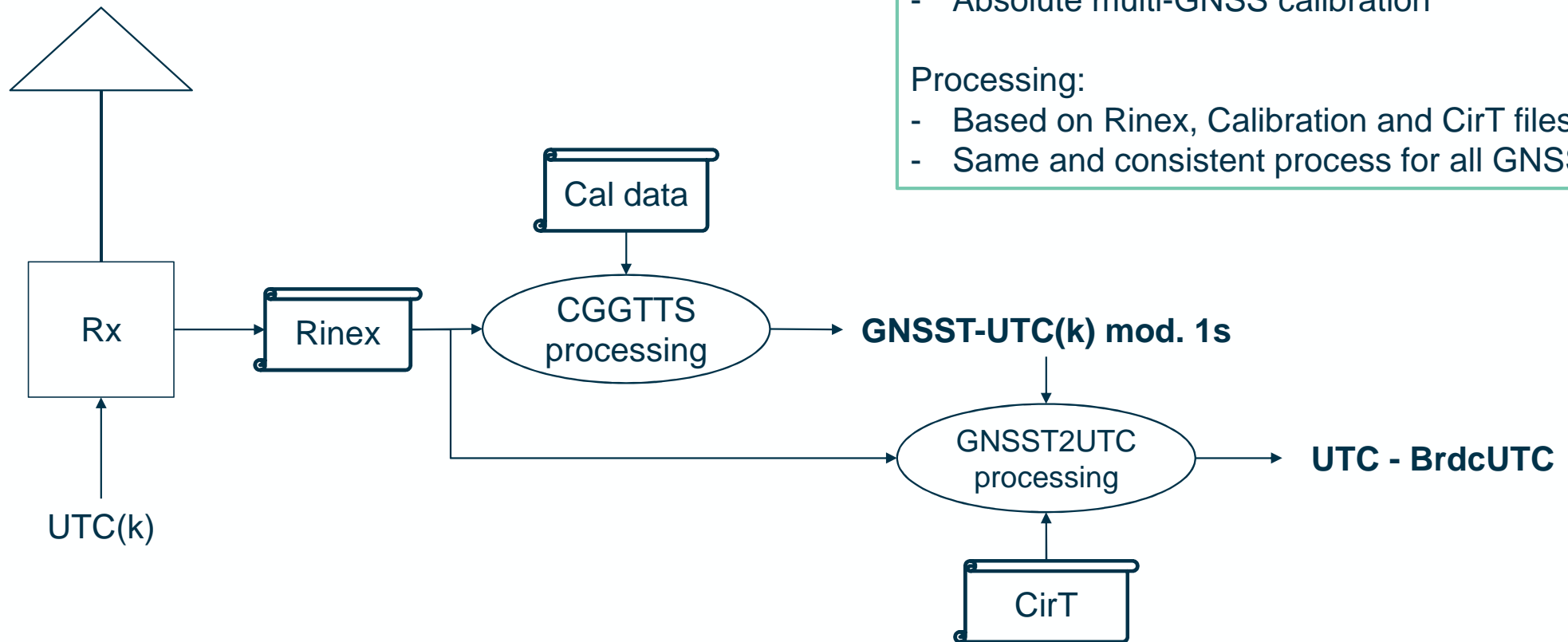
Results (example: BP27, calibrated for the BIPM):

		BP27			
		FW 3.2.0		FW 5.4.0	
Signal		value	uncert.	value	uncert.
GPS	L1C C1C	11.16	0.48	11.45	0.48
	L1P C1W	10.83	0.45	11.11	0.45
	L2P C2W	10.19	0.47	10.49	0.47
	L5Q C5Q	10.90	0.42	11.19	0.42
GAL	E1C C1C	11.26	0.42	11.56	0.42
	E5Q C5Q	10.89	0.44	11.20	0.44
	E7Q C7Q	7.11	0.43	7.40	0.43
	E8Q C8Q	8.88	0.45	9.18	0.45
	E6C C6C	6.82	0.47	7.13	0.47
BDS-2	B1I C2I	4.22	0.54	4.51	0.54
	B2I C7I	6.79	0.53	7.09	0.53
BDS-3	B1C C1P			11.29	0.44
	B2A C5P			11.29	0.52



Multi-GNSS Timing Monitoring

Principle:



Receiver Chain:

- Fixed multi-GNSS receiver
- Absolute multi-GNSS calibration

Processing:

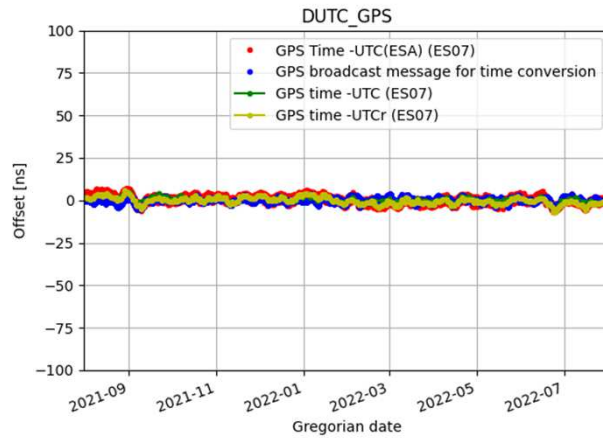
- Based on Rinex, Calibration and CirT files
- Same and consistent process for all GNSS

Multi-GNSS Timing Monitoring

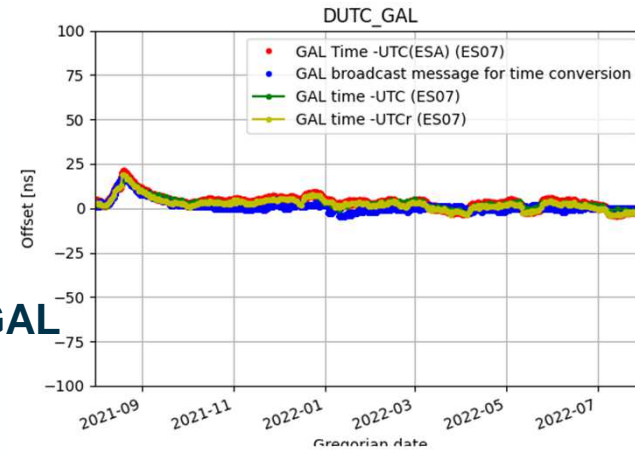


GNSSTime – UTC (modulo 1sec), Aug-2021 to Aug-2022

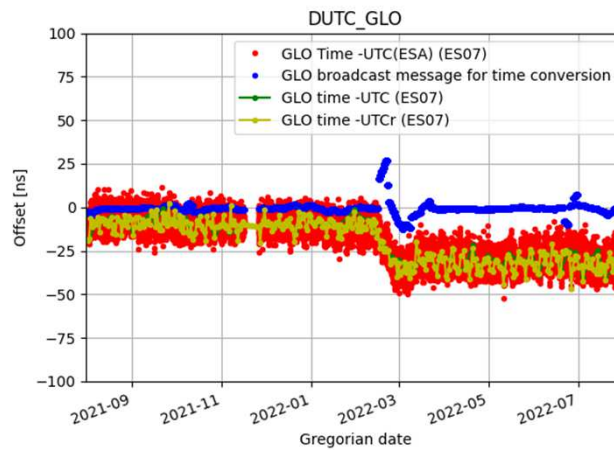
GPS



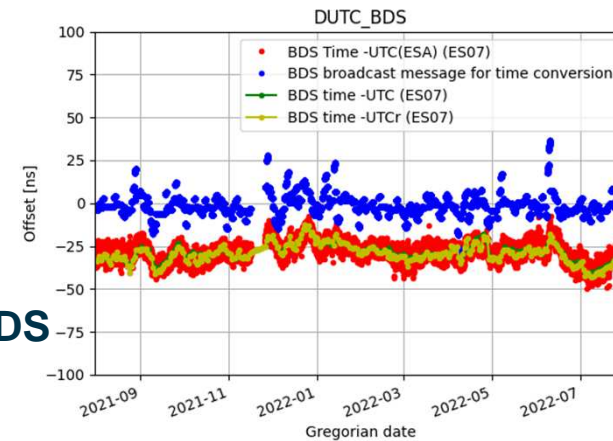
GAL



GLO



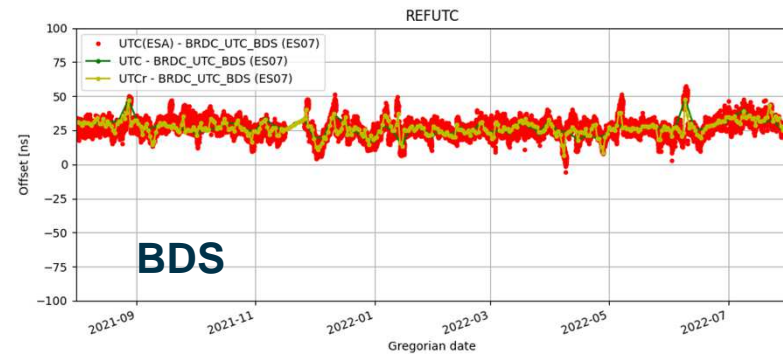
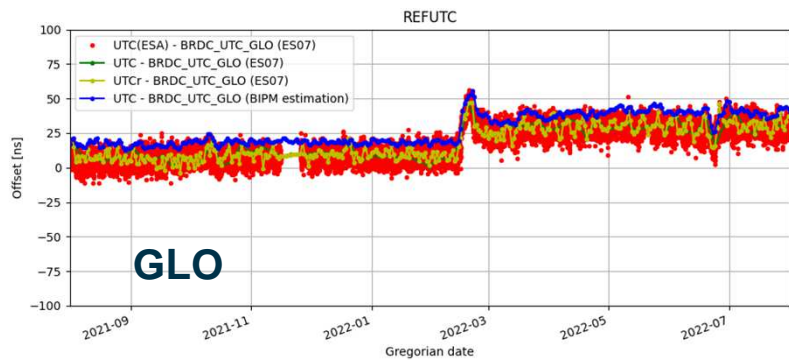
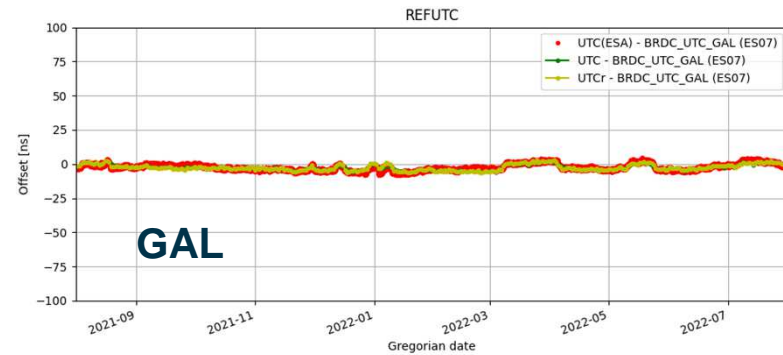
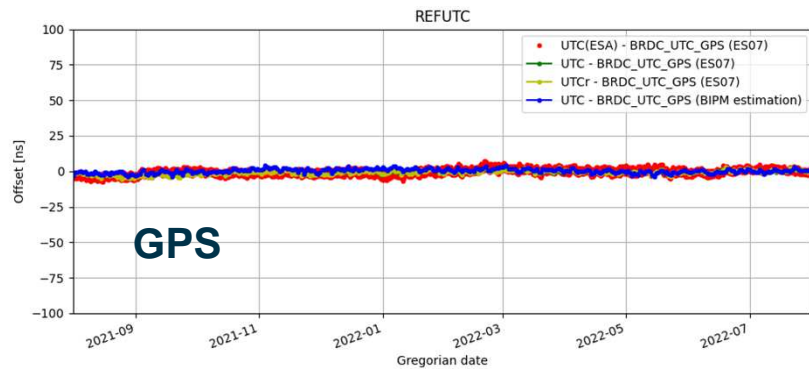
BDS



Multi-GNSS Timing Monitoring



UTC – BrdcUTC, Aug-2021 to Aug-2022



Conclusions, Outlook

Multi GNSS calibration

- Equipment, tools and processes available for multi-GNSS receiver chain calibration
- Covers all operational GNSSes
- Validation campaign demonstrated agreement/consistency at the 1~2ns level

Multi-GNSS Timing Monitoring

- Consistent tools and processes available for multi-GNSS timing monitoring
- Covers all operational GNSSes (NAViC to come soon)
- Observed GLO and BDS inconsistencies need further investigations

Outlook

- Implement NAViC in routine processes
- Investigate observed inconsistencies
- Further validate tools and processes, in particular with non-EU entities