

# AN EXAMPLE OF TERRESTRIAL REFERENCE FRAME REALISATION: GERMANY

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FIG Commission 5: Positioning and Measurement / University of Stuttgart, Institute of Engineering Geodesy





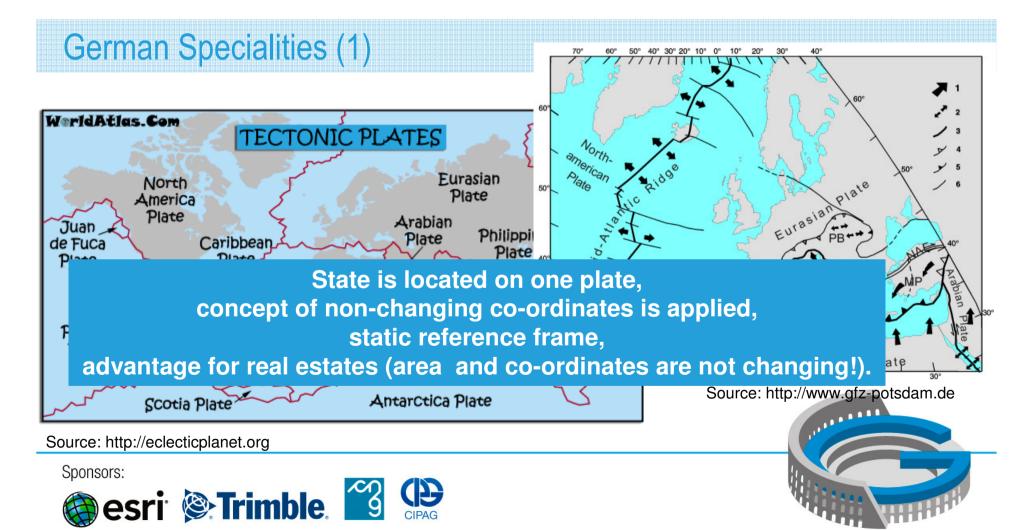


#### Structure

- German Specialities
- Definition of Reference Frame
- Realisation of Reference Frame
- GNSS CORS Networks
- GREF
- Control and Maintenance
- Summary









#### German Specialities (2)

- •Surveying / Geodesy is under the responsibility of the federal states:
- •16 state surveys with their respective responsibilities
- Bundesamt f
  ür Karthographie und Geodäsie (BKG / Federal Agency for Carthography and Geodesy) is reponsible for maintaining the German Reference Frame





## **Definition of Reference Frame**

May fixed co-ordinates result in problems, since GNSS orbits are given in respective current IGS realisation?

Relative GNSS currently without problems, absolute solutions (e.g. PPP) have to consider transformations to ETRS89.

#### Current Reference Frame

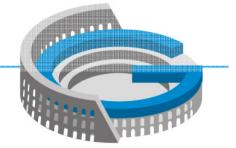
1991: ETRS89 was established as reference system, using GRS80 ellipsoid;

co-ordinates were fixed on values of 01.01.1989 (ETRF89)

(despite of 25 mm per year north-east movement)

1995: UTM was established as mapping projection





## **Realisation of Reference Frame**

- DREF91 (German Reference Frame 1991)
- Densification of 15 German ETRF89 / EUREF points (A-network) by 84 new points (B-network)
- Accuracy of 1 2 cm horizontal and 2 4 cm vertical
- Further densification under the responsability of the different state surveys (C-network);
   e.g. in North Rhine Westphalia: 169 points with 15 20 km point density
- A-, B- and C-networks are hierachical adjusted
- Some stresses occur due to the available satellite configuration and measurement technique in these years, especially in the height component





## **Realisation of Reference Frame**

- SAPOS (Satellitenpositionierungsdienst der deutschen Landesvermessung / Satellite Positioning Service of the German State Survey) is the CORS network of the German federal states
- Positioning is based on one least-square adjustment solution of one week GPS data (epoch 2002.79) for all 260 SAPOS sites including 8 IGS sites
- Stress-free 1-cm accurate network, homogeneous within Germany, taylored to DREF91 solution, discrepancies to neighbooring countries
- Coordinate changes up to 4 cm horizintal and 5 cm vertical with respect to DREF
- Since 2003 valid for all federal states





## **GNSS CORS Networks in Germany**

- **SAPOS** Official Provider of German Reference Frame
  - under the responsability of 16 state surveys
  - service for state and commercial users
  - network solutions for all Germany in real time, connection to neighbouring countries

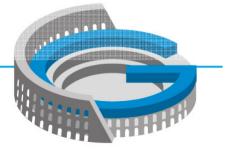
**Alternative CORS Networks Services** 

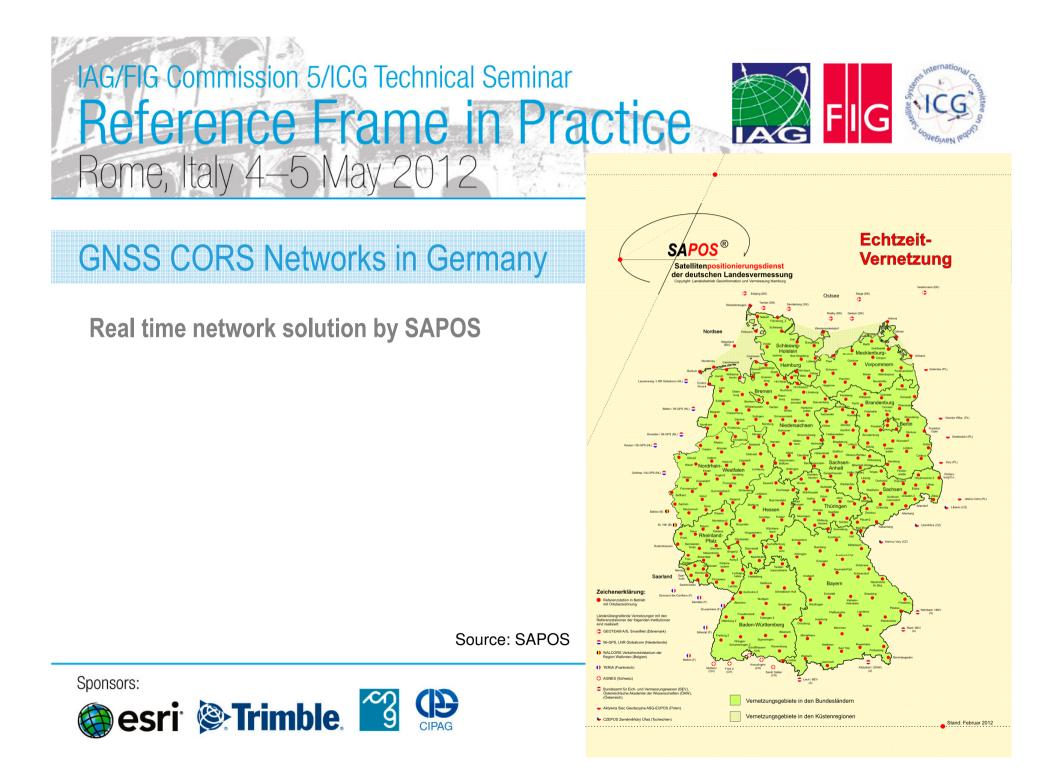
ASCOS - Allsat and EADS

Trimble VRS Now

SmartNet Germany - Leica



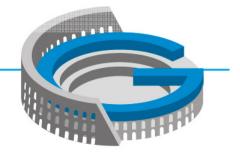




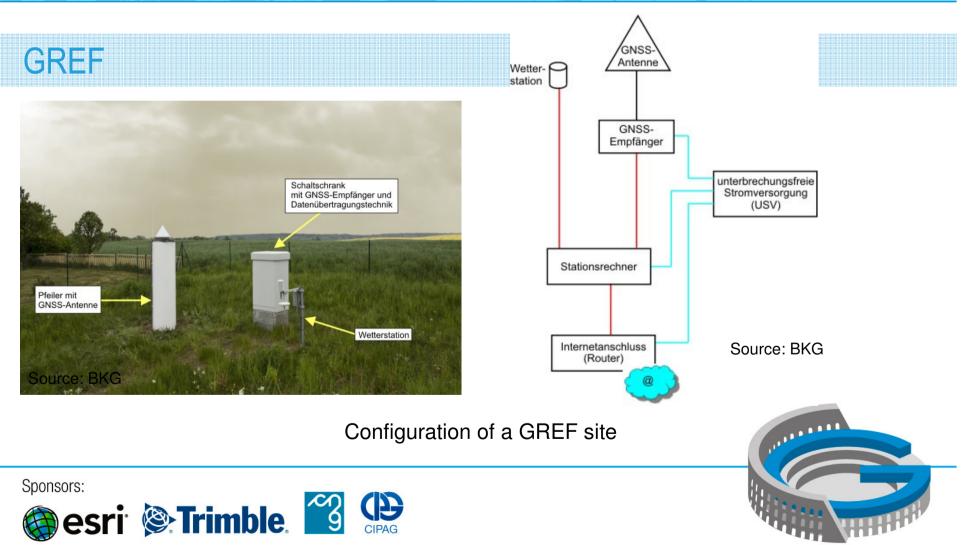
# IAG/FIG Commission 5/ICG Technical Seminar Reference Frame in Practice Rome, Italy 4–5 May 2012

## **GREF – Integrated Geodetic Reference Network for Germany**

- Around 30 CORS sites, 25 of them are operated by BKG (built up from 2001 to 2007)
- Co-ordinate accuracy: < 0.5 cm horizontal and < 1 cm vertical
- Part of superior networks: EPN and IGS
- Connection to German height and gravity networks as well as gauges
- GPS and Glonass measurements
- Integrated into SAPOS service
- GREF and SAPOS data is evaluated together regulary by BKG to maintain a homogeneous network for Germany









#### GREF

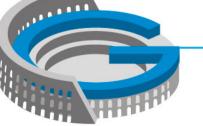


Site on the island Borkum (north see)



FIIG

All sites regularly evaluated







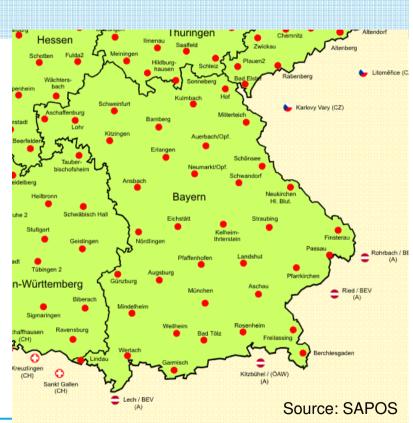
#### **Control and Maintenance**

#### **SAPOS Bavaria**

has established some tools for monitoring SAPOS and the Reference Frame: Co-ordinate monitoring, RTK-peformance, Network reports.

Other federal state surveys have developped or are developping similar services.





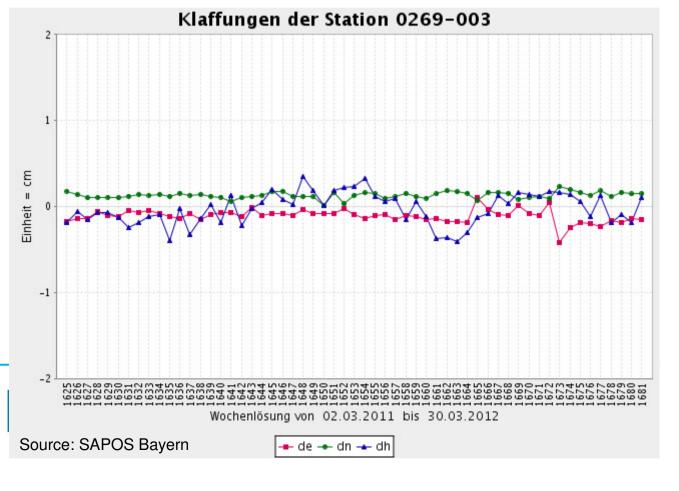




#### **Control and Maintenance**

**Co-ordinate Monitoring** All reference site co-ordinates are automatically determined using the Bernese software in a multi-site-solution. The results are published in the web.

Example: site 0269 / Wertach







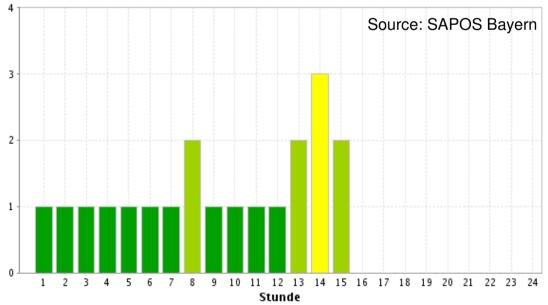
#### **Control and Maintenance**

#### **RTK Performance Monitoring**

Currently 3 RTK sites that show large distance to other SAPOS sites are performing continously positioning within the RTK service (40 fixes per hour). The results are summraized in a hourly RTK -Performance Index and published in the web.

#### orange / yellow / light green / green:

Hz: 33% > 3 cm / 67% > 3 cm / 90% > 3 cm / 90% > 2 cm Vt: 33% > 5 cm / 67% > 5 cm / 90% > 5 cm / 90% > 3 cm TtF: 33% > 3 min / 67 % > 3 min / 90% > 3 min / 90% > 1 min



#### RTK-Performance-Index





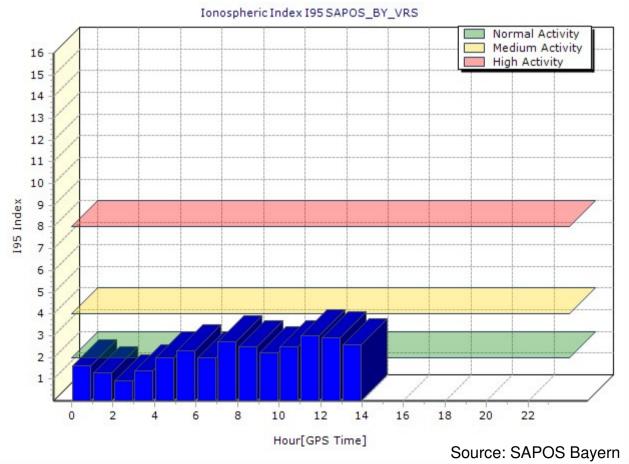
#### **Control and Maintenance**

#### **Network Reports**

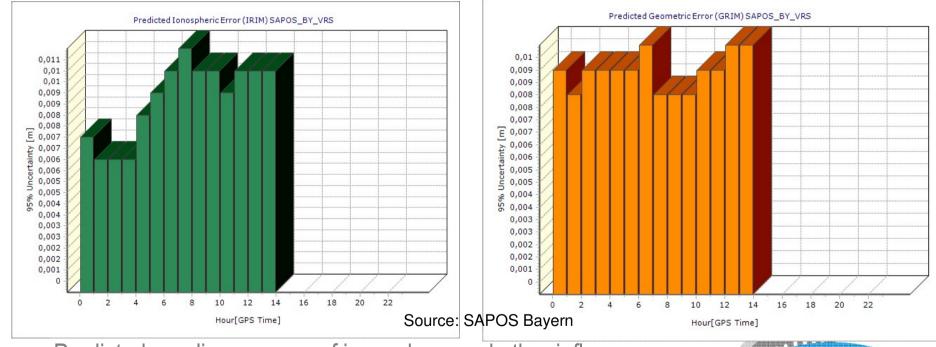
Core element of SAPOS is the network solution that reduces the distance dependent errors of GNSS.

Network report summarize in hourly solutions ionospheric information, as well as predicted remaining errors.





### **Control and Maintenance**



Predicted non-linear errors of ionosphere and other influences







## Summary

- Long history regarding reference frames
- Since the ninties: ITRF / ETRF89 based reference frame
- Static refernce frame, since no relative movements occur
- Realisation nowadays by CORS network SAPOS
- GREF integrates German 3D reference frame into superior systems as well as
   national height and gravity networks
- Co-ordinates are controlled regulary on national and federate state level
- Real time control of solutions is transparently realised



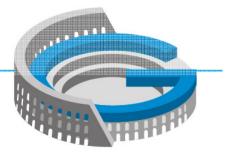




### References

- B. Görres (2010): Vom globalen Bezugssystem bis zur Umsetzung in der Praxis. In: GNSS 2010 - Vermessung und Navigation im 21. Jahrhundert, DVW-Schriftenreihe Bd.63, S. 39-57, Wißner-Verlag Augsburg.
- B. Görres, M. Meyer, A. Nothnagel, B. Heck (2012): DVW-Merkblatt zu GNSS Bezugssystemen (in discussion).
- •<u>www.sapos.de</u>
- <u>http://www.zentrale-stelle-sapos.de/</u>
- <u>https://sapos.bayern.de/</u>
- www.bkg.bund.de







Thank you very much for your attention ! Feel free to address your questions !

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