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INSTITUTE OF SPACE DEVICE ENGINEERING



## Signal Quality Monitoring

**Authors: Yury Yaskin, General Director, Chief  
designer.**

**Valeriy Tyubalin, Deputy Chief designer**

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## **Avnues of development:**

**1. Controlling ephemeris information through monitoring station network of differential correction and monitoring system (SDCM).**

**2. Mobile equipment serves to control the GLONASS and GPS navigation signals. It is used for testing vehicles equipped with satellite navigation equipment.**

**3. Fixed equipment serves to control navigation signals in time and spectral domains, and power characteristics of navigation signals.**

**Mobile equipment to control the GLONASS and GPS navigation signals (MECNS). The hardware composition.**







## Mobile MECNS . Software. Constellation characteristics forecasting .

Forecasting is based on the GLONASS and GPS almanacs.

Any point can be defined on the world map – performance forecasting will be provided for it exactly.

Forecasting is made for various antenna "masks" taking into consideration possible shady sectors.

Height of users may be up to 7000 km.

Possible mutual conversion of different coordinate systems.

The following characteristics are predicted :

Visibility zone of each satellite in a constellation at a given point;  
Satellite position on the celestial sphere, the angle of elevation, azimuth.

The coefficients of the geometry: HDOP, VDOP, PDOP, TDOP, GDOP

Availability over a time period on the basis of two criteria: guaranteed number of visible satellites and guaranteed geometry coefficient .

Integral characteristics of positioning global accuracy.

Integral characteristics of satellite global coverage.

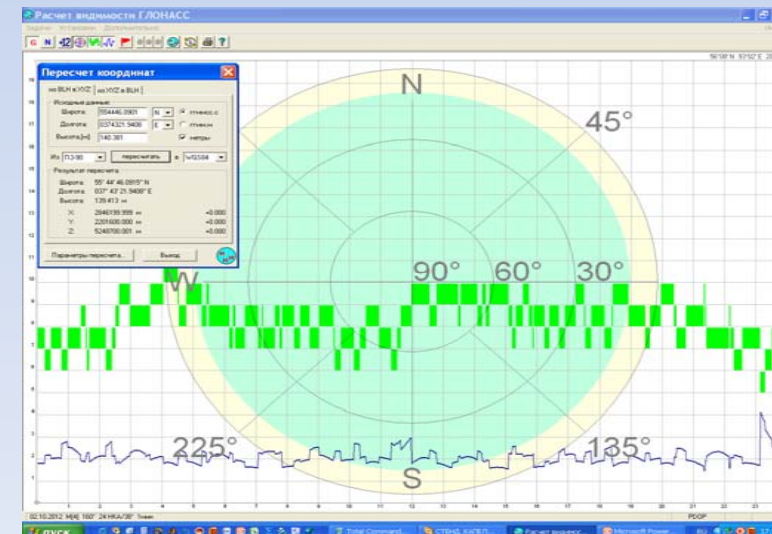
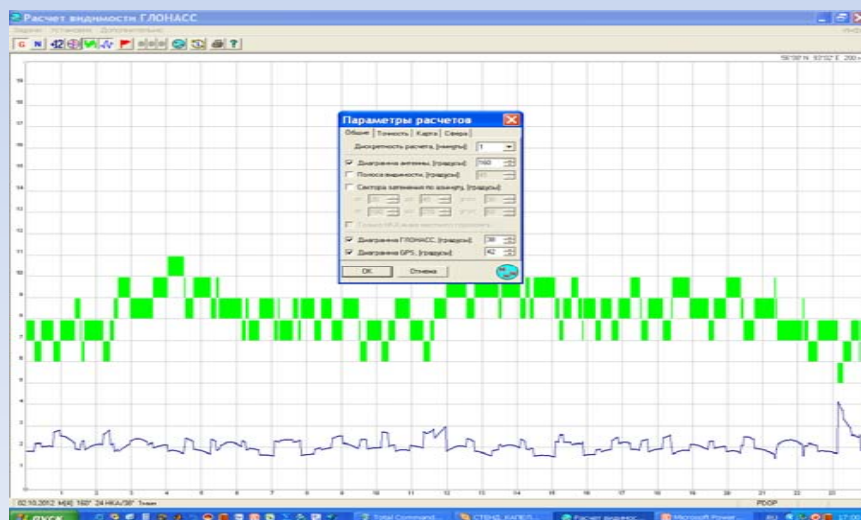
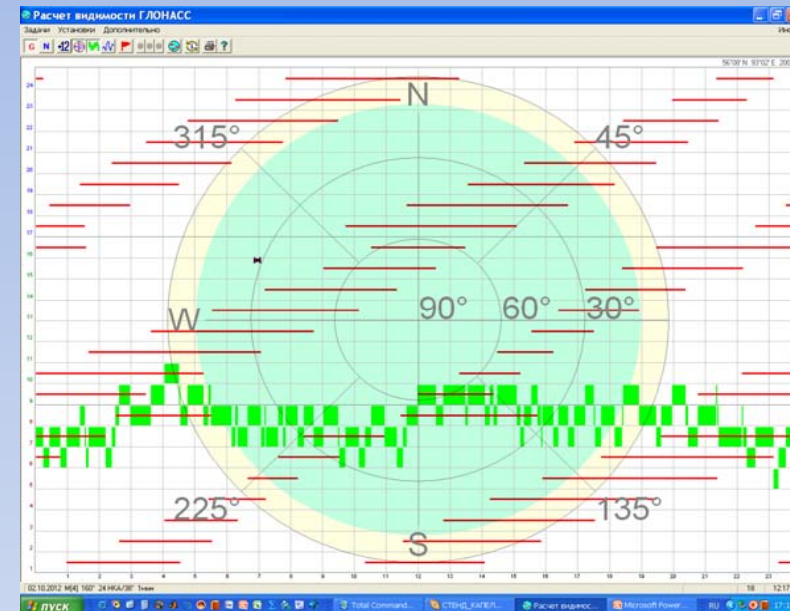
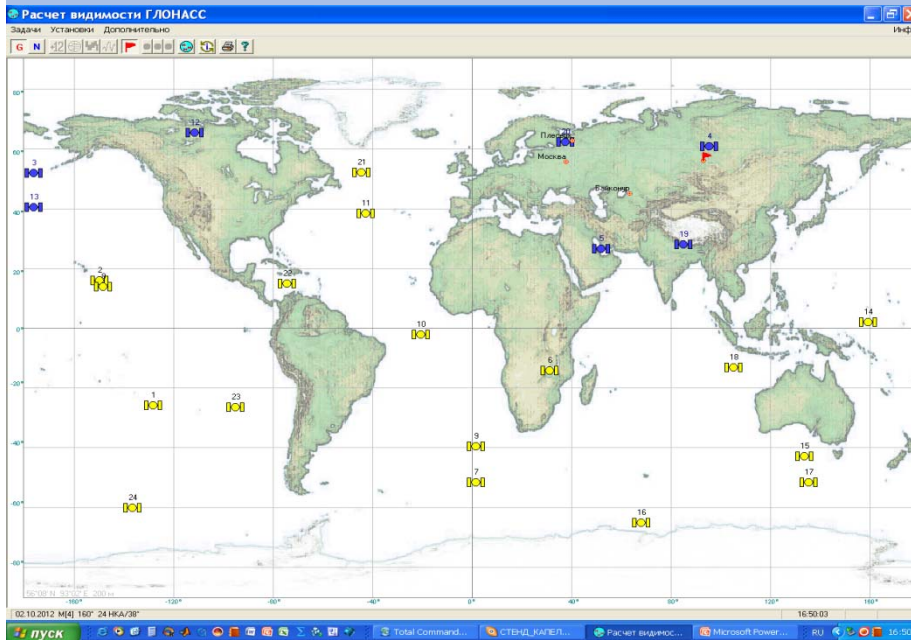
Recording all major parameters.



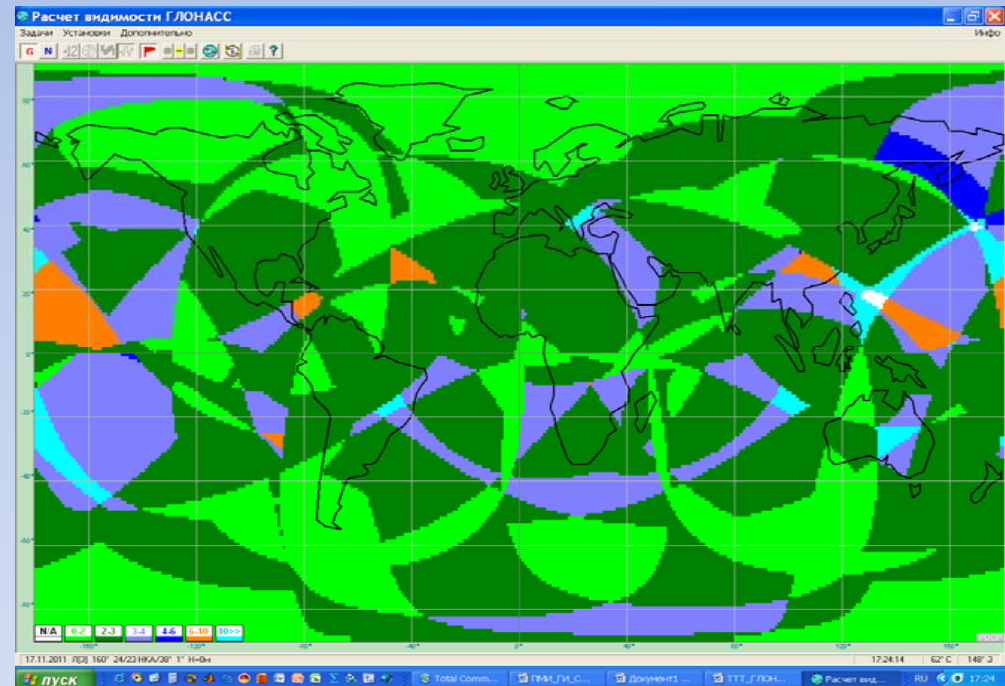
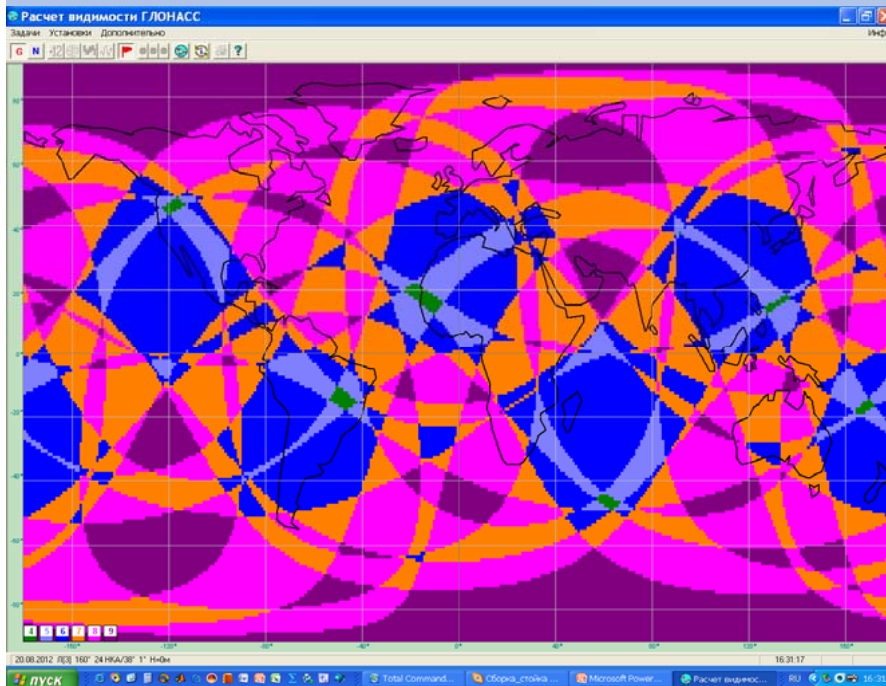
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# Constellation characteristics forecasting. Selection of a point. Geometry factors, availability, position in the celestial sphere.



Constellation characteristics forecasting. Number of visible satellites.  
Accuracy characteristics.





## Real time software.

There are the following operation modes in real time: "Movement", "Stop", "Control of the field."

In all modes, equipment can work with the following GLONASS and GPS signals: GLONASS (C/A, L1, L2) + GPS (C / A L1, L2C); GLONASS (C/A L1, L2); GPS (C / A L1, L2C).

In all modes the following parameters are displayed:

- receiver channels monitoring ( L1/L2 channels energy budget, search / tracking)
- position (current time, coordinates in a given system, satellite's number in the solution, estimation of coordinates and velocities accuracy (planned and altitude), altitude, course;
- satellite location in the celestial sphere (azimuth and elevation);
- continuous measurement on L1 and L2;
- messages on received information.

"Stop" and "Control field" modes display additional information

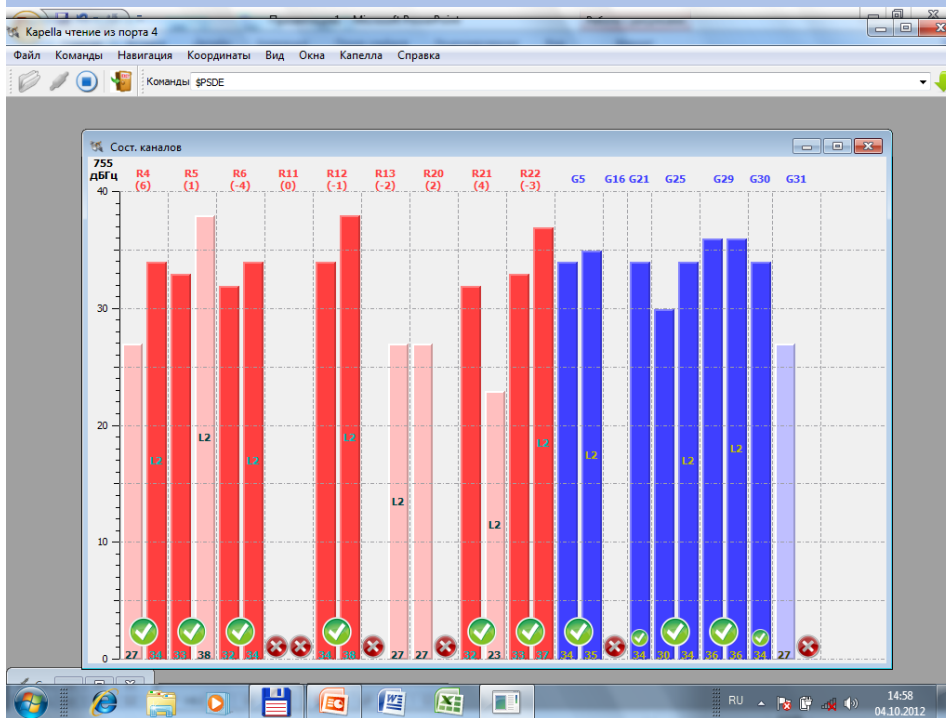
- accuracy "Target" for plane coordinates;
- differential operation modes (correction data / receiving and processing correction data according to the RTCM 104 standard).

"Control field" mode displays additional information:

- Screening GLONASS and GPS satellites using RAIM algorithms ;
- RAIM thresholds can be set by the operator either using SBAS data or without it.

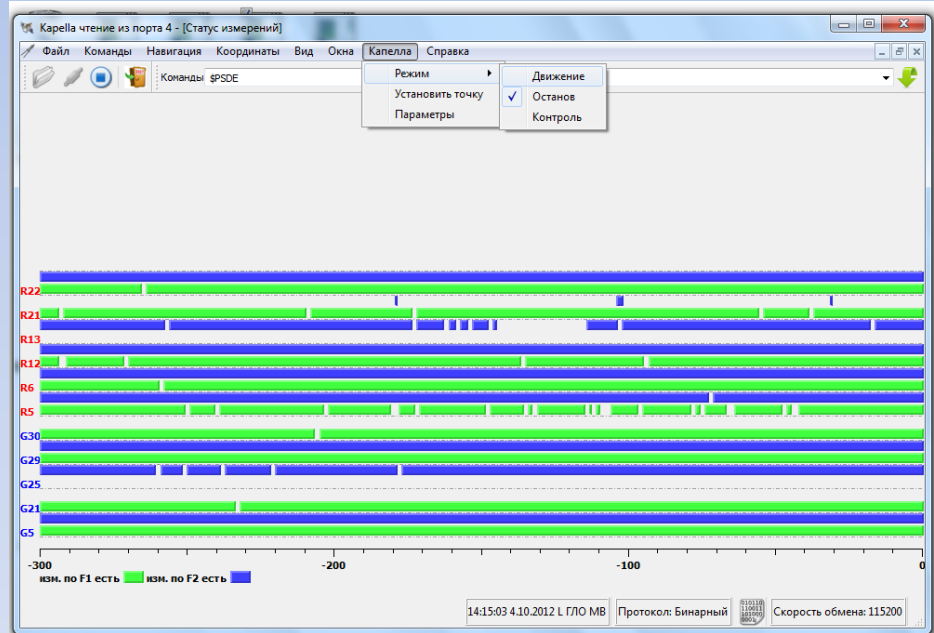
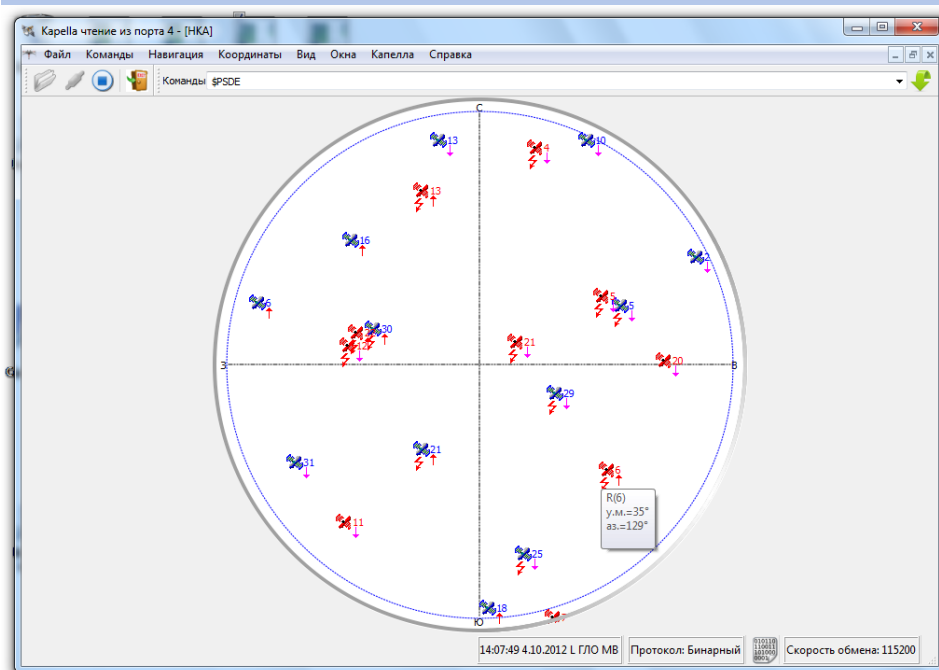
All digital information is recorded in decimal and binary form. A communication session can be stored and replayed later. Archive time - 30 days.

## Status and power budget of receiving channels. Position.

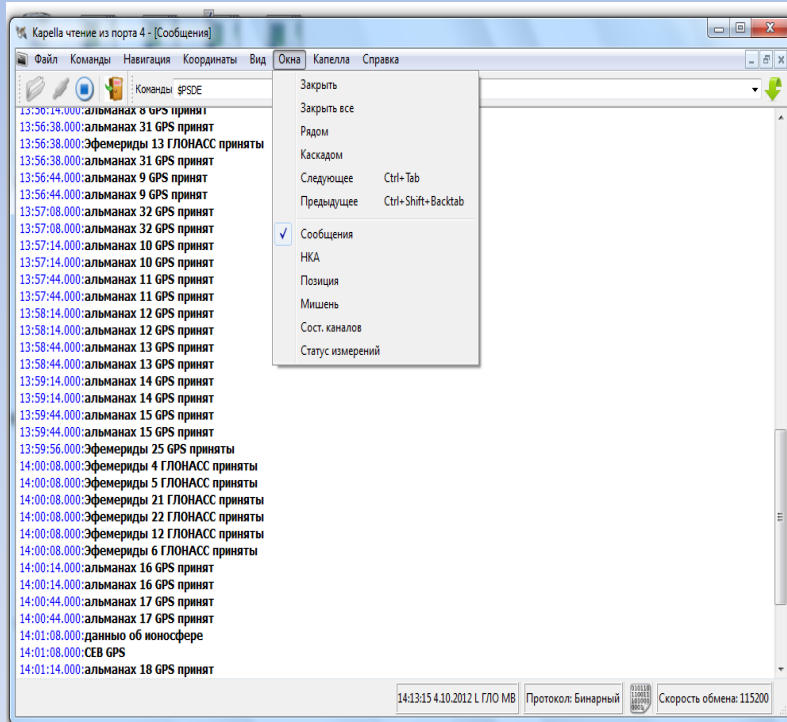




## Satellites position in the celestial sphere. Continuous measurement on L1/L2.



## Message, the target

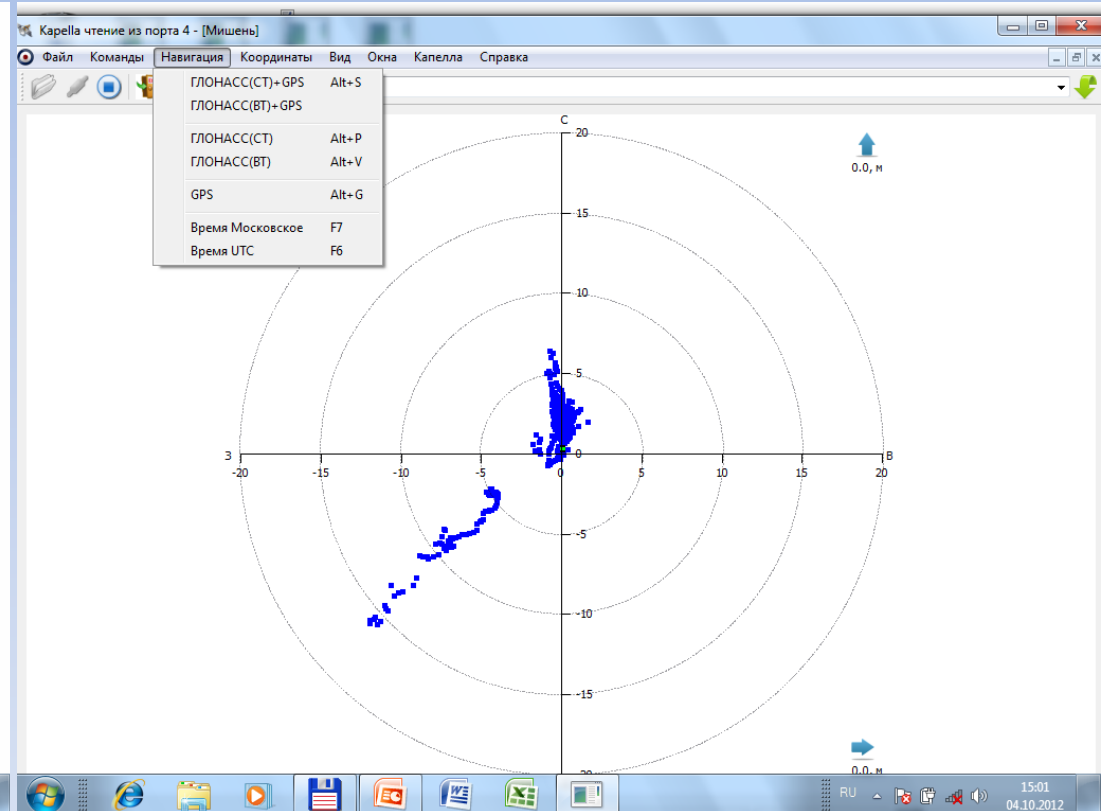


Карелла чтение из порта 4 - [Сообщения]

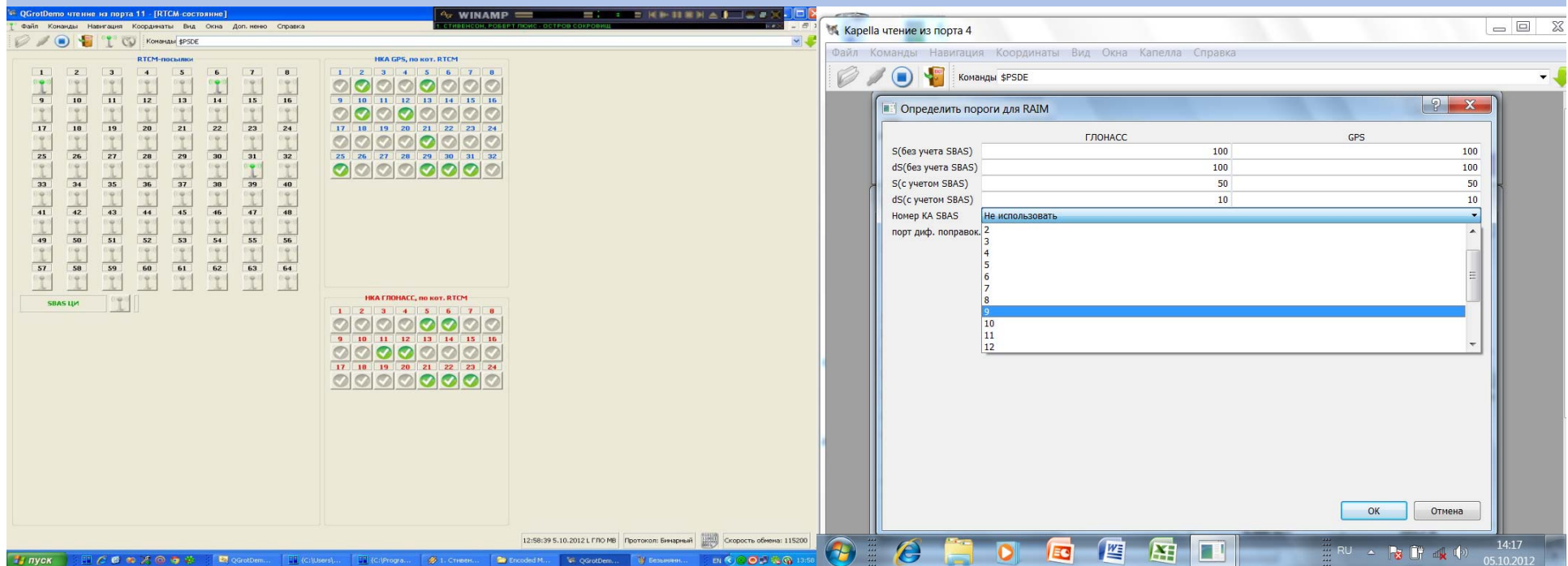
Команды: Кнопка: SPDE

- 13:56:14.000:альманах 8 GPS принят
- 13:56:38.000:альманах 31 GPS принят
- 13:56:38.000:Эфемериды 13 ГЛОНАСС приняты
- 13:56:38.000:альманах 31 GPS принят
- 13:56:44.000:альманах 9 GPS принят
- 13:56:44.000:альманах 9 GPS принят
- 13:57:08.000:альманах 32 GPS принят
- 13:57:08.000:альманах 32 GPS принят
- 13:57:14.000:альманах 10 GPS принят
- 13:57:14.000:альманах 10 GPS принят
- 13:57:44.000:альманах 11 GPS принят
- 13:57:44.000:альманах 11 GPS принят
- 13:58:14.000:альманах 12 GPS принят
- 13:58:14.000:альманах 12 GPS принят
- 13:58:44.000:альманах 13 GPS принят
- 13:58:44.000:альманах 13 GPS принят
- 13:59:14.000:альманах 14 GPS принят
- 13:59:14.000:альманах 14 GPS принят
- 13:59:44.000:альманах 15 GPS принят
- 13:59:44.000:альманах 15 GPS принят
- 13:59:56.000:Эфемериды 25 GPS приняты
- 14:00:08.000:Эфемериды 4 ГЛОНАСС приняты
- 14:00:08.000:Эфемериды 5 ГЛОНАСС приняты
- 14:00:08.000:Эфемериды 21 ГЛОНАСС приняты
- 14:00:08.000:Эфемериды 22 ГЛОНАСС приняты
- 14:00:08.000:Эфемериды 12 ГЛОНАСС приняты
- 14:00:08.000:Эфемериды 6 ГЛОНАСС приняты
- 14:00:14.000:альманах 16 GPS принят
- 14:00:14.000:альманах 16 GPS принят
- 14:00:44.000:альманах 17 GPS принят
- 14:00:44.000:альманах 17 GPS принят
- 14:01:08.000:данные об ионосфере
- 14:01:08.000:CEB GPS
- 14:01:14.000:альманах 18 GPS принят

14:13:15 4.10.2012 L ГЛО МВ Протокол: Бинарный Скорость обмена: 115200



## Differential mode. RAIM thresholds.



The screenshot shows a software interface with two main windows. The left window, titled 'QStarDemo чтение из порта 11 [RTCM состояние]', displays a grid of satellite status indicators for RTCM, GPS, and GLONASS. The right window, titled 'Капелла чтение из порта 4', is open to a dialog box 'Определить пороги для RAIM'.

The dialog box 'Определить пороги для RAIM' has the following configuration options:

	ГЛОНАСС	GPS
S(без учета SBAS)	100	100
dS(без учета SBAS)	100	100
S(с учетом SBAS)	50	50
dS(с учетом SBAS)	10	10
Номер КА SBAS	Не использовать	
порт диф. поправок	2	

The dialog box also includes a list of satellite numbers (2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12) and 'OK' and 'Отмена' buttons.



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Example of recording digital information. Measurements.  
Recorded binary frame.

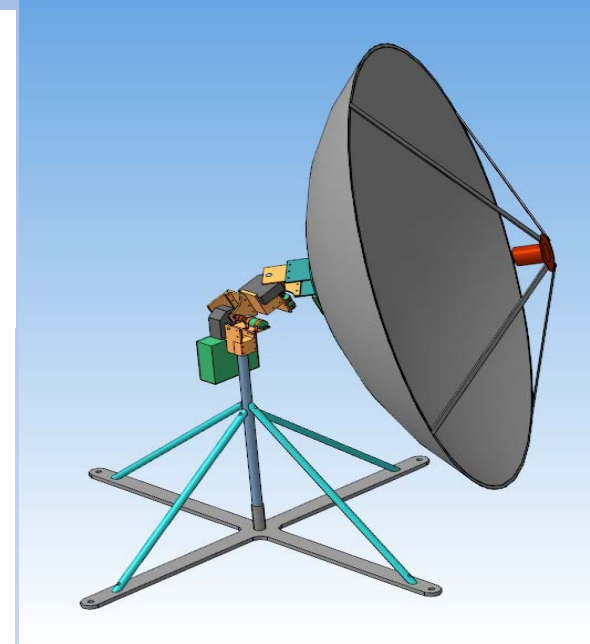
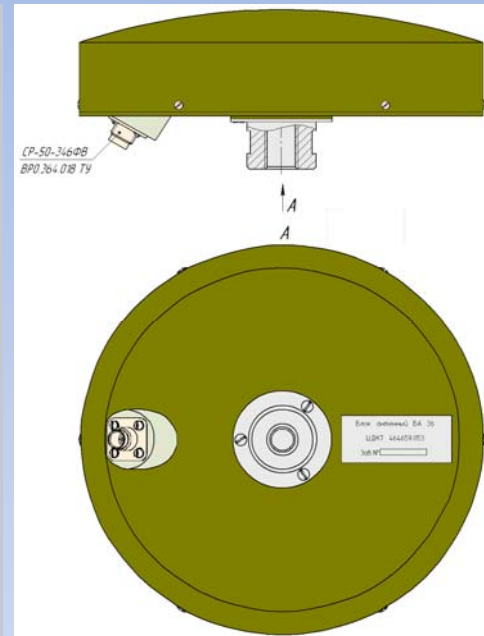
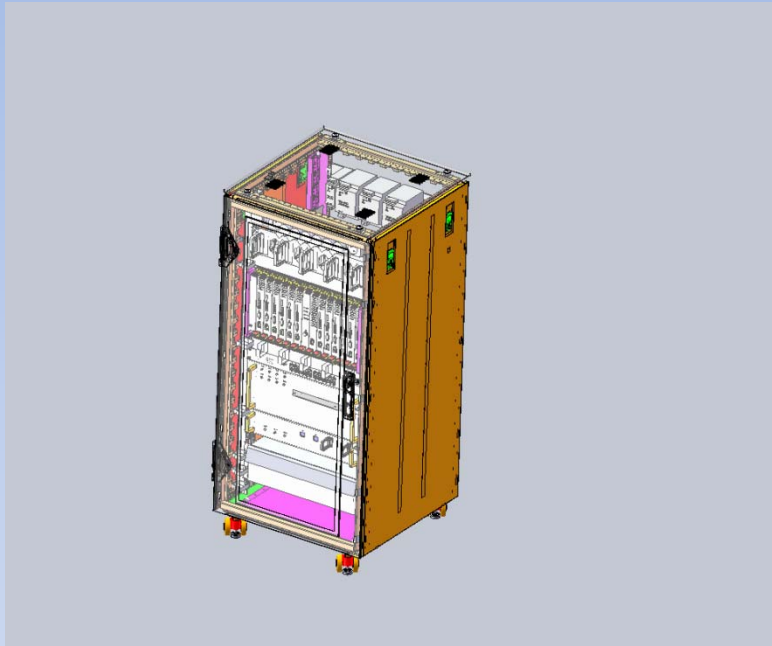
09:07:38.000  
эфемериды приняты для НКА ГЛОНАСС 15  
t\_b = 3.33000000e+04  
SV\_Health = 0x 0  
IODC = 0x 25  
X = 1.944899170e+04  
Y = 1.642590918e+04  
Z = 2.288999512e+03  
Vx = 3.958740234e-01  
Vy = 2.909755707e-02  
Vz = -3.581364632e+00  
Ax = 1.862645149e-09  
Ay = -9.313225746e-10  
Az = 0.00000000e+00  
gamma = 1.818989404e-12  
tau = -7.383152843e-05  
dtau = 3.725290298e-09  
en = 0

09:07:33.000  
эфемериды приняты для НКА GPS 10  
Code\_on\_L2 = 0x0000000000000001  
L2\_P\_flag = 0x0000000000000000  
SV\_accuracy = 0x0000000000000000  
SV\_Health = 0x0000000000000000  
IODC = 0x000000000000000016  
fit\_interval\_flag = 0x0000000000000000  
Tgd = -2.793968e-09  
Toc = 4.608000e+05  
A0 = -1.940737e-05  
A1 = -1.136868e-12  
A2 = 0.000000e+00  
e = 1.07813964132e-02  
dn = 5.008066e-09  
M0 = 8.20028294339e-01  
SqrtA = 5.15364611053e+03  
Toe = 4.608000e+05  
Omega0 = -2.93632310873e+00  
I0 = 9.476870835676e-01  
W = 7.16680260838e-01  
OmegaDot = -8.509640e-09  
IDOT = -2.189377e-10  
Cuc = 1.139939e-06  
Cus = 6.193295e-06  
Cic = -8.381903e-08  
Cis = 9.685755e-08  
Cre = 2.538750e+02  
Crs = 2.093750e+01

The screenshot shows a Microsoft Excel spreadsheet with two main data sections. The top section is a table of satellite parameters for GPS satellites, with columns for satellite ID (ID), PRN, Pseudo-Random Noise (PRN), Ephemeris ID (Ephemeris ID), and various orbital and clock parameters. The bottom section is a binary frame, represented as a grid of 0s and 1s, which is the recorded digital information for the measurements.



## Fixed equipment. Composition.



12 identical reconfigurable for different GNSS receivers in the eurorack :  
GLONASS (L1, L2, L3/L5, C/A, P, FDMA, CDMA);  
GPS (L1 C / A, L1C, L2C, L5);  
GALILEO (L1 E1, E5a, E5b);  
COMPASS (L1 BOC 1,1);  
QZSS (L1 BOC 1,1; L5 BPSK 10);  
SBAS (L1, L5).

Antenna (omnidirectional, directional), a set of cables, laptop, Power Supplies.

## Software of the fixed equipment .

**Software of fixed equipment includes:**

**Software to predict orbital GNSS performances and their augmentations. Fixed equipment software structure is similar to the software for mobile GLONASS/GPS equipment.  
Also for other GNSS**

**Real-time software is similar to the software for mobile GLONASS/GPS equipment.  
Also for other GNSS**

**Development of software for different GNSS signals depends on the interface control documents for these signals .**

**Status of development.**

**Eurorack is designed and manufactured.**

**Receivers are designed and manufactured.**

**Software is developed and aligned for GLONASS (L1, L2, C/A) and GPS (L1 C / A, L2C).**

## **SQM monitoring of the GNSS navigation signals.**

**Monitoring the quality of GNSS navigation signals performs the following functions:**

**estimates spectral characteristics of the navigation signals;**

**estimates spectral and energy characteristics of the interference;**

**displays and estimates the time characteristics of the navigation signals;**

**estimates the energy characteristics of navigation signals.**

## **Composition of the equipment to control quality of GNSS navigation signals.**

**Beam antenna diameter,  $d = 3.7$  m, gain,  $K = 33$  dB. Antenna control system, monitoring antenna orientation system.**

**Dedicated receiver.**

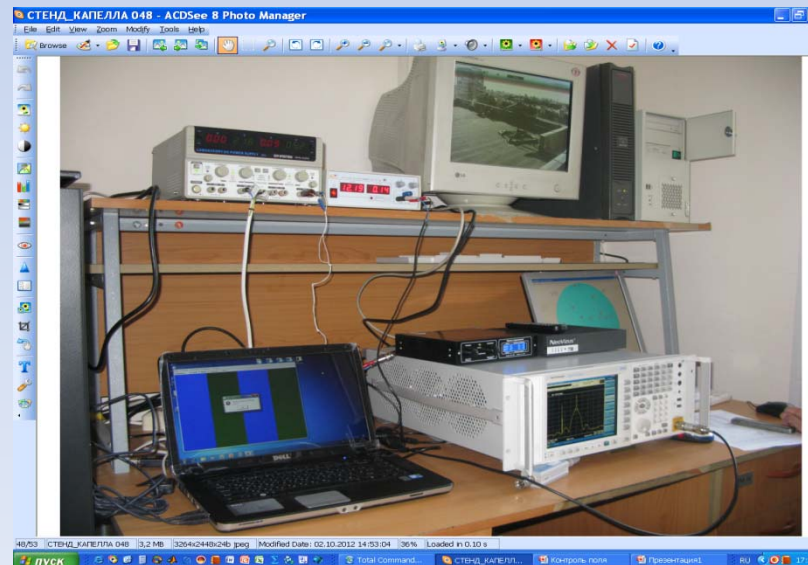
**A high-quality spectrum analyzer.**

**Dedicated software .**

**Laptop.**



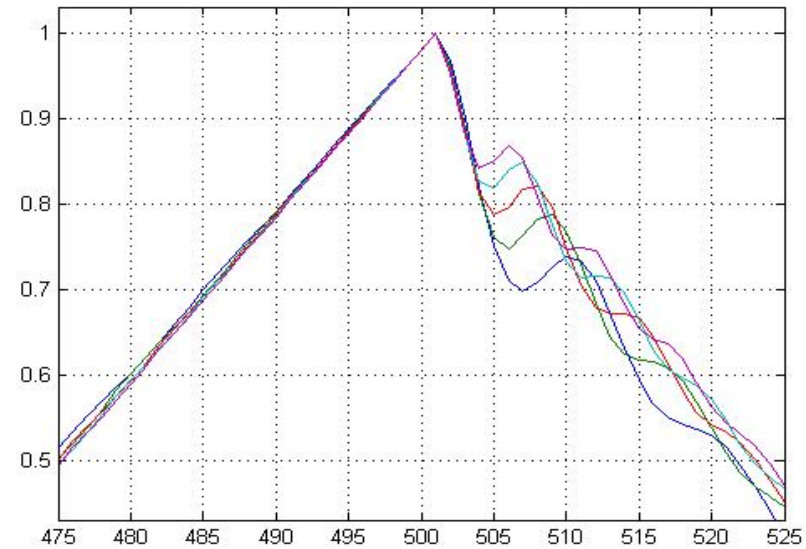
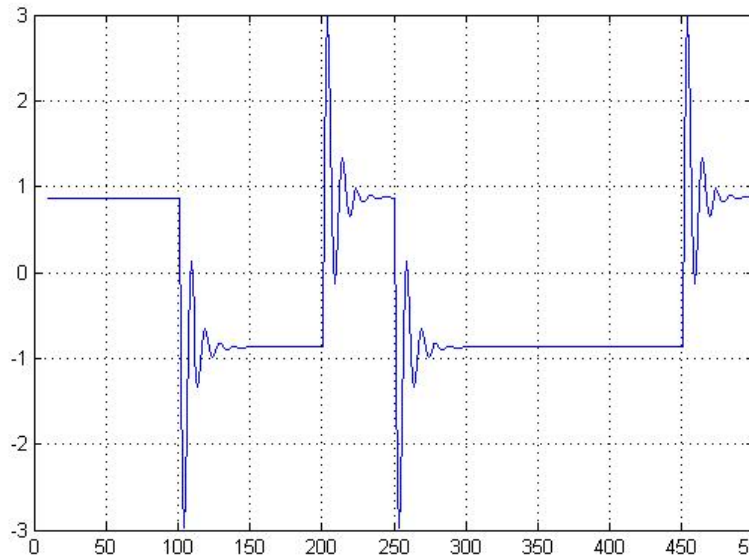
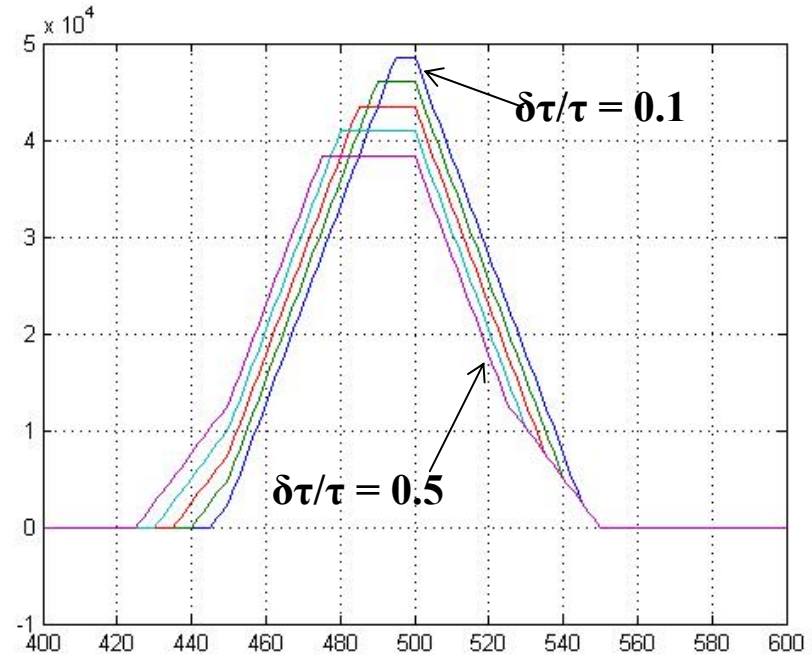
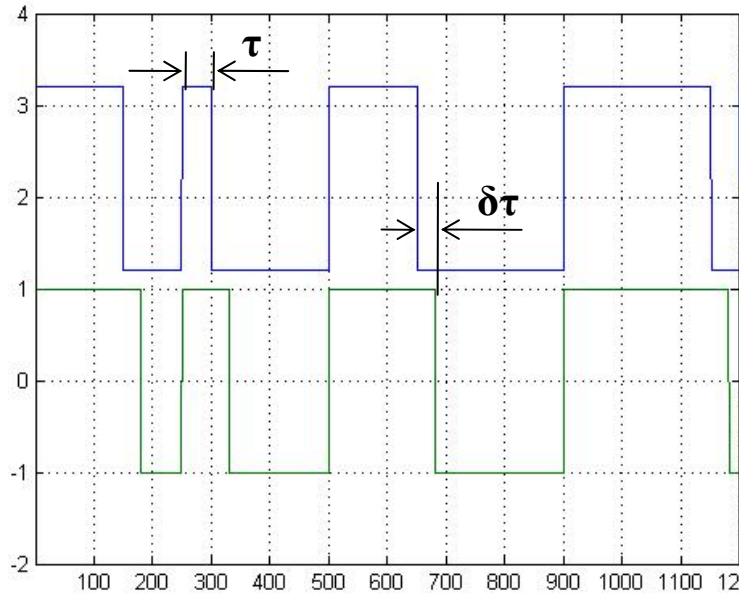
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SQM. Fixed equipment



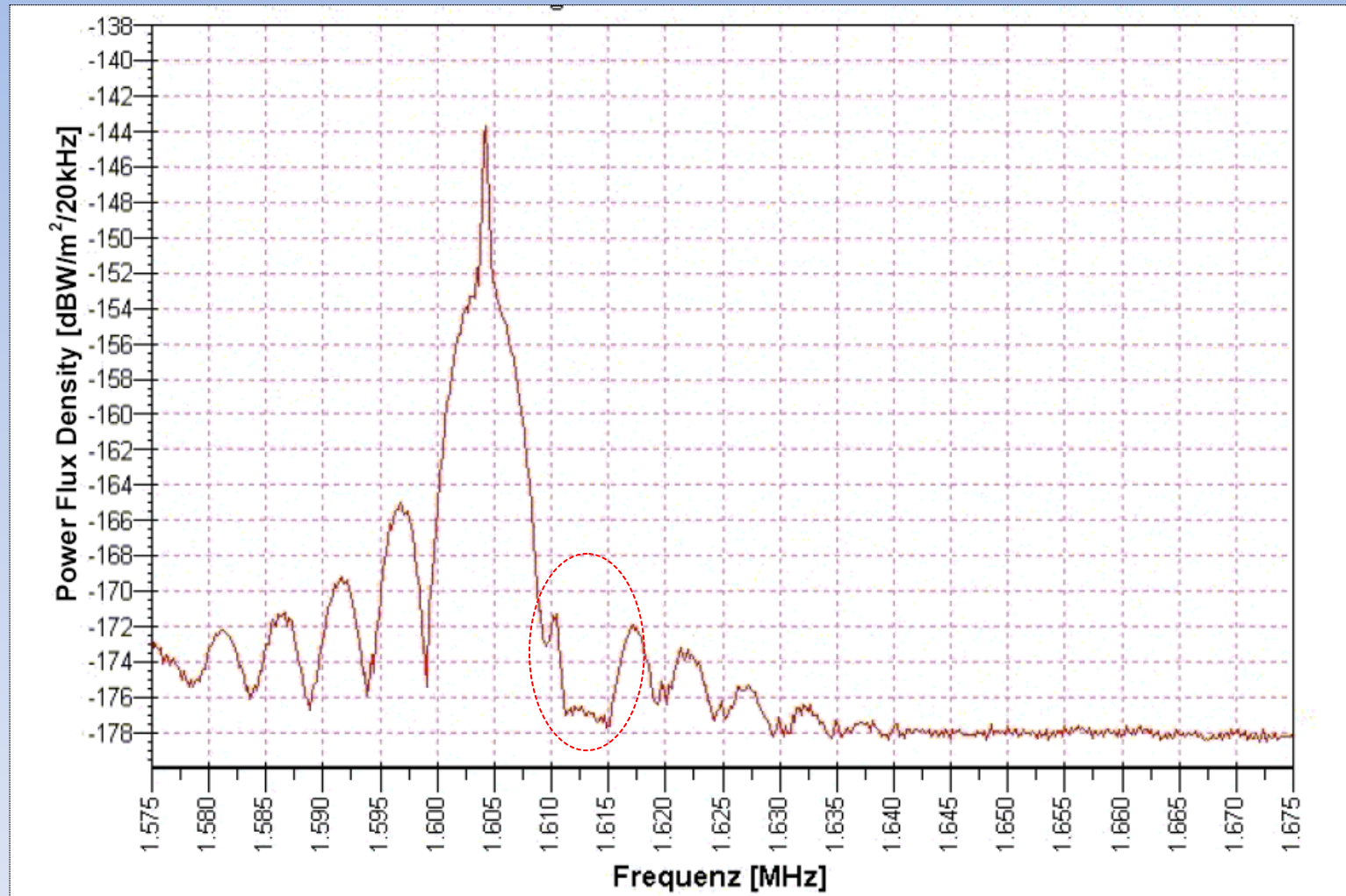




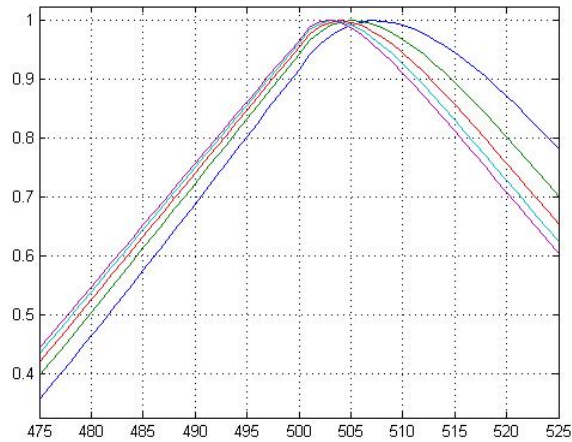
P



## Spectrum distortion of GLONASS navigation signals on the L1 band



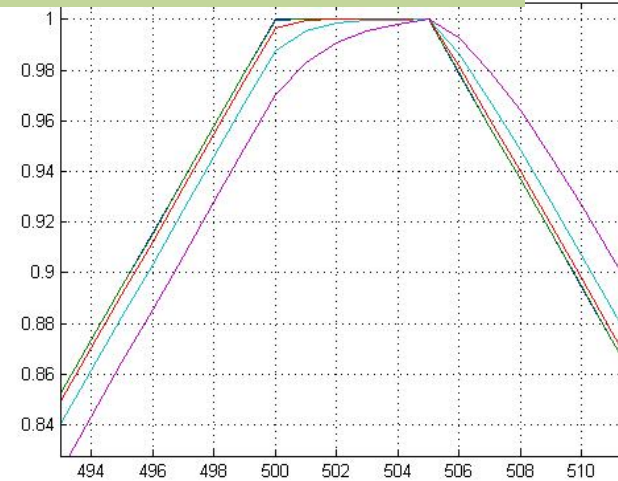
Simulation served to define basic parameters of a dedicated receiver.



ACF in the finite duration of the transition process.

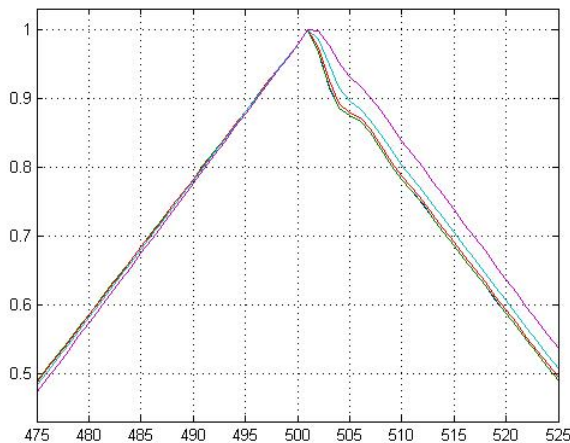
ADC.

$\Delta f$  in L1 band.



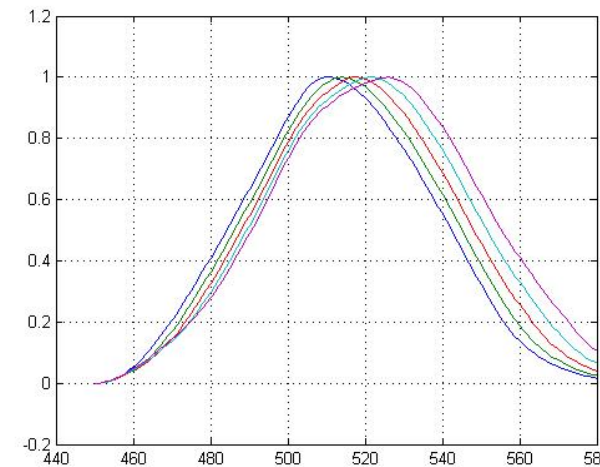
ACF at distortions of the 1st kind and band-limited input signal.

$\Delta f$  in L5-L2 band.



ACF view the perversions of the 1st kind and band-limited input signal.

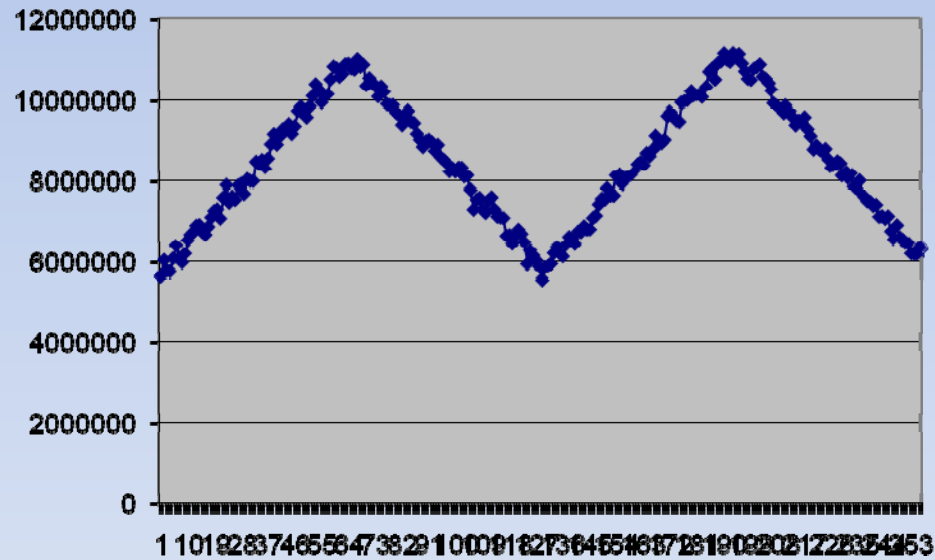
Number of points of the ACF.



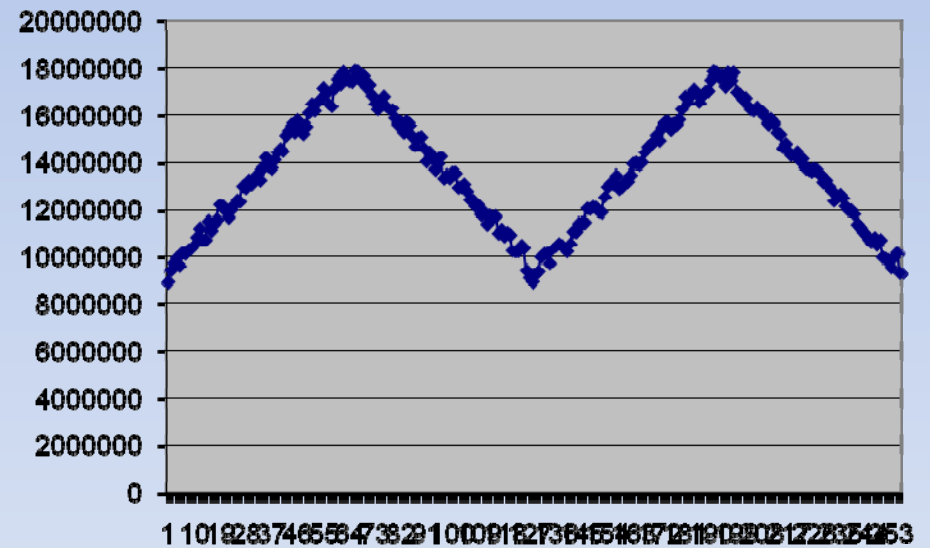
View of ACF in the band 2 and a different change of duty cycle.

## Experimental studies of navigation signals.

Glonass-M; № 13, (f. = -2, ACF - 128, date: 30 August 2012, L1 band. Point coordinates: 55 ° 34 'N, 37 ° 38' I (Moscow).



GPS; № 4, (ACF - 128, date: 30 August 2012, L1 band. Point coordinates: 55 ° 34 'N, 37 ° 38' I (Moscow).



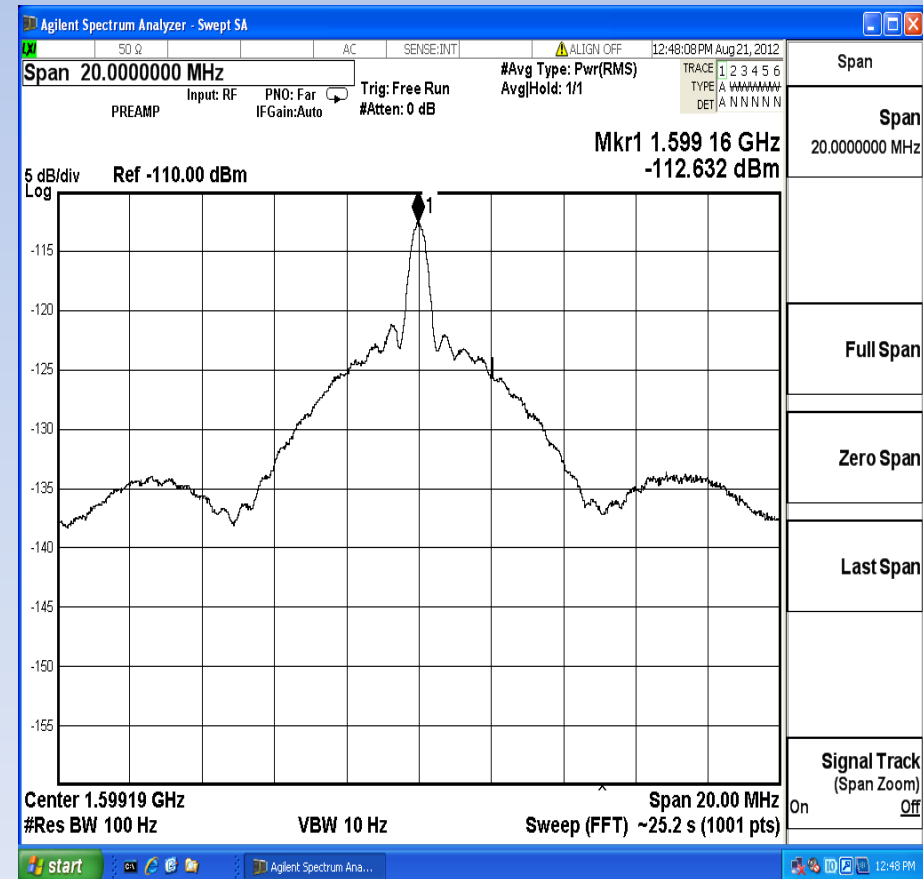
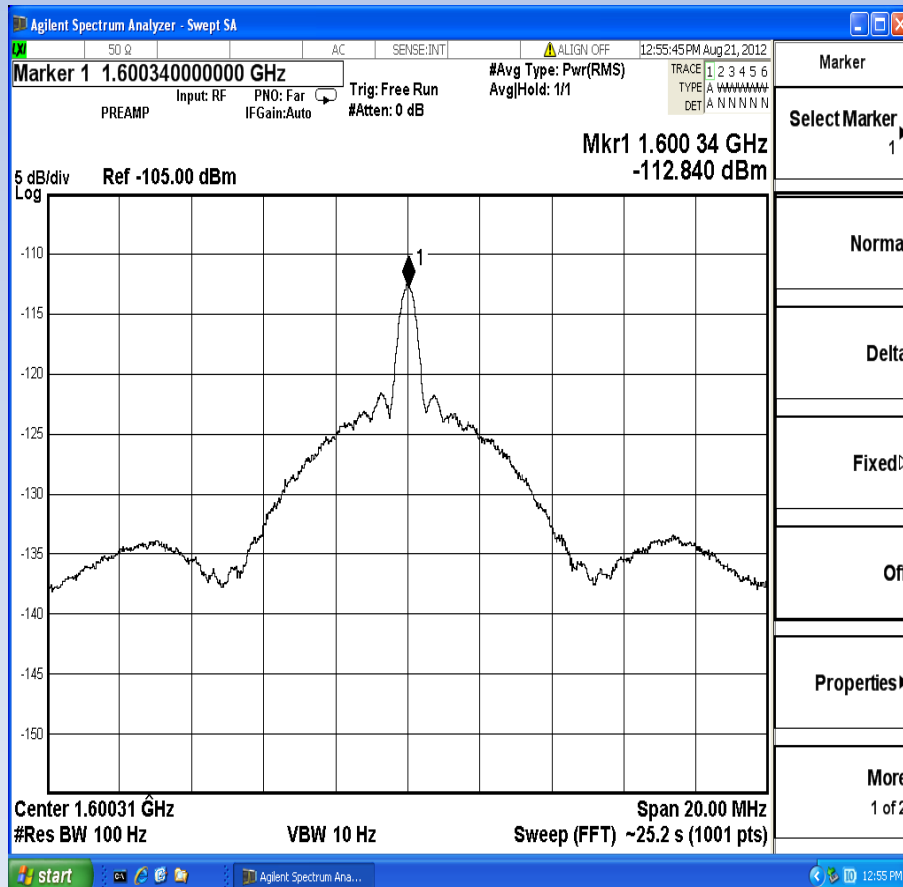


## Experimental studies of navigation signals spectrum.

### Band L1

#### Glonass-M № 22

#### Glonass -K;

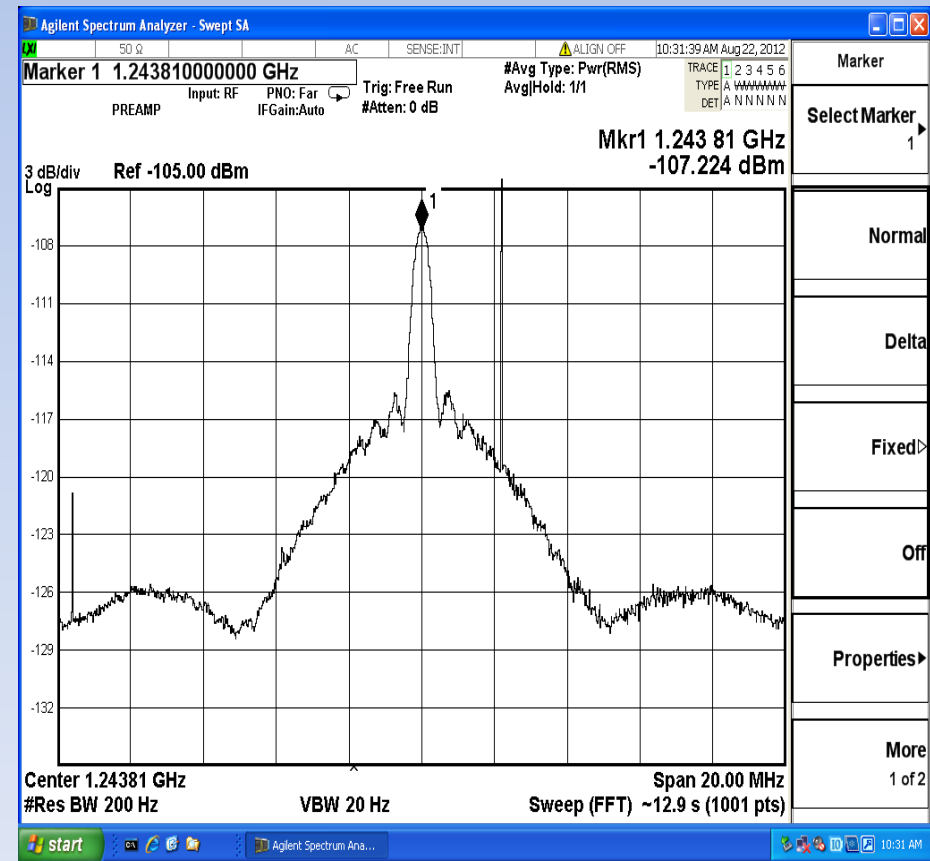
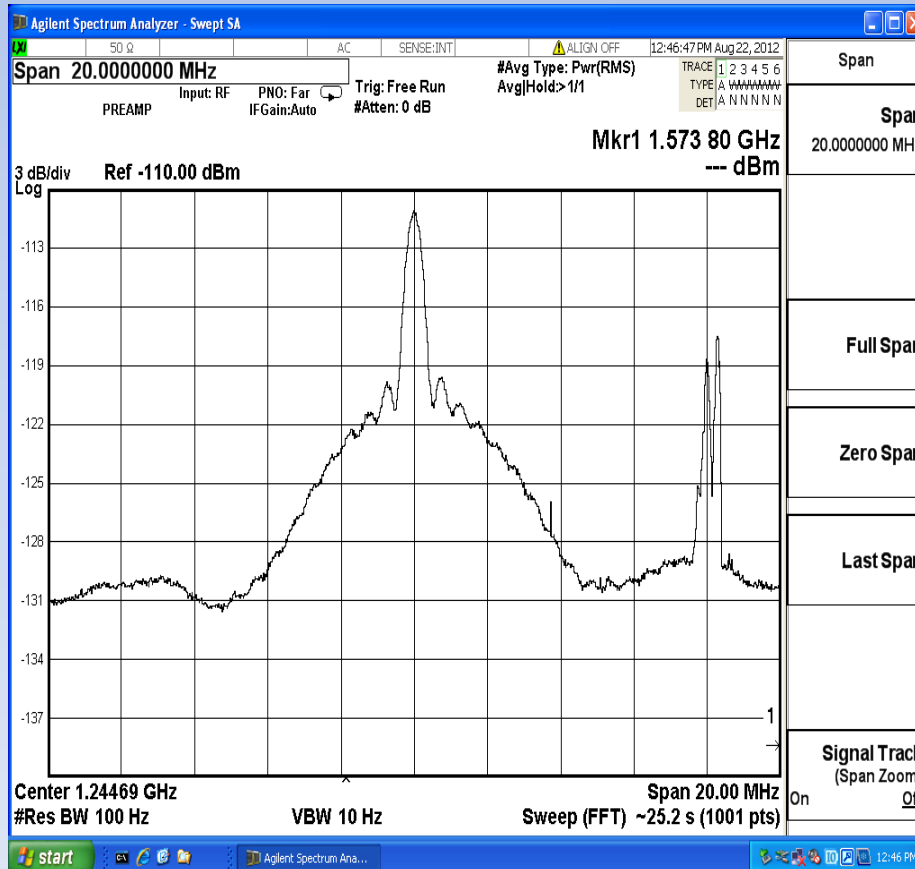


## Experimental studies of navigation signals spectrum.

### Band L2

#### Glonass-M № 22

#### Glonass -K

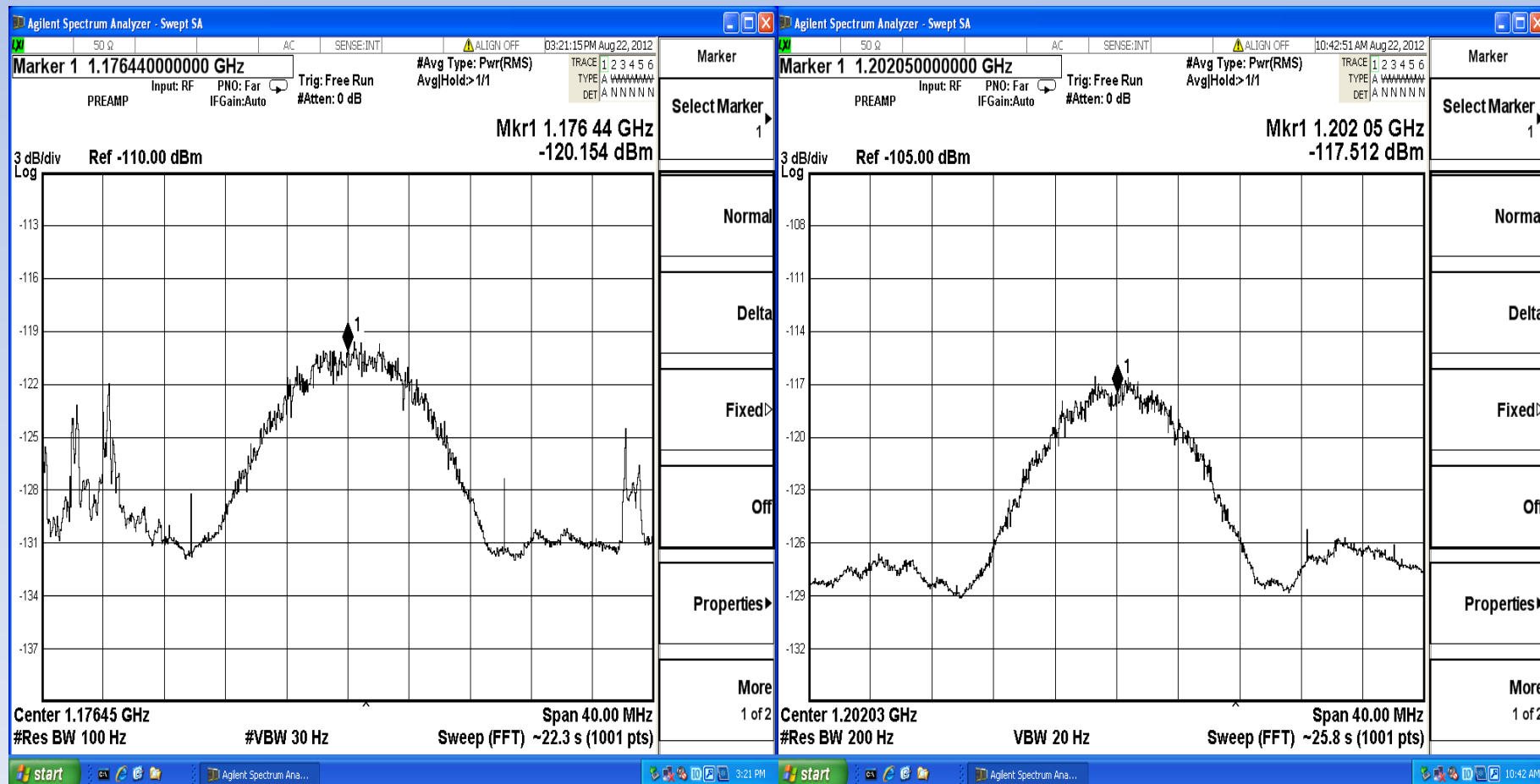


## Experimental studies of navigation signals spectrum.

### Band L3/L5

#### GPS № 25

#### Glonass -K





## Conclusions (1).

- 1. Compact (mobile) 64 - channel equipment to control GLONASS/ GPS navigation signals on L1/L2 bands are designed, manufactured and operate.**
- 2. Such equipment is especially useful in areas of testing mobile technique using the GLONASS/GPS satellite navigation device. It allows you optimally plan the tests and serve as a "referee" in conflict situations .**
- 3. Fixed multi-system navigation signals monitoring equipment can receive and process open signals of all (now known) GNSS and their augmentations. This allows you to compare and evaluate different GNSS options. The equipment is designed so that if any GNSS signal structure is modified, then it will be sufficient to reprogram the settings without changing the hardware. The equipment is manufactured. Currently, this equipment and software are being tested.**





## Conclusions (2).

**4. Developed quality control system for GNSS navigation signals on the band of L1, L2 and L3/L5 allows:**

- estimate modulating wave distortions : changing pulse bandwidth, presence of the transient process in the pulse bandwidth formation;
- estimate the level of the navigation signal near the ground;
- estimate the spectral characteristics of the signals;
- estimate interference conditions at the receiving point .

**5. The state of SQM development: the equipment is manufactured; currently this equipment and software are being tested; calibration equipment for directional antenna is mounted.**



РОСКОСМОС



**Thank you for your attention**