Next BIPM Publication of (UTC - bUTC_GNSS)

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Circular T « Section 4 »

Section 4 publishes the difference between UTC and the prediction of UTC broadcast by GNSS

4 - Relations of UTC and TAI with predictions of UTC(k) disseminated by GNSS.

```
[UTC-UTC(USNO)\_GPS] = C_0', [TAI-UTC(USNO)\_GPS] = 37 s + C_0'[UTC-UTC(SU)\_GLONASS] = C_1', [TAI-UTC(SU)\_GLONASS] = 37 s + C_1'
```

For this edition of Circular T, $\sigma_0 = 0.9$ ns, $\sigma_1 = 7.1$ ns

| 2022 | 0h UTC | MJD | C ₀ '/ns | N ₀ | C1'/ns | N ₁ ' |
|------|------------|-------|---------------------|----------------|--------|------------------|
| | APR 30 | 59699 | -0.4 | 89 | 40.4 | 87 |
| | MAY 1 | 59700 | -0.5 | 90 | 41.1 | 85 |
| | MAY 2 | 59701 | 0.3 | 89 | 41.9 | 83 |
| | MAY 3 | 59702 | -1.3 | 89 | 41.9 | 85 |
| | MAY 4 | 59703 | -3.1 | 89 | 42.4 | 88 |
| | MAY 5 | 59704 | -1.3 | 89 | 43.5 | 87 |
| | MAY 6 | 59705 | -2.0 | 88 | 44.9 | 87 |
| | X # A X7 7 | 50702 | 27 | 07 | 45 0 | 00 |

Date of appearance in Section 4 : GPS in 1988 (circular T 12) GLONASS in 1990

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recommends that

Section 5* of BIPM Circular T be retitled "Relations of UTC and TAI with predictions of UTC disseminated by GNSS", and adds similar information on new GNSS as they become operational.

* Now Section 4

https://www.bipm.org/en/committees/cc/cctf/20-2015/resolution-2

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New Naming Convention

Introducing new abbreviation: **bUTC**_{GNSS} (GNSS = BDS, GAL, GLO, GPS)= "broadcasted prediction of UTC via [GNSS]" Ascii : butc GNSS Which will be computed as : Comes from Circular T section 1 $UTC - bUTC_{GNSS} = (UTC - UTC(k)) \checkmark$ + (UTC(k) - GNSStime) Comes from calibrated receivers measurements, sent by selected $+ (GNSStime - bUTC_{GNSS})$ G1 labs = ΔUTC , Comes from GNSS systems through navigation messages Bureau

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1 lab per GNSS constellation, specific file



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Pool of calibrated G1 labs, regular rinex file, independent Δ UTC calculation



1^{st} step : Δ UTC

 $\Delta \text{ UTC} = (GNSStime - bUTC_{GNSS})$ difference between GNSS system time and a UTC prediction realized by the system operator

Found in Rinex3 nav headers and in Rinex4 nav data (as polynomials).

Different satellites can broadcast different polynomials, some outliers exist.



2nd step: UTC - broadcast prediction of UTC (bUTC_{GNSS})

(UTC(k) - GNSStime)determined by generating CGGTTS files, estimating the REFSYS for each epoch then filter (24h sliding average).



(UTC - UTC(k))Interpolated from Circular T section 1.

$$\begin{split} UTC - bUTC_{GNSS} &= \begin{pmatrix} UTC &- UTC(k) \end{pmatrix} \\ &+ (UTC(k) - GNSStime) \\ &+ (GNSStime &- bUTC_{GNSS}) \end{split}$$

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Comparison with Current Publication over 7 Months

An upcoming Metrologia paper will detail the method.

On these plots : the shaded area visualizes the estimated uncertainty of our measurement, which should not be mistaken for the uncertainty GNSS receiver users may achieve.



Expected Output (Provisional Version)



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Thank you for your attention



