



ESA's GENESIS Mission – At the foundation of Navigation

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ESA/ESOC and **ESTEC**

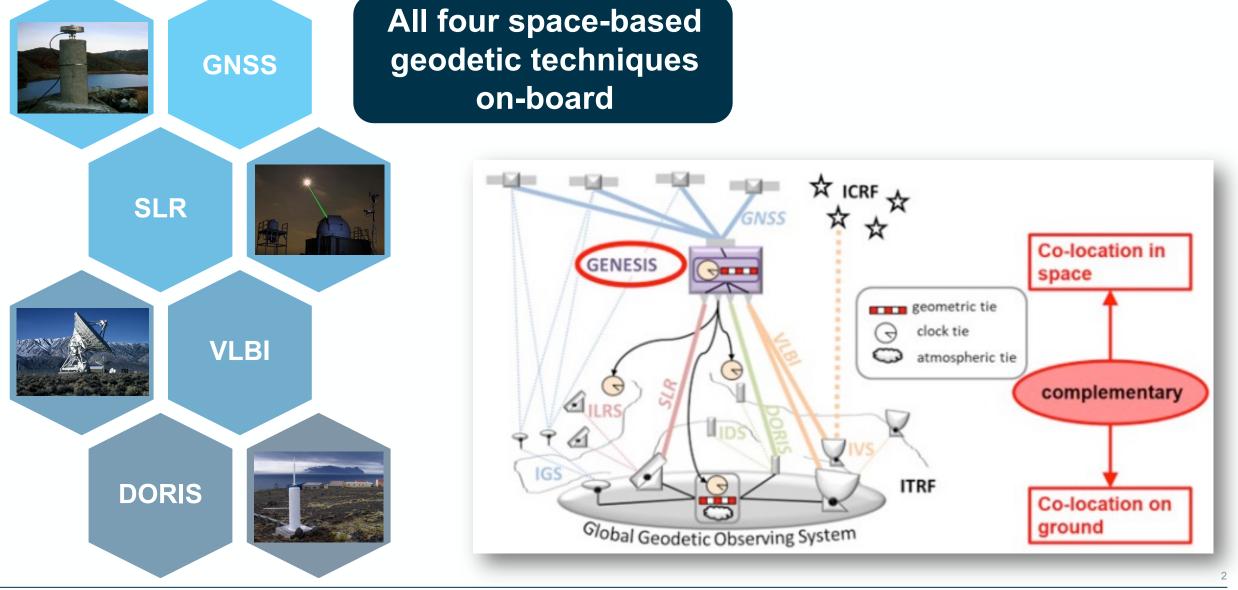
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ESA's GENESIS Mission – Overview





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The GENESIS Mission – Objectives



Improve ITRF accuracy and stability by providing in-orbit colocation and necessary combined processing of the four space-based geodetic techniques that contribute to its realization. The goal is to contribute to the achievement of the Geodetic Global Observing System (GGOS) objectives for the ITRF realisation, aiming for a parameter **accuracy of 1 mm and a stability of 0.1 mm/year**, in order to provide significant scientific benefits in Earth modelling, and to support a wide range of societal applications (as endorsed by the United Nation resolution A/RES/69/266).

Objective

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Improve the link between the ITRF and the ICRF, thanks to the increased consistency of the Earth Orientation Parameters (EOP). In particular, this mission shall allow for the first time a link between the orbit reference frame, ITRF and ICRF.

The GENESIS Mission – Background and Scope

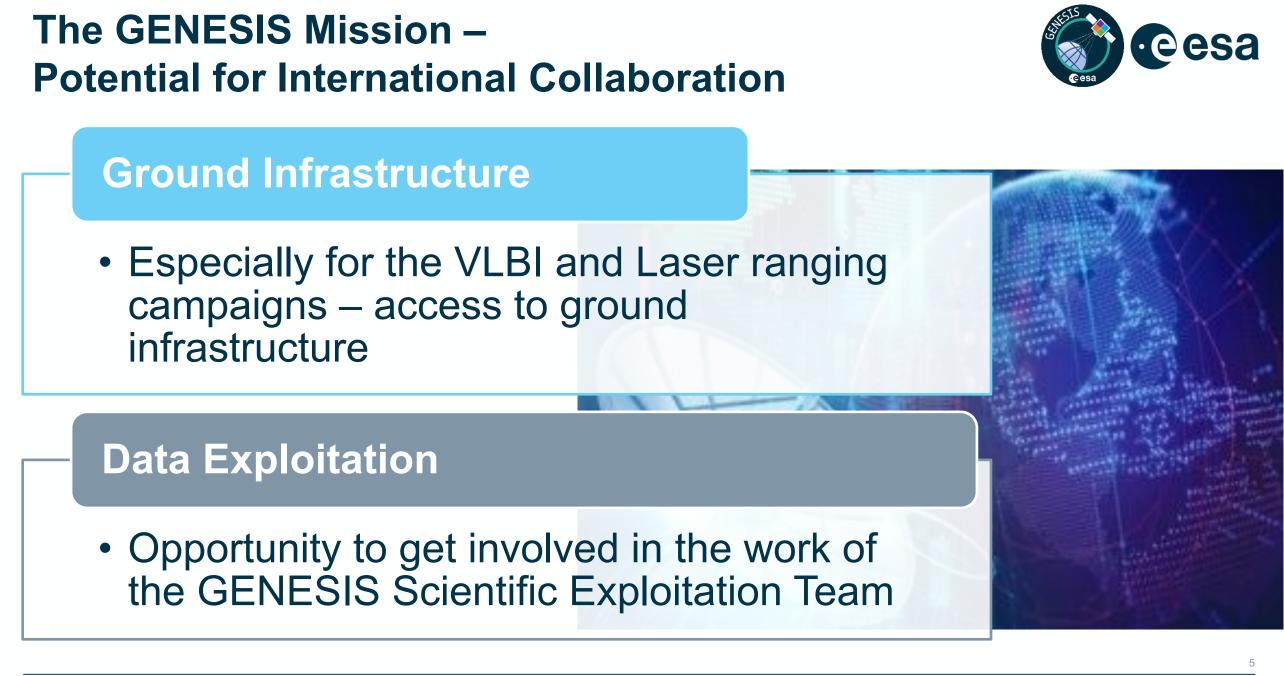


Background

- GENESIS mission is widely supported by the international scientific community
- GENESIS is managed by ESA and part of its FutureNAV Programme
- Launch of GENESIS is currently planned for second half of 2027

Mission scope

- Design, development and qualification of the satellite (incl payloads) and ground segment
- Launch and early operations including commissioning and calibration
- Operations (2 years, option for extension)
- Data exploitation



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The GENESIS Mission – POD Aspects – Requirements for GNSS Measurements



- A sufficient number of satellite measurements (15 to 25 satellites) have to:
- come from satellite antenna main lobe;
- have a CN0 above 25 dBHz;
- Multi-constellation and dual frequency measurement simultaneously available
- Optical and thermal material properties (absorption, reflection, etc.) of the satellite outer surfaces has to be known in order to make an accurate radiation pressure model of the satellite.
- GNSS observations (combined Galileo and GPS) must be of high quality and unbiased (after calibration is applied) to allow high success rate Integer ambiguity resolution

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The GENESIS Mission – POD Aspects



GENESIS POD and GNSS observation simulation within the Concurrent Design

Facility (CDF) Activities:

- Three different scenarios for POD calculation
 - GPS-only observations
 - GALILEO-only observations
 - GPS + GALILEO combined observations
- Two different processing approaches
 - Carrier-phase Ambiguities Integer resolved
 - Carrier-phase Ambiguities estimated (floating solution)

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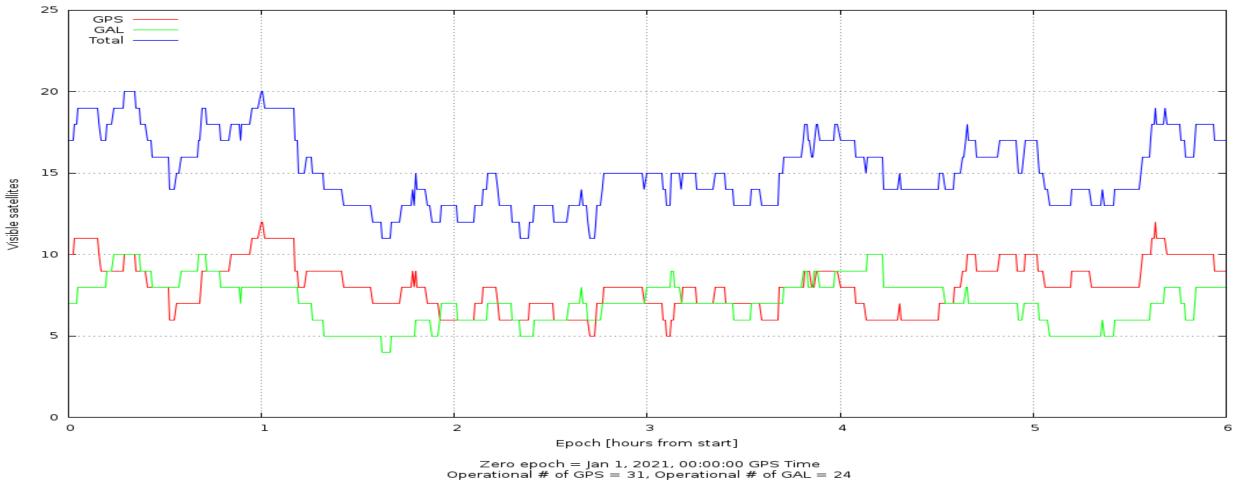
The GENESIS Mission – POD Aspects - Visibility



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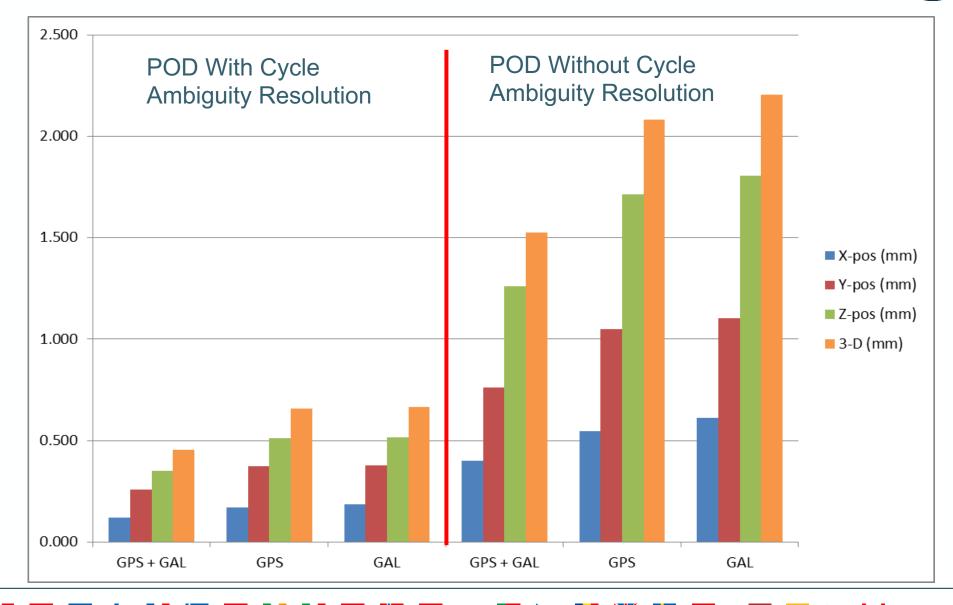
Patch Antenna – Zenith Pointing, SNR = 25dBHz

GNSS Simulation: Space User in 6000km circular orbit - Patch antenna - Zenith pointing



The GENESIS Mission – POD Aspects Satellite Position Formal Errors (m





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The GENESIS Mission - Conclusions



POD Analysis

- Successful Integer ambiguity resolution is key for achievable POD accuracy!
- Individual (not combined) POD solutions for GALILEO and GPS shows very similar accuracy performance
- Combined GPS and GALILEO observation processing shows best POD accuracy performance
- GNSS Interoperability is important for POD achievable accuracy
 - NOTE: Formal errors do depend on the location of the state vector. Selected initial inertial state vector was (x, y, z) = (12378, 0, 0) km. For the chosen state vector X and Z are highly correlated (radial and along-track)

GENESIS Mission Implementation

- Challenging and Exciting path ahead!
- The teams are working hard to realise the mission and ensure the best conditions for data exploitation
- A mission with high potential for international collaboration

Thank you for your attention



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