Design and Realization of DMR Based on GPS for Sea Surface Wind Measurement

Dr. Yang Dongkai School of Electronic and Information Engineering BeiHang University Jan-17-2011

Email: edkyang@buaa.edu.cn

Outline

- Introduction
- Geometry of GPS scattered signal
- Measurement Technique
- Delay Mapping Receiver Design
- Data Collection
- Results analysis
- Conclusion

Introduction

- Signals of Global Positioning System (GPS) can be used for purposes other than navigation and positioning
- The utility of scattered GPS signals from rough surfaces brings a new technology for microwave remote sensing.
 - The concept is to use GPS in a bistatic radar configuration with the GPS satellite transmitting an L-Band spread spectrum signal, and the receiver on an aircraft or spacecraft platform measuring the reflected signal.

Main Applications

- Ocean Altimetry
- Ocean Surface Wind Retrieval
- Sea Ice Remote Sensing
- Earth Moisture Remote Sensing
- Passive Target Detection
- Terrain Imaging

Geometry of GPS scattered signal



Measure Technique

- Direct Transmitting GPS Signal is RHCP (Right-Hand Circularly-Polarization)
 - Scattered signal is LHCP (Left-Hand Circularly-Polarization)due to phase shift at reflection
- **Correlation is expressed as the integral:**

$$Y(\tau, \tau_0, t) = \int_0^{t_i} a(t + \tau_0 - \tau) \cdot u(t + \tau_0) dt$$

Here a(t) is the locally generated C/A code, u(t) is the received signal, τ_0 is specular point delay, τ_1 is delay between [τ_0 -M, τ_0 +32-M] at half code chip, T_i is integration time,

Delay Mapping Receiver Design



Delay Mapping Receiver

12 parallel channels

- Channel 1-6 connected to RHCP antenna to receive direct signal from GPS satellite, working in close loop for code tracking, and positioning calculation.
- Use 2hsin(θ) to calculate the path delay of the specular points relative to the direct signals for each satellite.
 - Channel 7-12 connected to LHCP antenna to receive scattered signal, working in open loop mode.
- Channel 7-12 is configured to the code phase and carrier frequency calculated from direct channels.
 - Local replica is then moved between $[\tau_0 M, \tau_0 + 32 M]$ to record the cross-correlation power stepped by half chip bins.
 - At each step, the signal is integrated for one millisecond ,measurements are filtered and output at 1Hz.





Data Collection

- 9 Test flights were done at TianJin, QingDao, DaLian with the DMR mounted on YUN-12 airplane.
- RHCP antenna is mounted on the top of the airplane to receive the direct signal from GPS satellite
- LHCP antenna at the bottom of the airplane, facing downward to sea surface to receive scattered signals.

Data Collection



Equipped DMR

LHCP Antenna



YUN-12 Airplane For Test



RHCP Antenna



B-3807-

MS

Laptop & Software

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Direct & Scattered Signal



direct and scattered cross-correlation power of satellite NO.22

During Taking Off & Landing, Test Window Closed, LHCP antenna was Shielded

Example of Output Data



Signal of LHCP Antenna

Flight Time: Aug.03.2004 Flight Height: About 1000m SNR:>15dB Cross-correlation of 32 half code Delay was Measured

Example of Sep.9.2004

Ocean Reflected Wave Form (Measured)

(From scatterometer) Flight Path wind speed 7.6 38.7 7.4 38.6 38.5 7.2 38.4 北隍坂 Latitude 38.3 6.8 38.2 6.6 38.1 6.4 38 6.2 37.9 120.7 120.8 120.9 121 121.1 121.2 121.3 longitude

Wind Speed Contour



Flight Height: ~3000m Flight Date: Sep.9.2004 Mean Wind Speed: ~7.2m/s

Reflection Waveform of 3 Flights

Wind From Scattermeter (Mean of 1 hour)

13:00 Sep.10.2004 >6m/s 13:00 Aug.03.2004 ~2m/s 11:00 Sep.18.2004 <1m/s

Wind Retrieval

Sea surface wind vector can be obtained by comparing the analyzed model and measured data





Conclusion

- Ocean Scattered GPS Signal was Successfully Detected
- Cross-Correlation Expansion Was Demonstrated
- Wind Information can be get from the wave characteristics

Thanks for your attention!