GNSS Low-Cost High-Accuracy Receiver (L-CHAR)

Dinesh Manandhar

Center for Spatial Information Science

The University of Tokyo

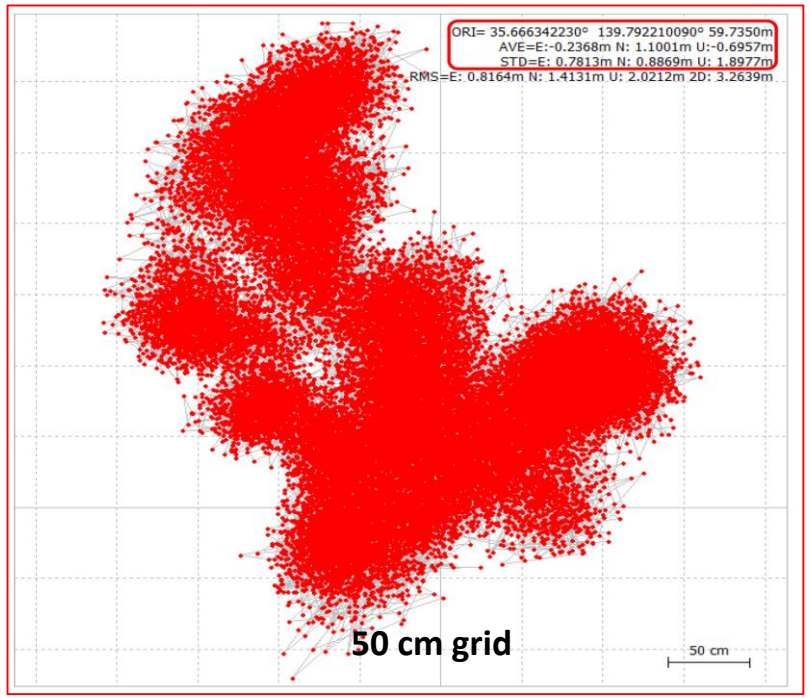
Contact Information: dinesh@iis.u-tokyo.ac.jp

High Accuracy Receivers are Expensive

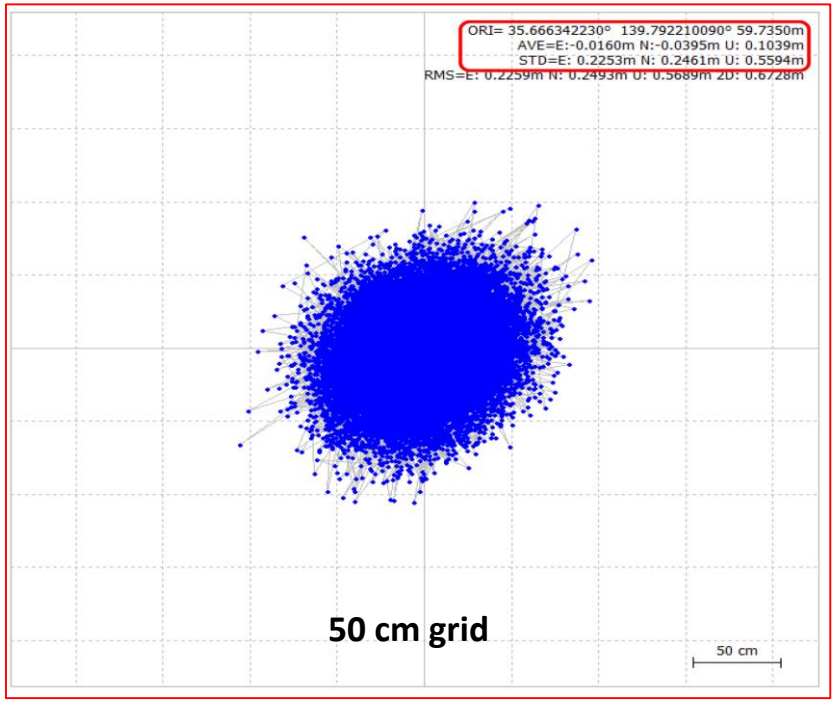
- High-Accuracy Survey Grade Receivers are multi-frequency and multi-system receivers
  - L1/L2/L5, G1/G2, B1/B2/B3 etc
  - GPS, GLONASS, BGALILEO, BeiDou, QZSS etc
  - Price varies from $3, 000 to $30,000 or more.
- However, Low Cost Receivers are also capable of
  - Multi-System: GPS, GLONASS, GALILEO, BeiDou, QZSS, SBAS etc
  - Basically only in L1-Band Frequency
  - Low Cost: $300 (Multi-GNSS, L1 Only)
  - Very soon: Multi-System, Multi Frequency, L1/L2/L5
    - Broadcom, u-Blox and ST Micro already announced Multi-System, Multi-Band GNSS Chips for Mass Market

Dinesh Manandhar, CSIS, The University of Tokyo, dinesh@iis.u-tokyo.ac.jp

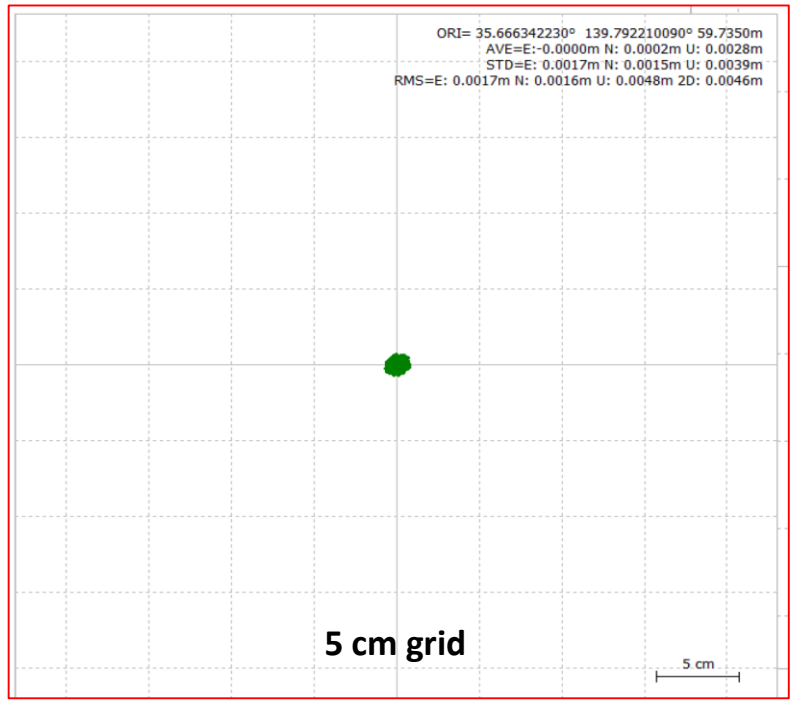
How accurate is GPS Position?



SPP (Single Point Position)



DGPS (Differential GPS)



RTK (Real Time Kinematic)

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Errors in GPS Observation (L1C/A Signal)

Error Sources	One-Sigma Error , m		Comments
	Total	DGPS	
Satellite Orbit	2.1	0.0	Common errors are removed
Satellite Clock	2.1	0.0	
Ionosphere Error	4.0	0.4	Common errors are reduced
Troposphere Error	0.7	0.2	
Multipath	1.4	1.4	
Receiver Circuits	0.5	0.5	

If we can remove common errors, position accuracy can be increased.

Common errors are: <u>Satellite Orbit Errors, Clock Errors and Atmospheric Errors (within few km)</u>

Table Source : http://www.edu-observatory.org/gps/gps_accuracy.html#Multipath

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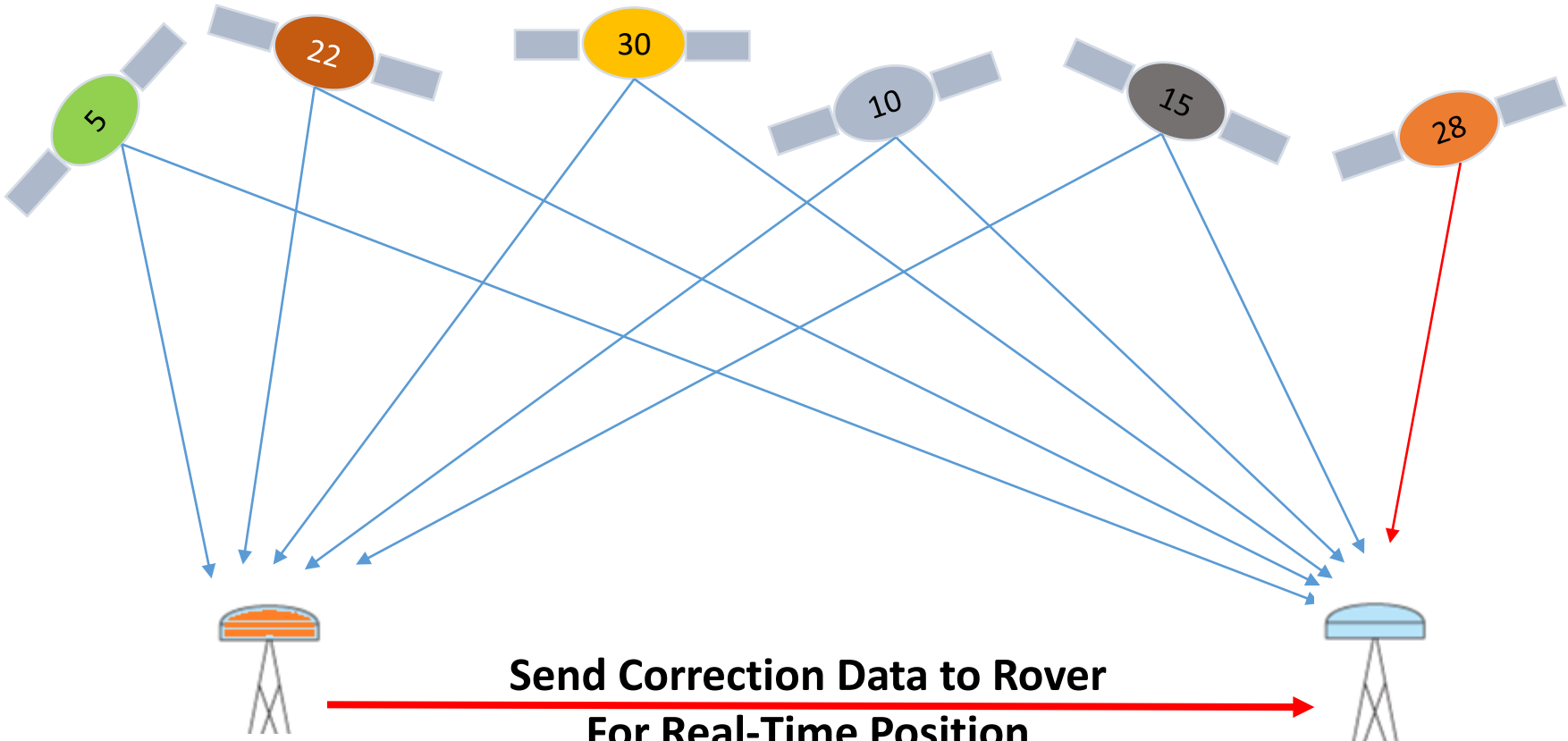
Principle of Differential Correction



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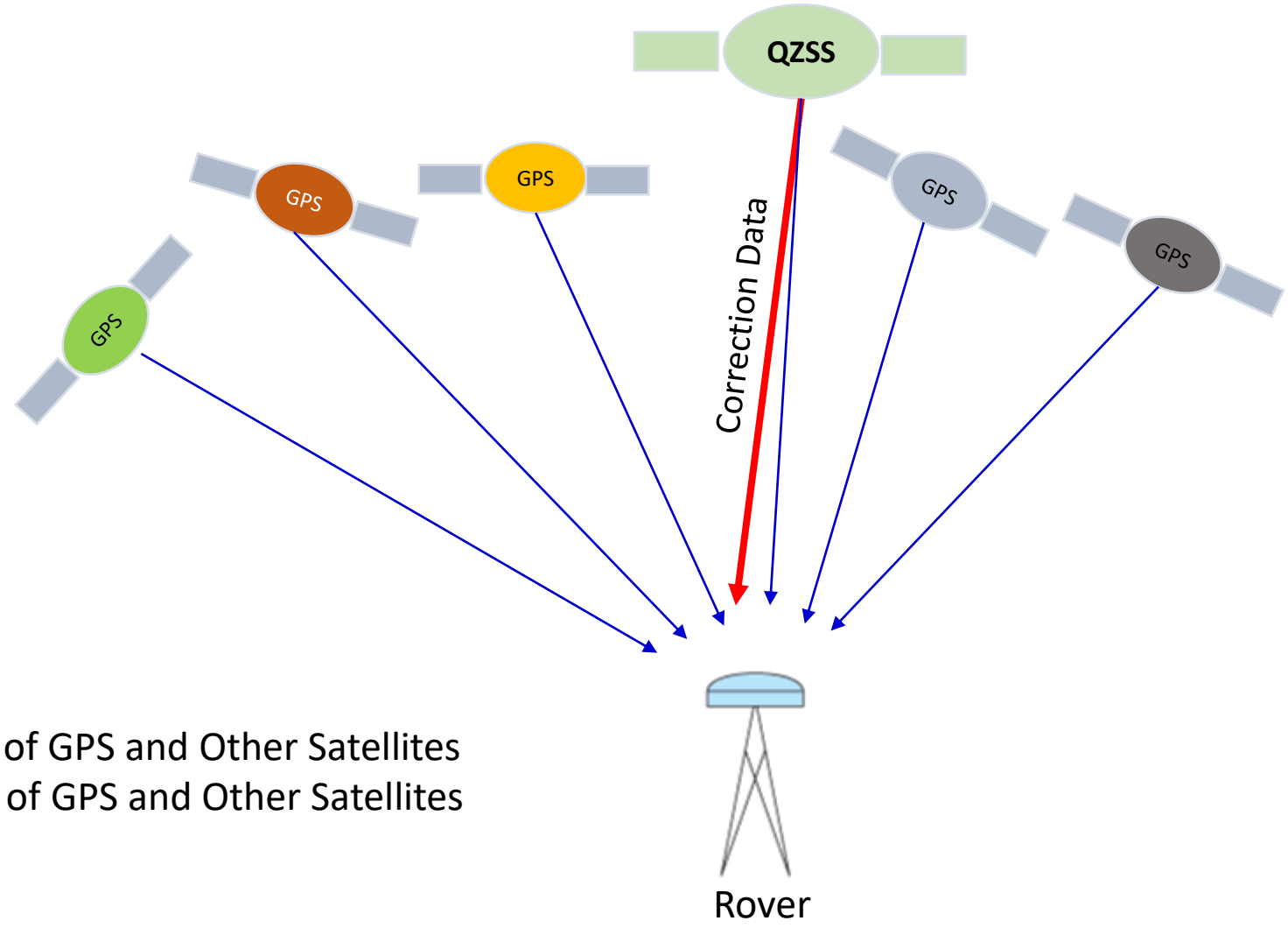
Principle of QZSS MADOCA / CLAS Service



Correction Data:
Satellite Orbit Error of GPS and Other Satellites
Satellite Clock Error of GPS and Other Satellites

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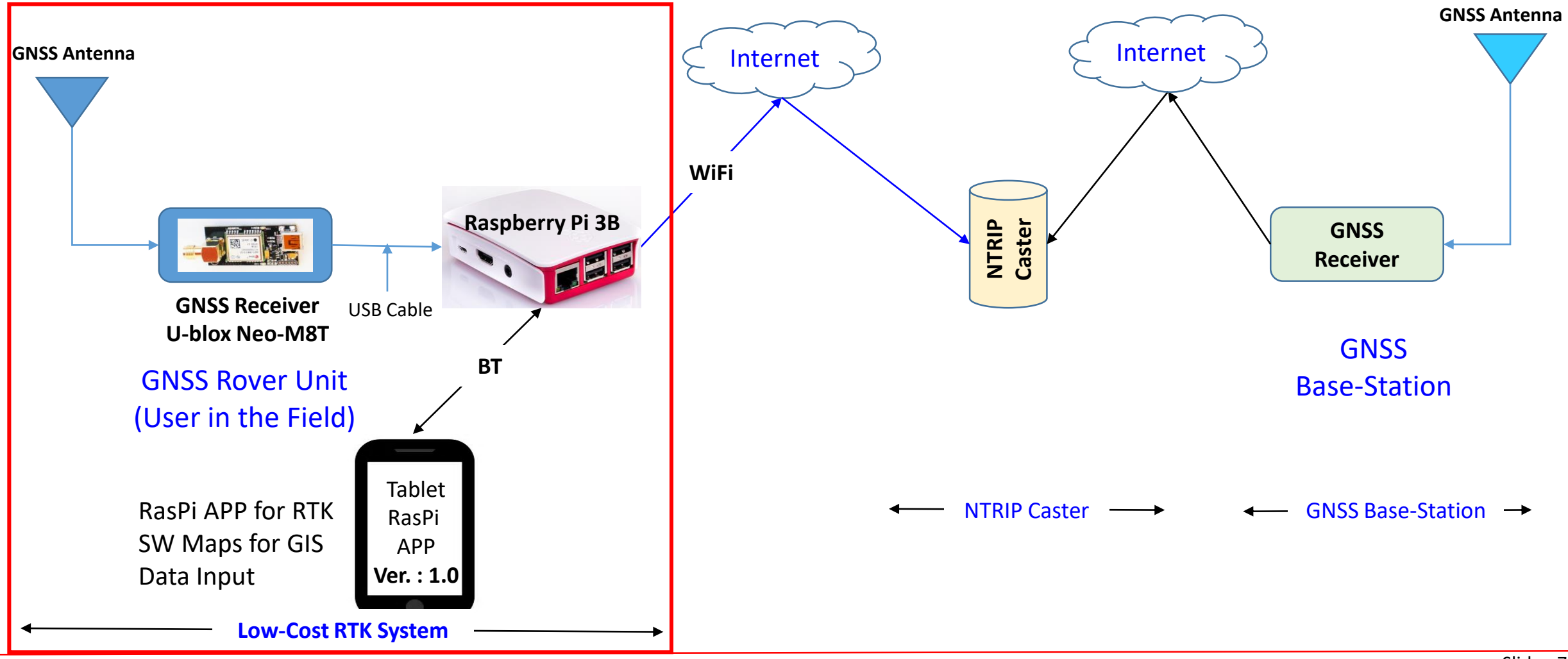
Low-Cost High Accuracy System



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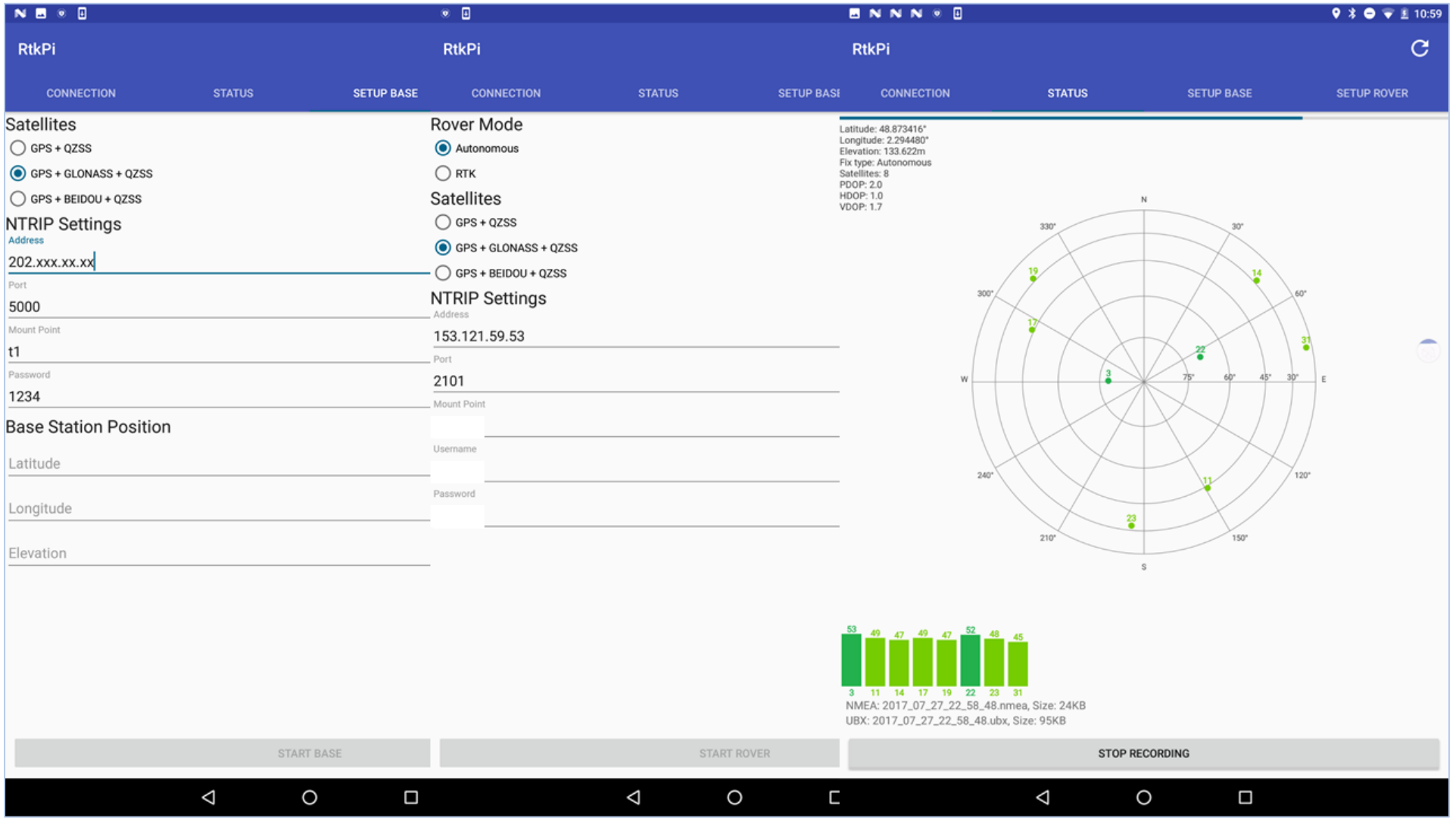
RTK-Pi APP for Low-Cost RTK System



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Board Computer for Low-Cost RTK System

Raspberry Pi 3B for Realtime and Postprocessing RTK

Raspberry Pi Zero w/WiFi & BT for Post-processing RTK

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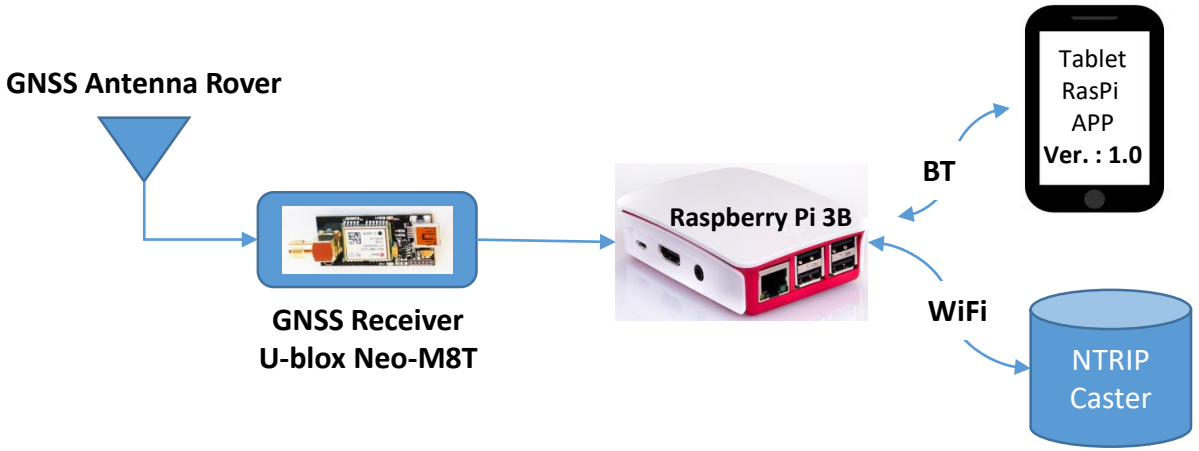
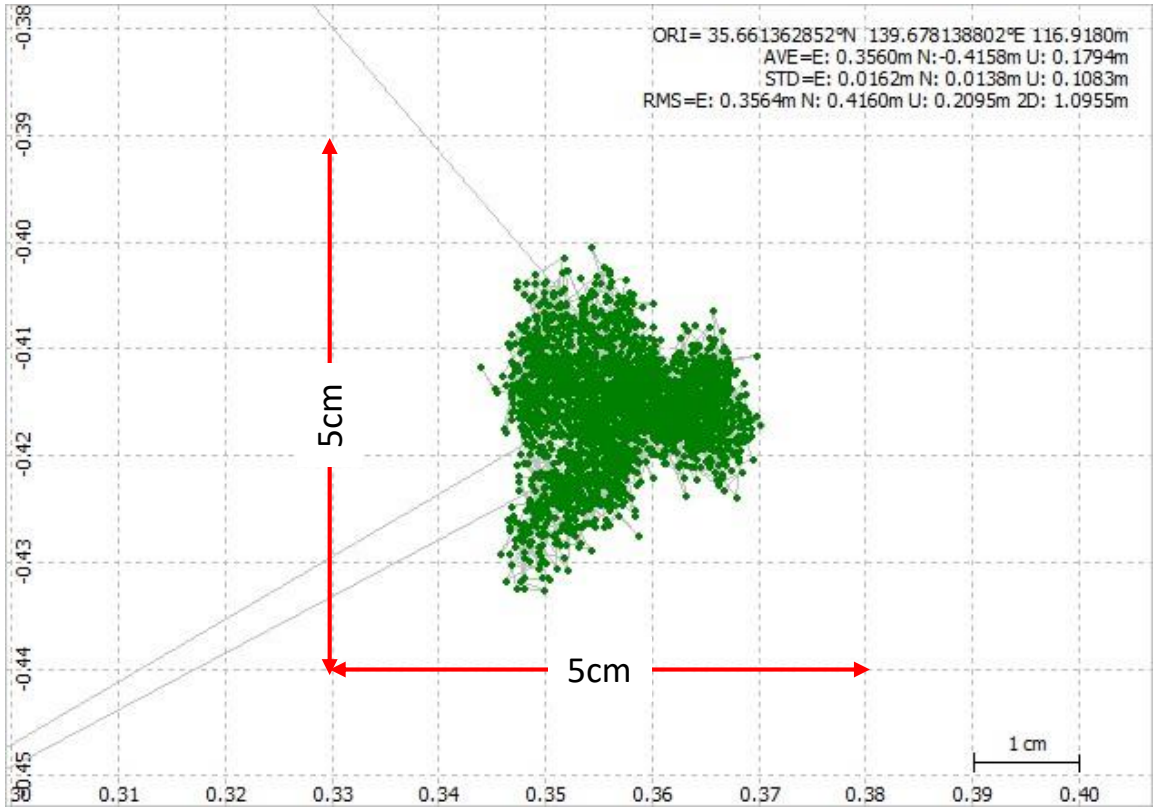
Accuracy from Low-Cost RTK System



Rover-Station:
Receiver: u-blox M8T
Antenna: Zephyr 2
Computer: RaspberryPi 3B+
Distance between Base and Rover : about 12Km

Base-Station:
Receiver: Trimble NetR9
Antenna: Zephyr 2



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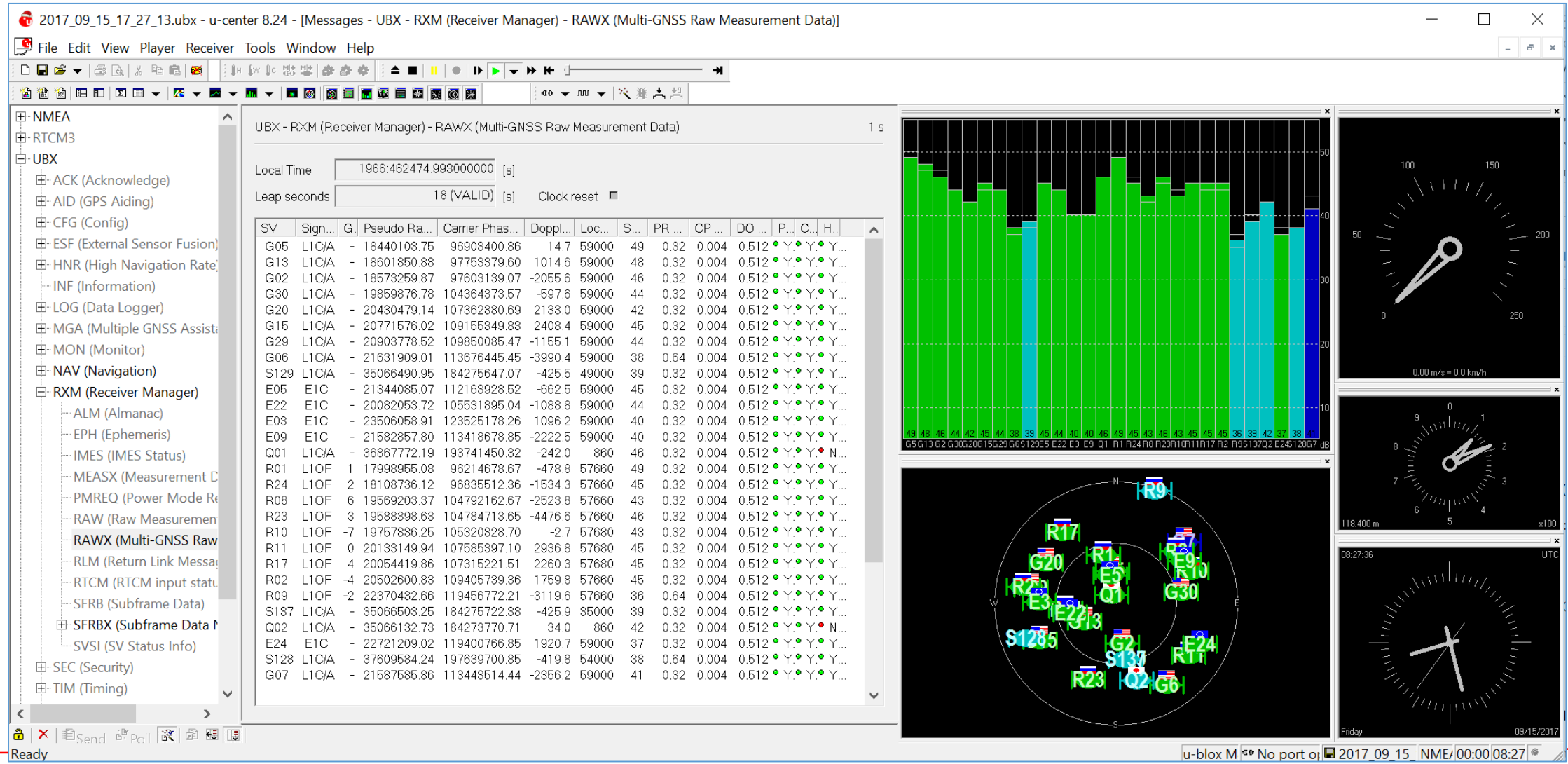
Data from Low-Cost RTK System



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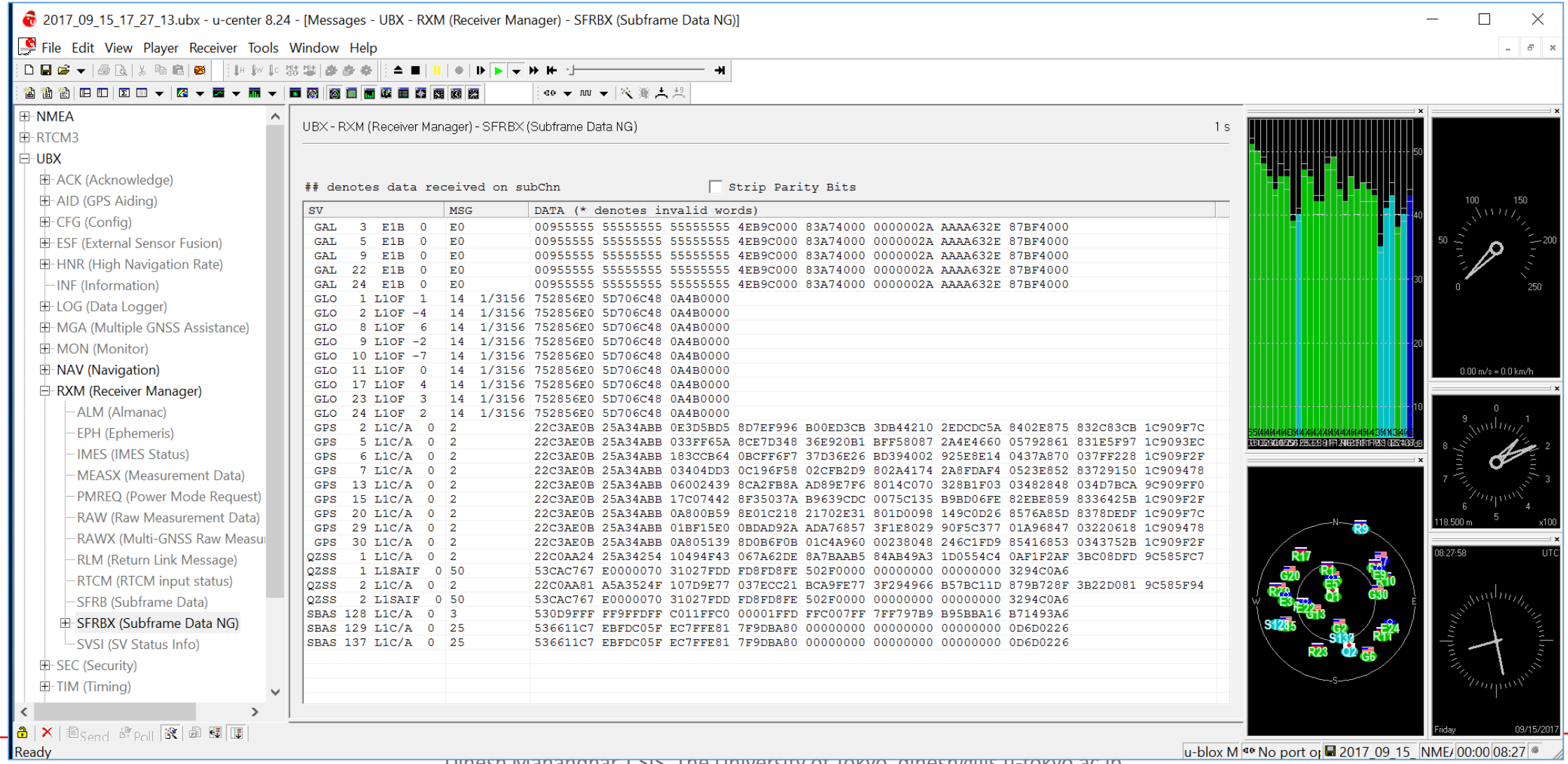
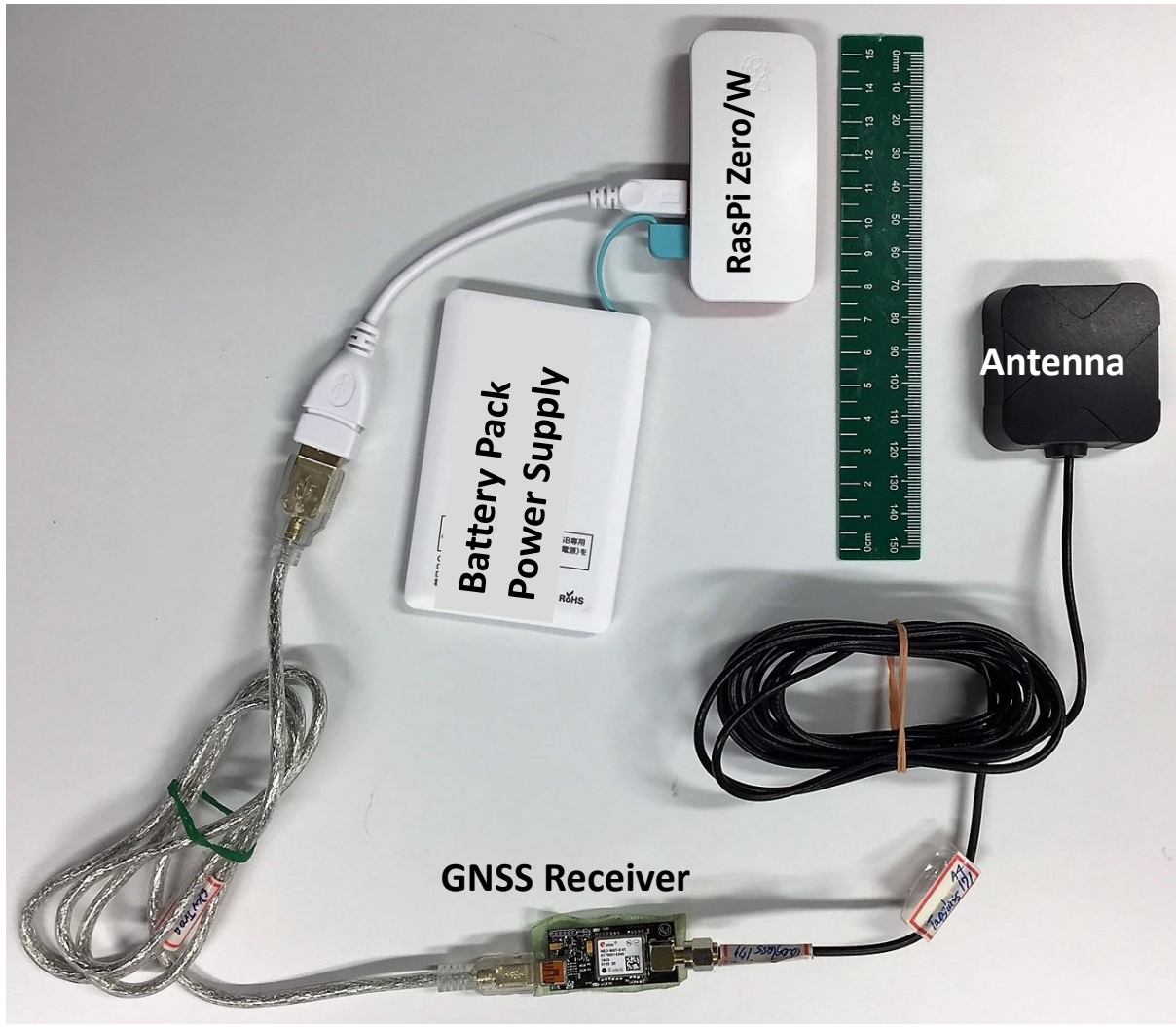
Data from Low-Cost RTK System



Simple to Use, Low-Cost System

Simple to Use, No Commands, Just One Time Setting
Connect Antenna, Receiver and Battery Pack
Device Starts Logging GNSS Raw Data required for RTK Post-Processing



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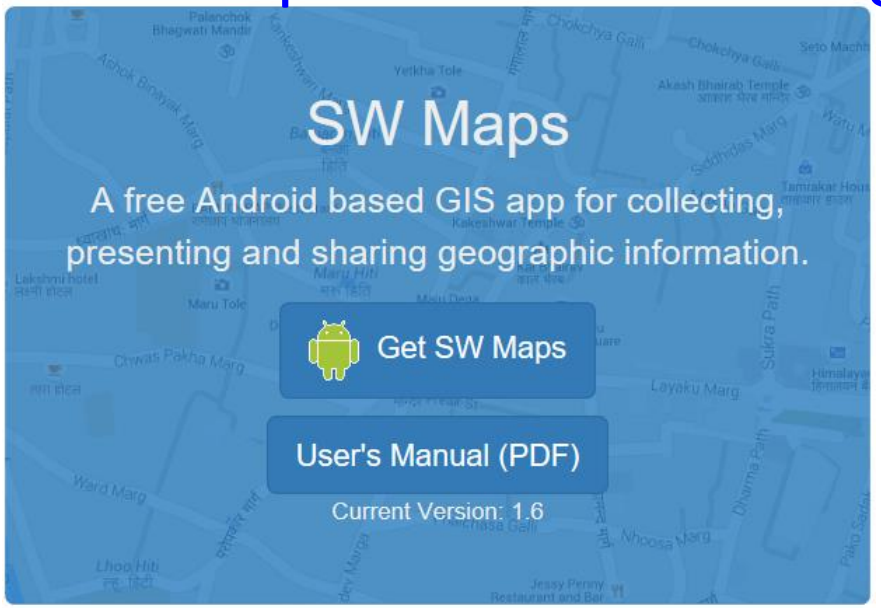
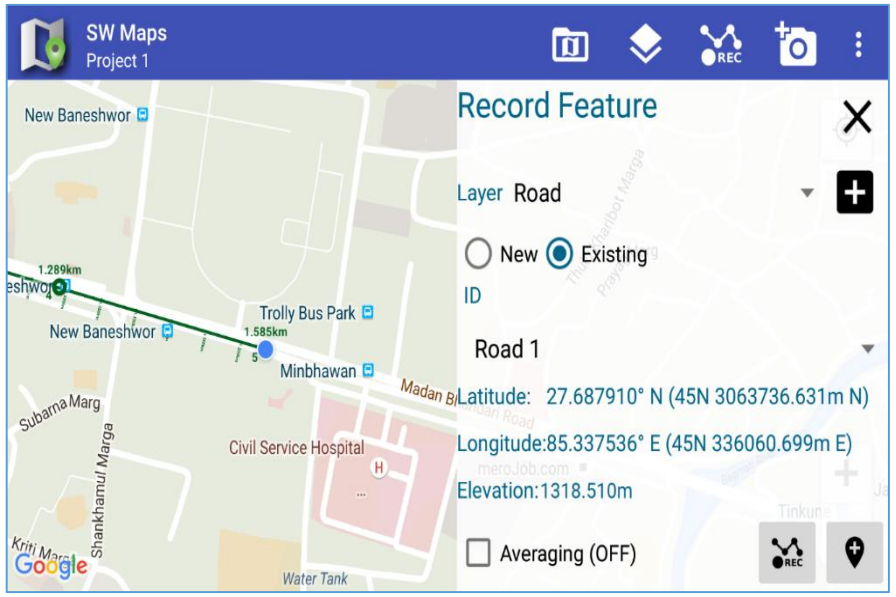
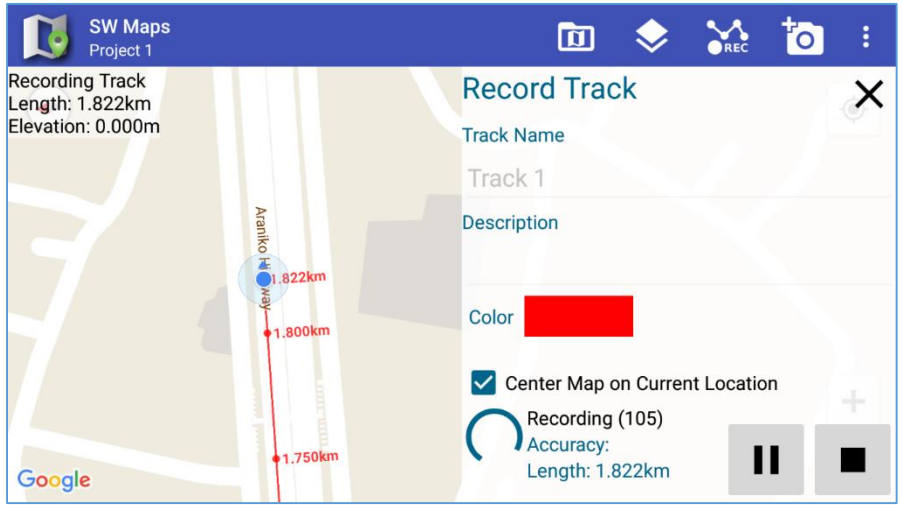
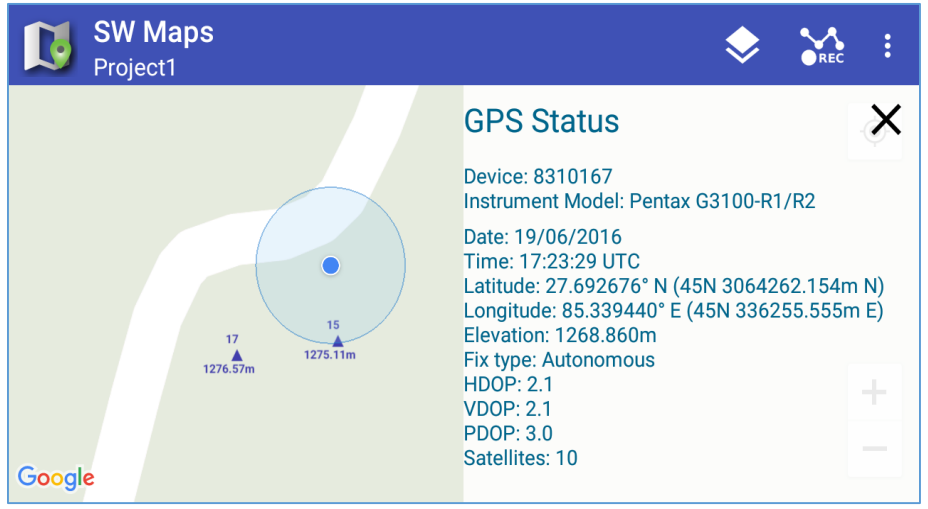
SW Maps APP to Integrate GPS Data into GIS









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Conclusion

- Accuracy better than few tens of centimeters using Low-Cost Receiver in RTK mode is possible.
  - Both Base and Rover with Low-Cost Receiver
  - Smaller base length, < 10km
- Accuracy better than few centimeters using Low-Cost Receiver in RTK mode is possible.
  - Base with High-End Receiver and Low-Cost Receiver
  - Smaller base length, < 5km
- Our Target of Low-Cost High-Accuracy Receiver
  - $100x100cmx100gm (Cost- Accuracy-Weight)

Dinesh Manandhar, CSIS, The University of Tokyo, dinesh@iis.u-tokyo.ac.jp

Additional Information

Please visit website at

http://www.csis.u-tokyo.ac.jp/~dinesh/

Or Contact:

dinesh@csis.u-tokyo.ac.jp

Sample Raw Data can be downloaded to Check Accuracy of RTK Processing

1. High-End Base (NetR9) Data vs Low-End Rover (u-blox M8T) Data
2. Low-End Base (u-blox M8T) Data vs Low-End Rover (u-Blox M8T) Data