



## ***ICG-6 Working Group A***

# **Relationship between Visible Satellite and Receiver Noise Floor**

**National Time Service Center, CAS**

**Prf. LU Xiaochun**

**Tokyo, Japan, Sep., 8, 2011.**



**I . Background**

**II . Analyzing Method**

**III . Simulation Result**

**1. Simulation Condition**

**2. Simulation Process**

**IV . Influence on Ranging Accuracy**

**V . Conclusion**



# *Background*

- Multi-GNSS world is coming and it will provide more visible satellites and more signals.
- Interoperability is an effective way to provide better services to users.
- On the one hand, increasing satellite number will improve PDOP value. On the other hand it will raise receiver noise floor.



# Background

- The noise floor is not only caused by intra-system signals, but also caused by inter-system signals .
- Increased noise floor will impact the service.
- Analyze the relationship between visible satellite and noise floor is benefit for interoperability.



**I . Background**

**II . Analyzing Method**

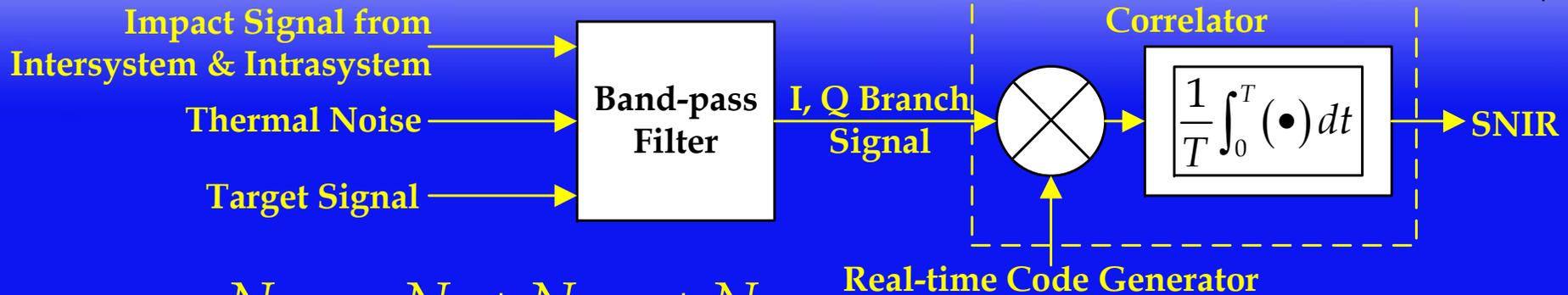
**III. Simulation Result**

**1. Simulation Condition**

**2. Simulation Process**

**IV. Influence on Ranging Accuracy**

**V . Conclusion**



$$N_{total} = N_0 + N_{inter} + N_{intra}$$

$$= N_0 + \sum_{q=1}^{Q-1} \sum_{k=1}^{K_q} \sum_{j=1}^{J_q} P_{q,k}^{(j)} k_{q,k}^{(j)} (\Delta f_{q,k}^{(j)})$$

$$+ \sum_{i=1}^{I-1} P_M^{(i)} K_M^{(i)} (\Delta f_M^i) + \sum_{u=1}^{U-1} \sum_{i=1}^I P_u^{(i)} k_u^{(i)} (\Delta f_u^{(i)})$$

$N_{total}$ : Total complex noise floor.

$N_0$ : Thermal noise (-201.5dBW/Hz).

$N_{intra}$ : Equivalent noise power density of impact signal from satellites belonging to the same system.

$N_{inter}$ : Equivalent noise power density of impact signal from satellites belonging to the other system.



**I . Background**

**II . Analyzing Method**

**III . Simulation**

**1. Simulation Condition**

**2. Simulation Process**

**IV . Influence on Ranging Accuracy**

**V . Conclusion**

Consider the following signals:

Signal		Minimal receive power (dBW)	Maximal receive power (dBW)
BeiDou	MBOC(6,1)	-158	-155
	BOC(14,2)	-158	-155
GPS	BPSK(1)	-158.5	-153
	BPSK(10)	-160	-155.5
	BOC(10,5)	-157	-150
	MBOC(6,1)	-157	-154
Galileo	BOC_COS(15,2.5)	-155	-150
	CBOC(6,1)	-157	-154

$N_0$ : Thermal noise (-201.5dBW/Hz)

Front receive band-width: 30MHz;

Receiver location: Lintong, (34.27°N, 109.22°E, 450m).



# *Simulation*



**Three Constellation conditions we simulated:**

**1、 Current Constellation**

(GPS 33+BeiDou 9+Galileo 2)

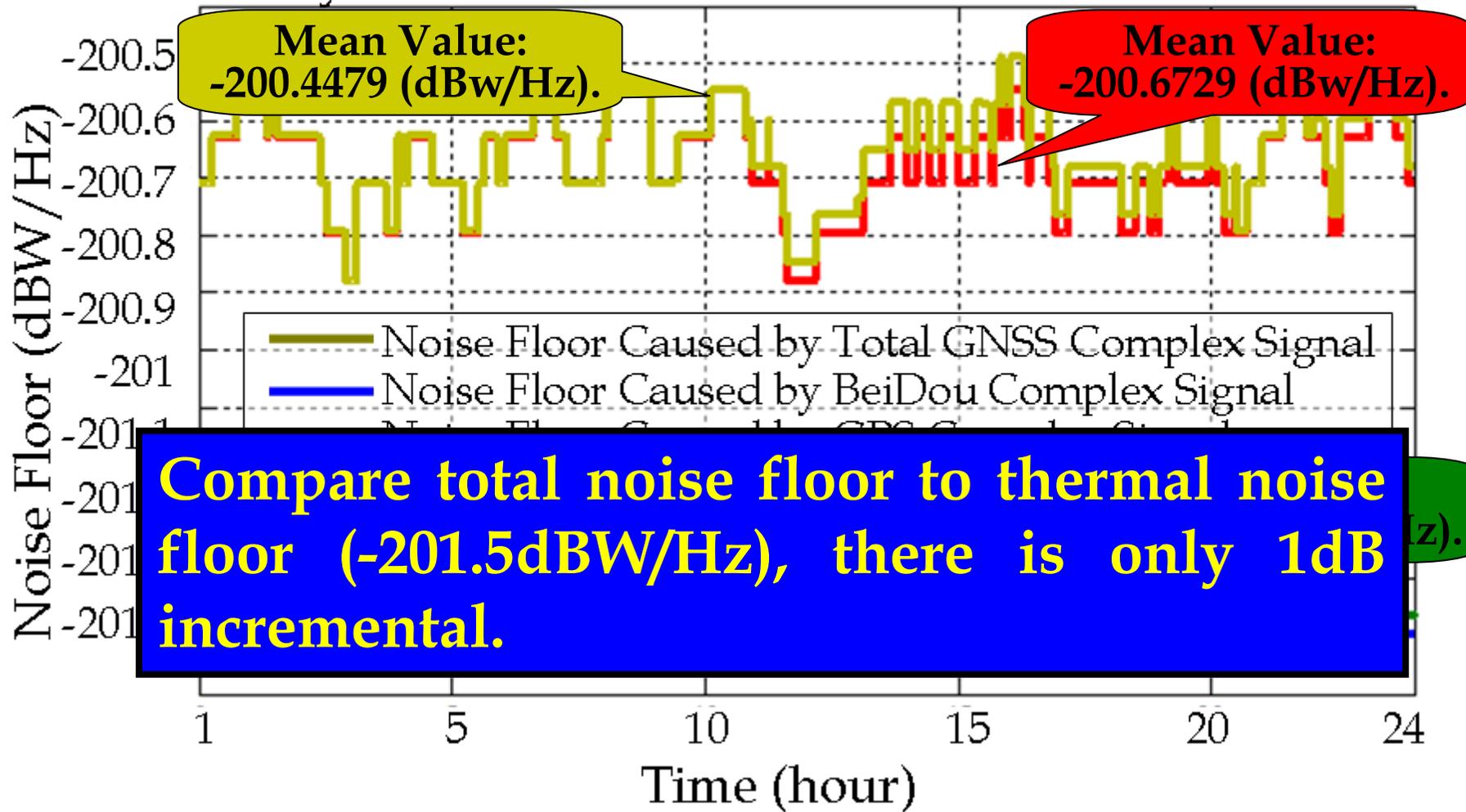
**2、 Designed Constellation**

(GPS 33+BeiDou 35+Galileo 30)

**3、 Adding Visible Satellite Numbers**

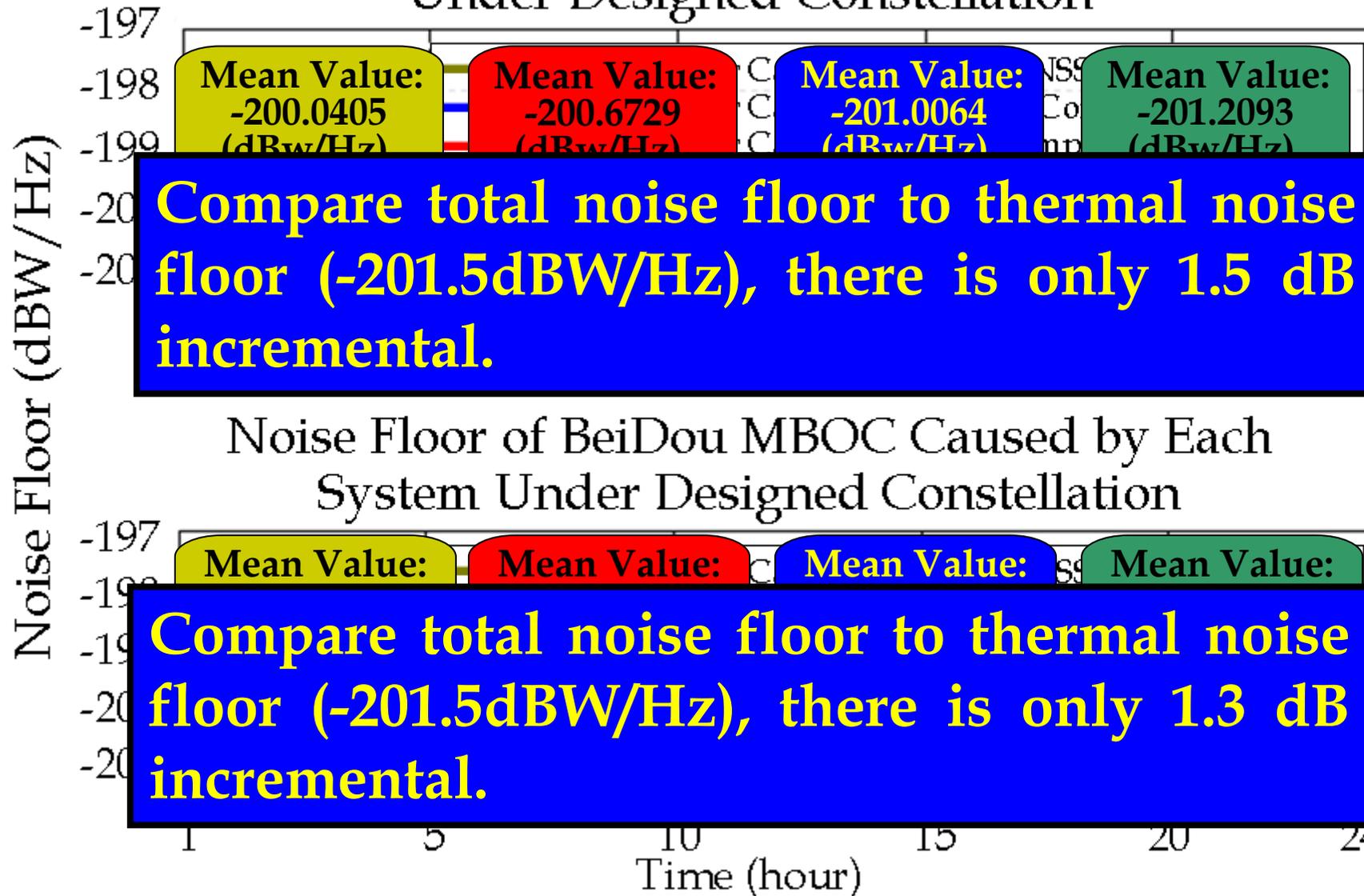
(GPS 533+BeiDou 535+Galileo 530)

## Noise Floor of GPS MBOC Caused by Each System Under Current Constellation

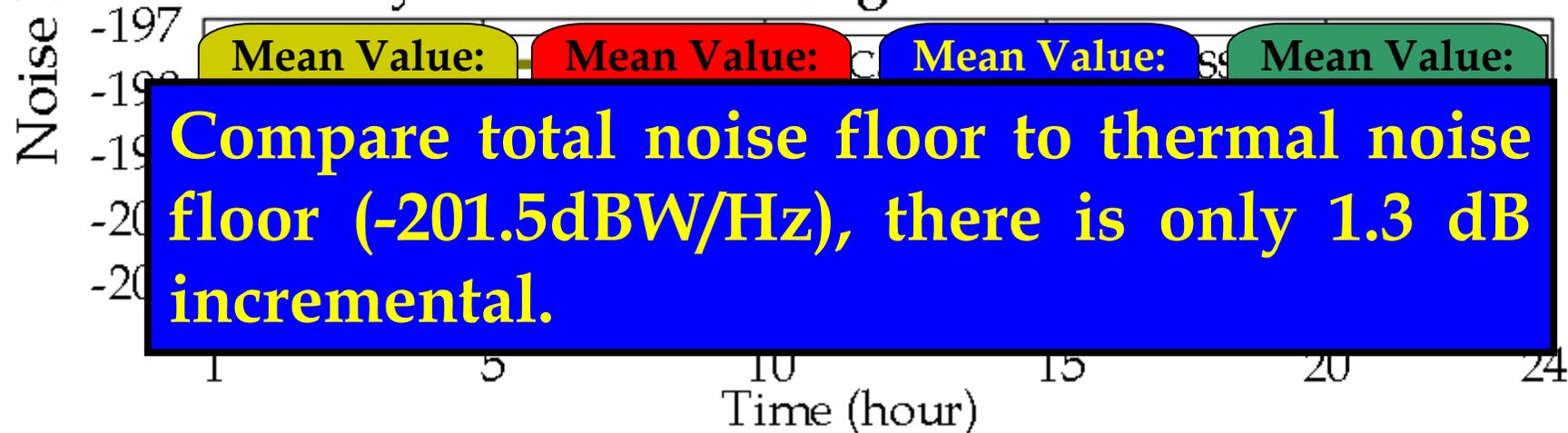


# Noise Floor of Designed Constellation

Noise Floor of GPS MBOC Caused by Each System Under Designed Constellation

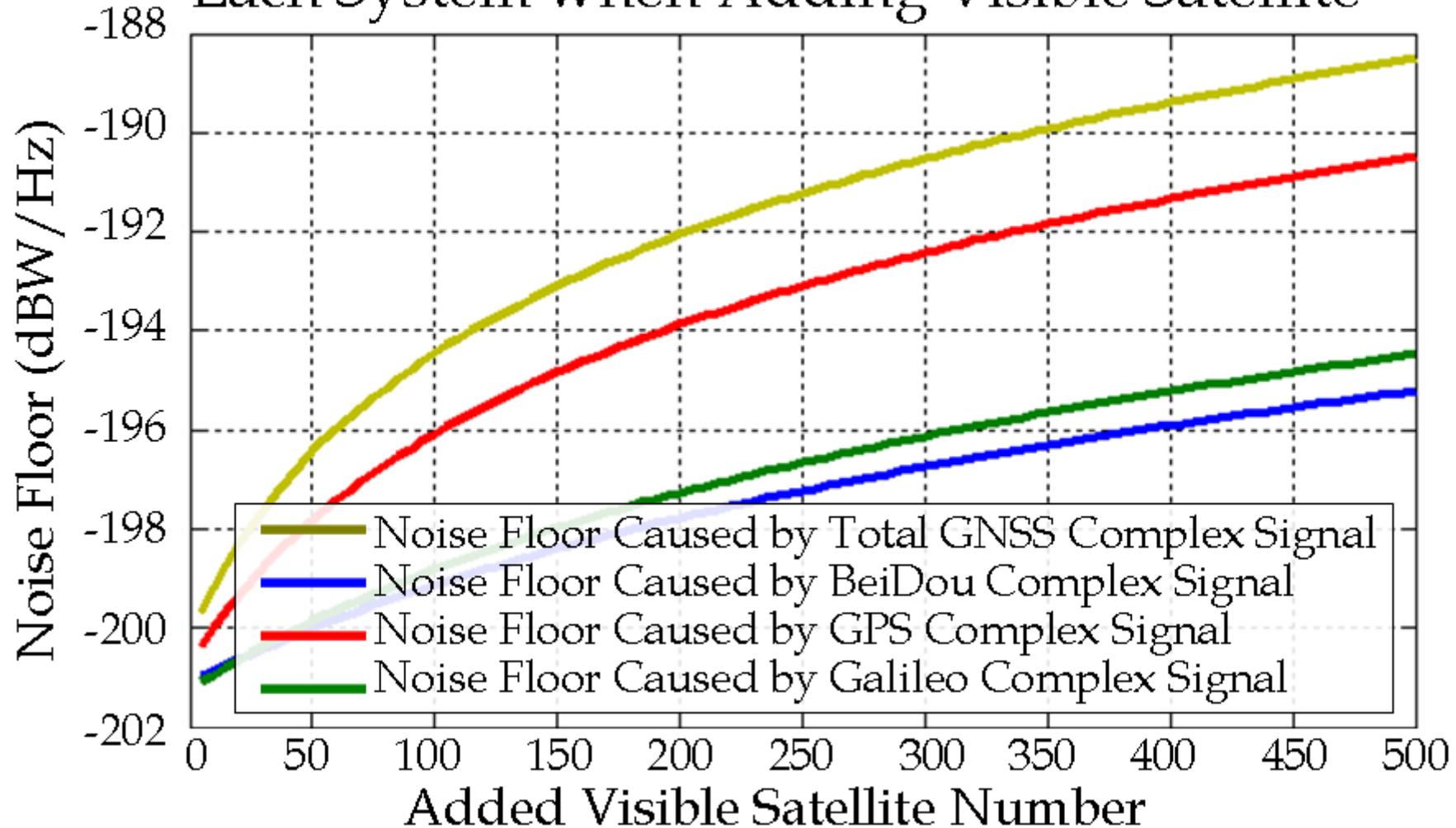


Noise Floor of BeiDou MBOC Caused by Each System Under Designed Constellation



# Noise Floor of Adding Visible Sat. No.

Noise Floor of BeiDou MBOC Caused by Each System when Adding Visible Satellite

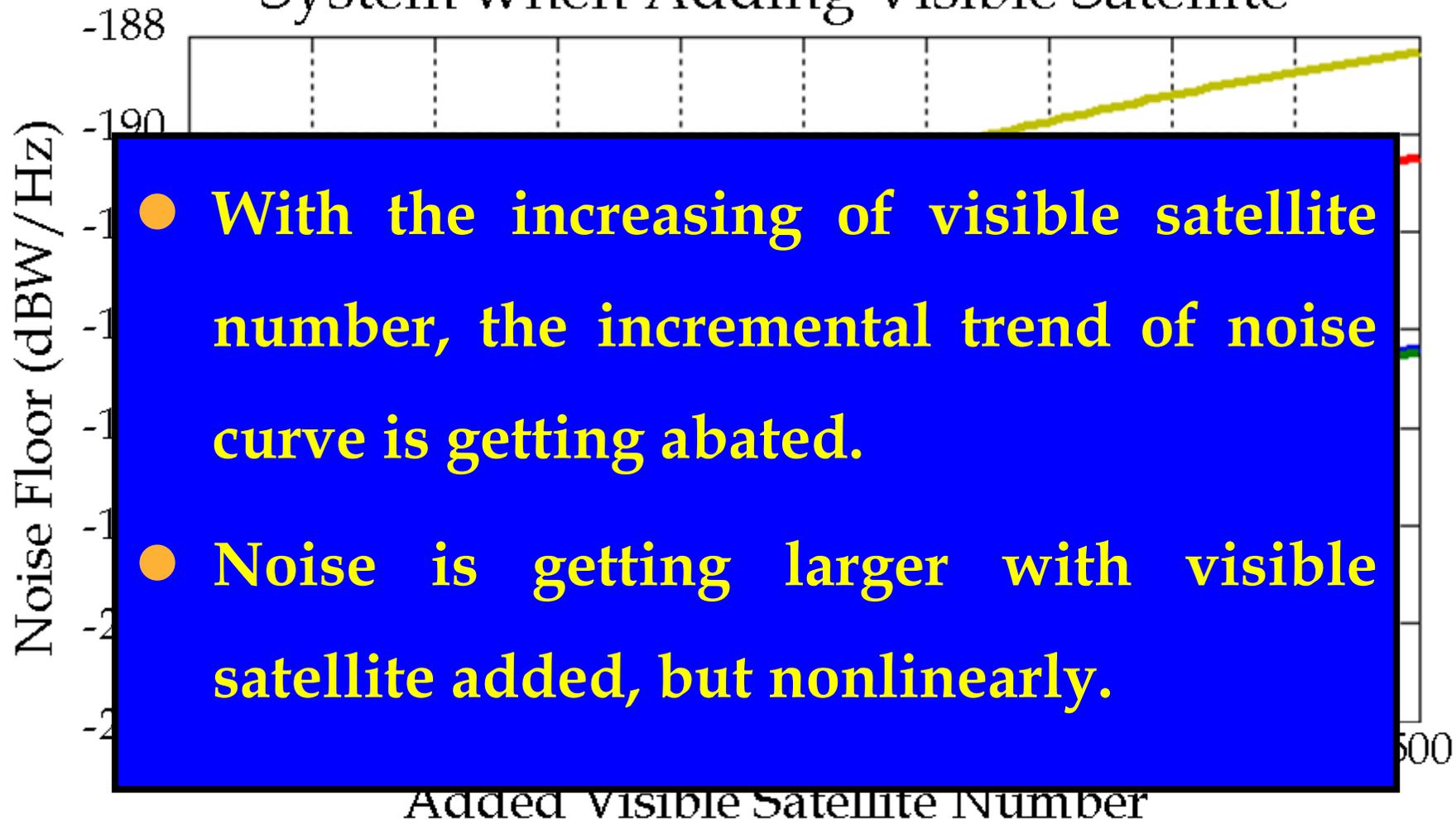




# Noise Floor of Adding Visible Sat. No.

Secondly, choose the target signal be GPS MBOC.

Noise Floor of GPS MBOC Caused by Each System when Adding Visible Satellite





**I . Background**

**II . Analyzing Method**

**III. Simulation**

**1. Simulation Condition**

**2. Simulation Process**

**IV. Influence on Ranging Accuracy**

**V . Conclusion**



# *Influence of Ranging Accuracy*



- Adding Visible satellite number
- Increasing receiver noise floor
- Reducing  $C/N_0$
- Reducing S/N
- Increasing Ranging error

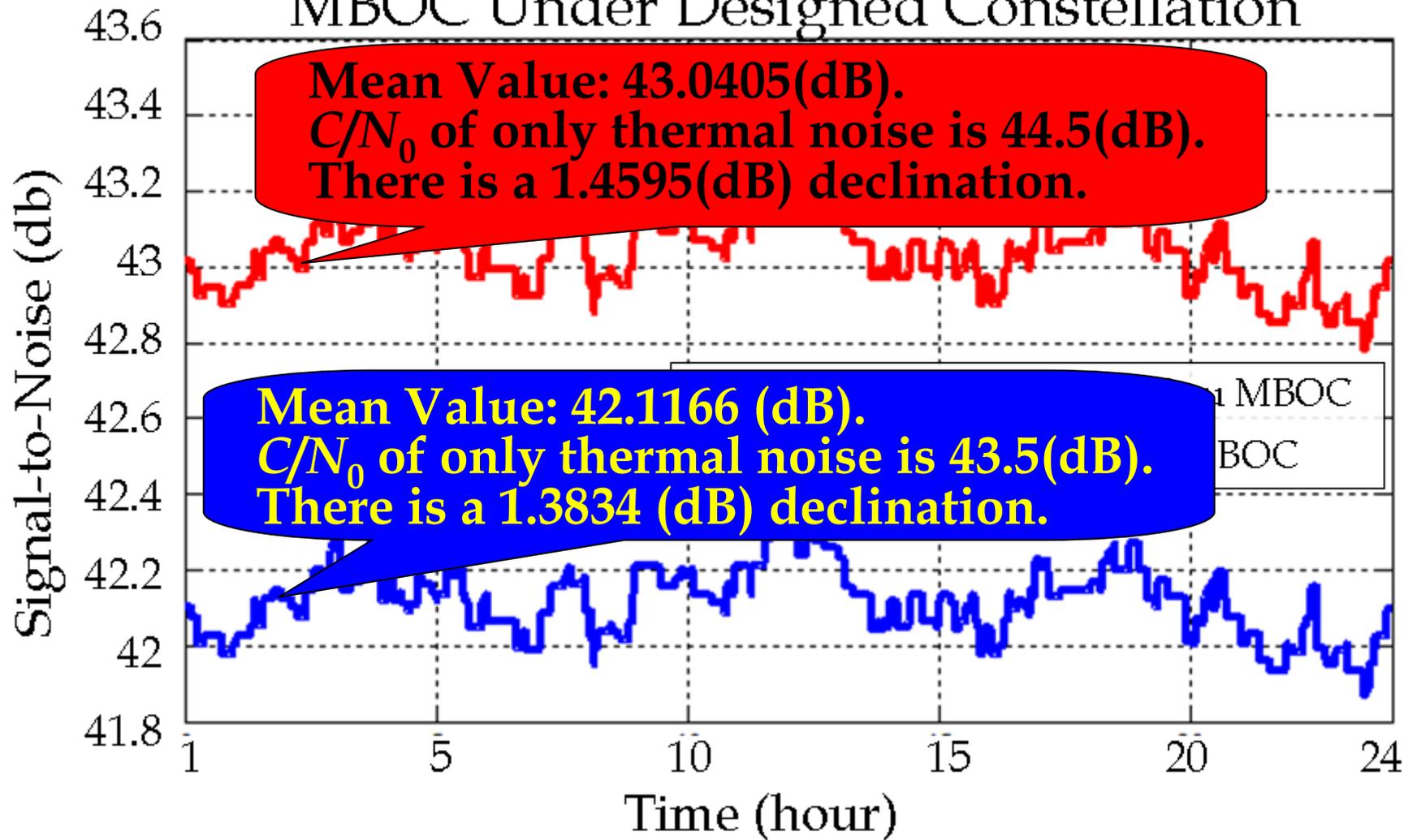
# Influence of Ranging Accuracy

## Variance of Ranging Error:

$$\sigma_{NELP}^2 = \frac{B_L(1-0.25B_L T) \int_{-\beta_r/2}^{\beta_r/2} G_S(f) \sin^2(\pi f \Delta) df}{\frac{C}{N_0} \left( 2\pi \int_{-\beta_r/2}^{\beta_r/2} f G_S(f) \sin(\pi f \Delta) df \right)^2} \times \left[ 1 + \frac{\int_{-\beta_r/2}^{\beta_r/2} G_S(f) \cos^2(\pi f \Delta) df}{T \frac{C}{N_0} \left( \int_{-\beta_r/2}^{\beta_r/2} G_S(f) \cos(\pi f \Delta) df \right)^2} \right]$$

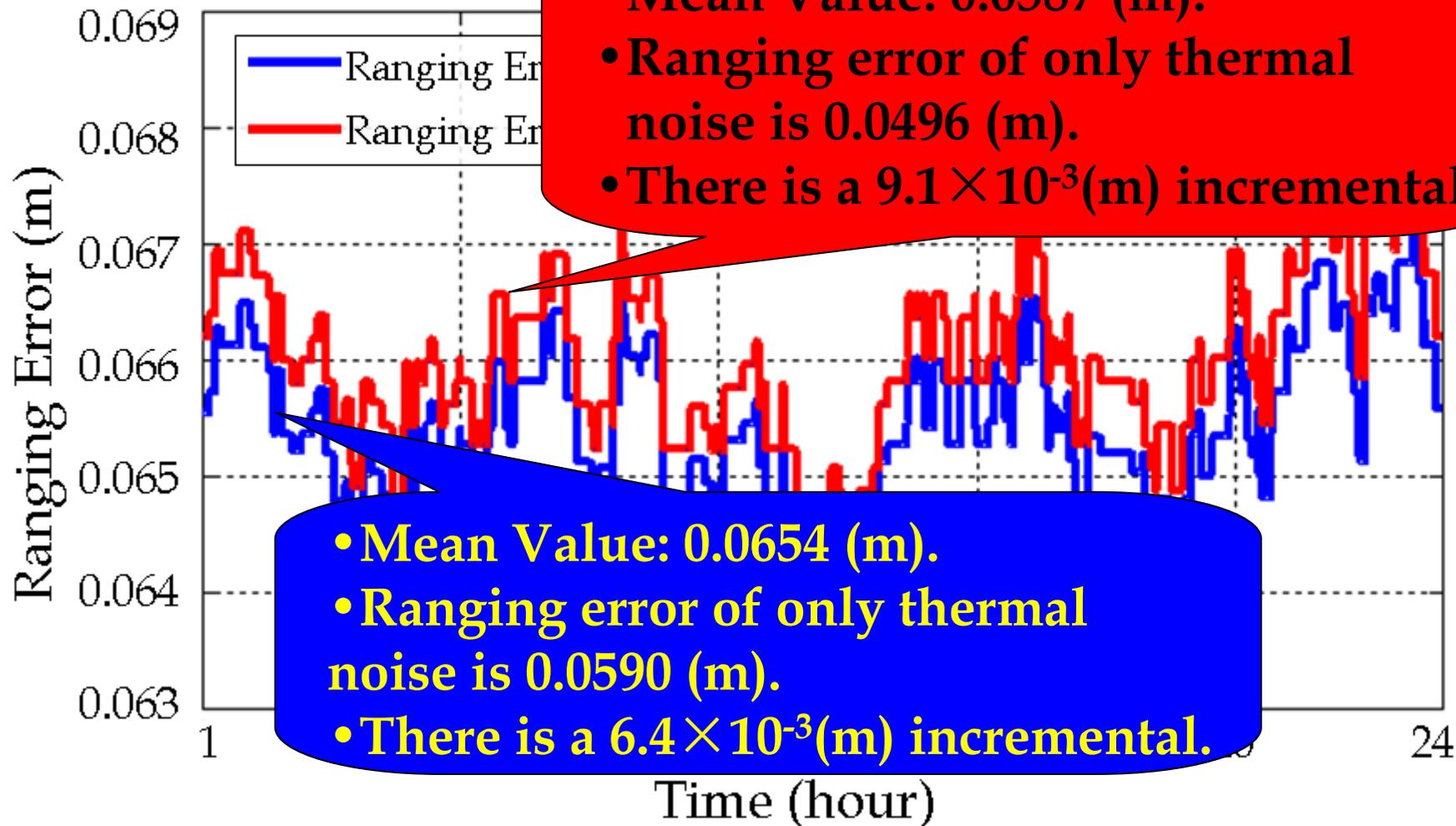
# Influence of Ranging Accuracy

Signal-to-Noise of BeiDou MBOC and GPS  
MBOC Under Designed Constellation



# Influence of Ranging Accuracy

Ranging Error of BeiDou MBOC and GPS  
MBOC U





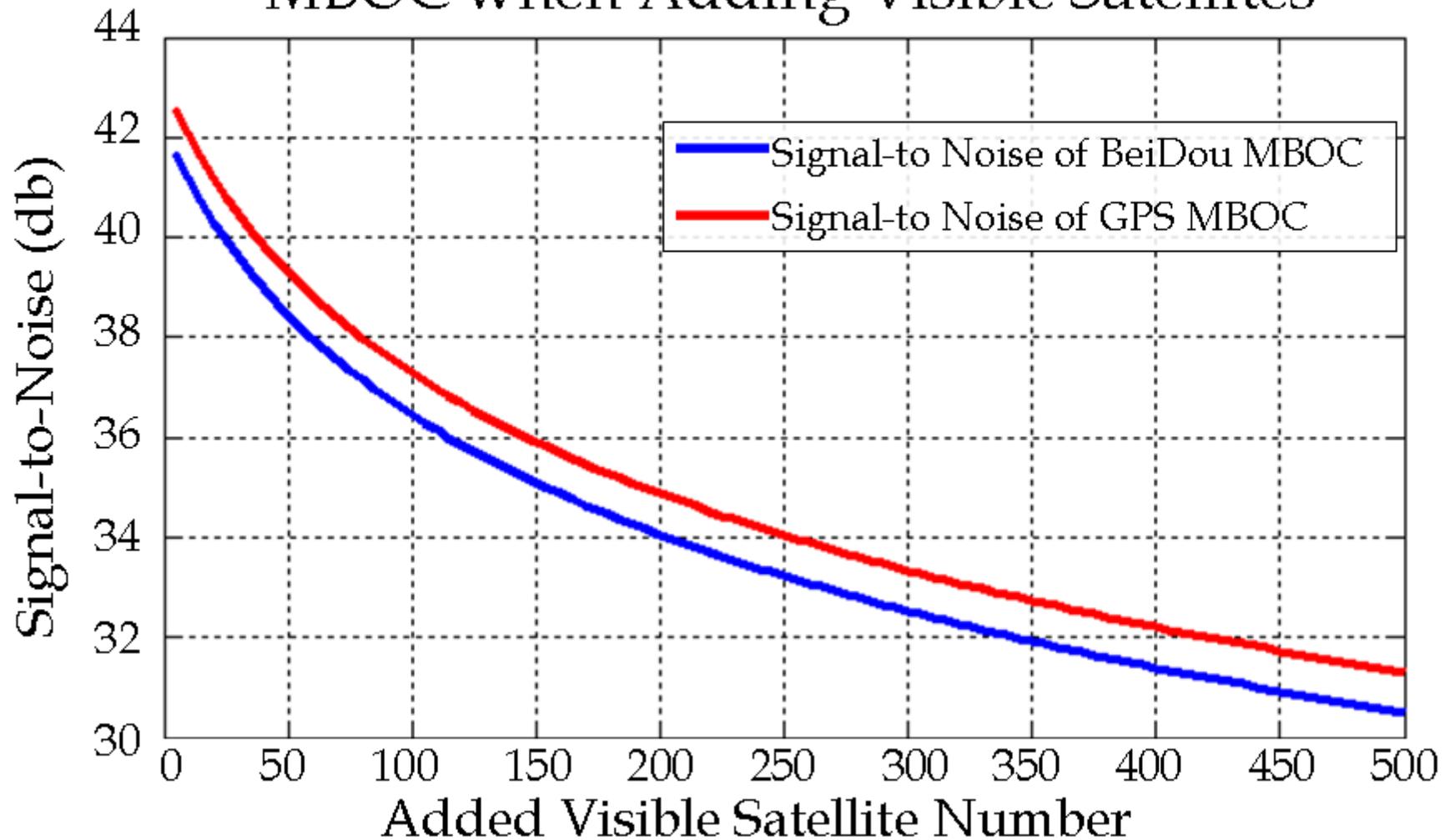
# Influence of Ranging Accuracy

Target Signal	GPS MBOC		BeiDou MBOC	
Value	$C/N_0$ (dB)	Ranging Error (m)	$C/N_0$ (dB)	Ranging Error (m)
Only thermal noise	44.5	0.0496	43.5	0.0590
Thermal noise + GNSS noise	43.0405	0.0587	42.1166	0.0654
Change	1.4595 ↓	$9.1 \times 10^{-3}$ ↑	1.3834 ↓	$6.4 \times 10^{-3}$ ↑
Added Visible Satellite No.	19			

# Influence of Ranging Accuracy

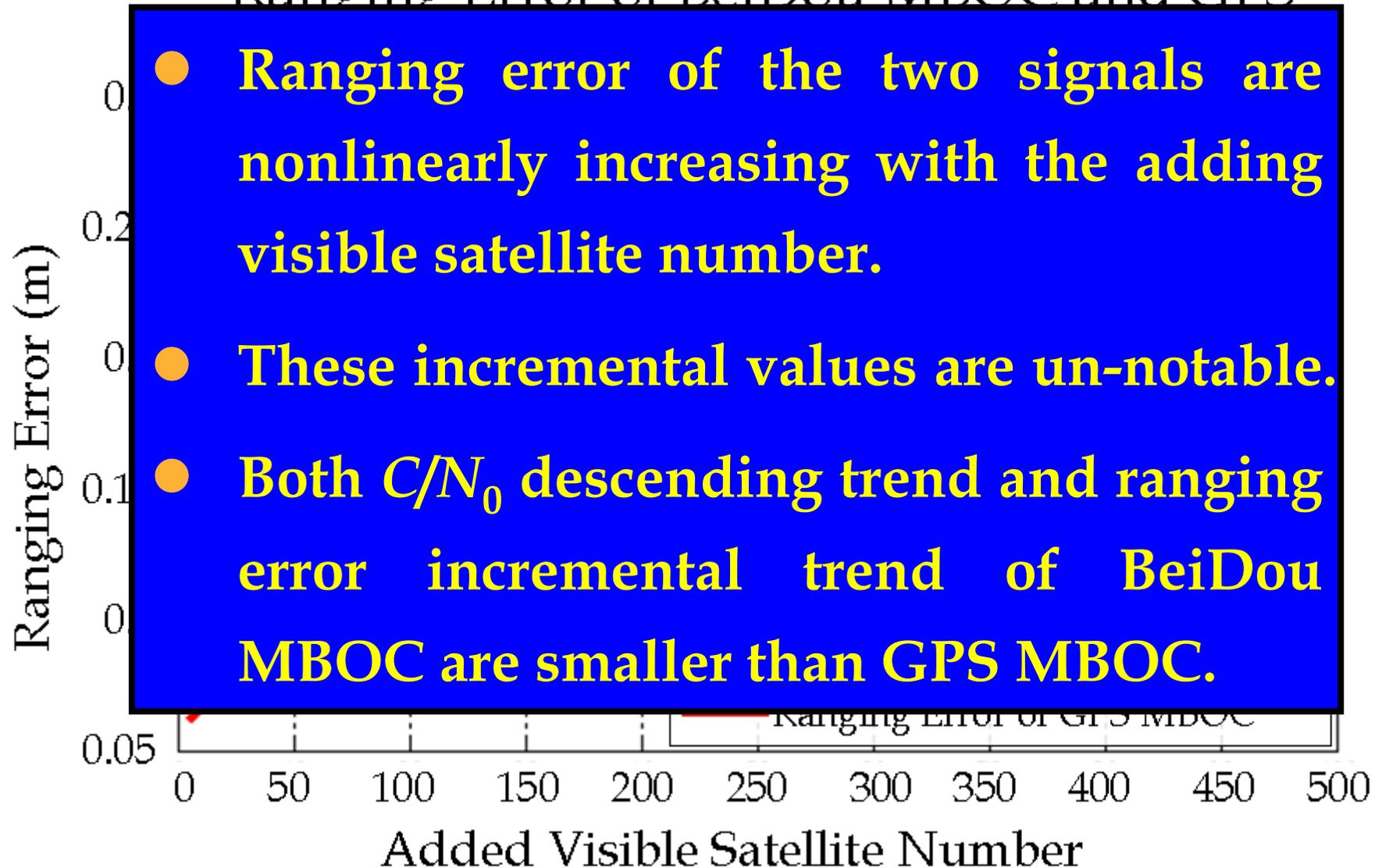


Signal-to-Noise of BeiDou MBOC and GPS MBOC when Adding Visible Satellites



# Influence of Ranging Accuracy

## Ranging Error of BeiDou MBOC and GPS





**I . Background**

**II . Analyzing Method**

**III. Simulation**

**1. Simulation Condition**

**2. Simulation Process**

**IV. Influence on Ranging Accuracy**

**V . Conclusion**



1. Relationship between noise floor and visible satellite number is that, noise floor is getting larger with visible satellite added, this incremental trend is nonlinearly and is getting abate.
2. Ranging errors of BeiDou MBOC and GPS MBOC are slightly increasing with the largen of noise floor.

# *Conclusion*

3. Interoperability has a great potential capability to promote GNSS service performance. This issue has been concerned and debated by both the Providers and the users. The co-relationship between interoperability and service as well as other related issues should be thoroughly researched by a subgroup set up under the framework of ICG. The work done in this regard will contribute to the general work of interoperability of WG-A.

# Questions?

Chinese Academy of Science  
National Time Service Center

Prf. Lu Xiaochun

[Luxc@ntsc.ac.cn](mailto:Luxc@ntsc.ac.cn)