



# **EUREF's Infrastructure Galileo Ready**

*International Association of Geodesy Reference Frame  
Sub-Commission for Europe*

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*And EUREF TWG Members*

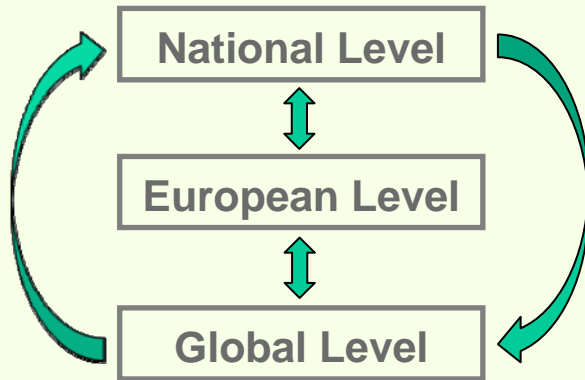
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Hosted by the Government of the People's Republic of China  
Beijing, China  
4 – 9 November 2012**



# EPN - EUREF Infrastructure

## EPN Regional Densification in Europe: Provide reference system data and information in ITRS and ETRS89 to European users by GNSS technologies



GNSS Permanent Network (EPN) with 250 stations

- 130 EPN stations are part of ITRF2008
- About 150 stations provides RT and GLONASS data ⇒ 40 Galileo
- Station movements monitored

HOME ROB  
GNSS Research Group  
EUREF

**EUREF Permanent Network**

ORGANISATION	TRACKING NETWORK	DATA & PRODUCTS	NEWS & MAILS	FTP & WEB ACCESS
Creation, Management, Structure, Relation to IGS, Projects, Guidelines, FAQ	Site maps, Site list, Proposed sites, Equipment & calibration, Site coordinates, Site log submission, Site picture submission	Data access, Analysis centres, Products, Time series, ETRS89/ITRS transformation, Formats	News, Mails, Calendar, Papers, Workshops, Web site history	Anonymous FTP, Web site index, Related links

[DATA & PRODUCTS](#) > **TRACKING STATUS**

Details on the GNSS signals included in the daily RINEX v2.11 data files available from the EPN data centres are given below. The GPS L1 signal is mandatory included in all GNSS data files and cannot be de-activated. When GLONASS is selected, the GLONASS L1 signal is also considered as mandatory (and cannot be de-activated).

Status on 2012-04-23

Locate site on map

**Tracking criteria selection**

GPS

using the signals:

code:  C1  C2  C5  P1  P2  P5

phase:  L1  L2  L5

not using the signals:

code:  C1  C2  C5  P1  P2  P5

phase:  L1  L2  L5

GLONASS

using the signals:

code:  C1  C2  P1  P2

phase:  L1  L2

not using the signals:

code:  C1  C2  P1  P2

phase:  L1  L2



## Directions of GNSS Satellite Deployment

**New navigation satellite constellations and signals,  
building the “System of Systems”**

- **Current GNSS satellite constellation**
  - 31 GPS operational
  - 24 GLONASS operational
  - 2 Giove and 4 IOV Galileo operational
  - 1 QZSS (tracked by geodetic receiver)
  - 11 COMPASS (tracked by geodetic receiver)
- **Frequencies**
  - GPS: L1, L2, L5
  - GLONASS: L1, L2
  - Galileo: E1, E5a, E5b, E5
  - QZSS: L1, L2, L5, LEX(6)
  - Compass: E2, E5b, E6
- **Tracking Mode (C/A, P, L1C, L2C, I, Q, X=I+Q, ...)**



## Outline - Evolution of the GNSS Landscape

- I. The IGS Multi-GNSS Experiment (M-GEX) and EUREF in practice***
- II. EUREF's Infrastructure Galileo Ready***
- III. Reference Frames in Real-Time with PPP-RTK***
- IV. EUREF: How to proceed?***



# I. The IGS Multi-GNSS Experiment (M-GEX) - MULTI-GNSS Activities in EUREF

EUREF Symposium 2010 in Gävle recommended:



## Resolution no. 3

The IAG Reference Frame Sub-commission for Europe (EUREF)

*Noting* the leading role that EUREF has taken using and developing the use of GNSS together with the advantages that such leadership has given Science, IAG, EU and NMCAs;

*Recognising* the GNSS modernisation programmes in particular the European Galileo;

*Encourages* members of EUREF to provide the necessary infrastructure, data and analysis from these new GNSS developments:

*Requests* the TWG to establish a platform for the exchange of experiences in upgrading the EPN.



## MULTI-GNSS Working Group EUREF

### Topics:

- Handling RINEX3.xx and/or RINEX2.xx and compatibility to RTCM 'High Precision Multiple Signal Messages' (HP MSM) and procedure to implement it to the EPN
- Enhancing the EPN infrastructure by Multi-GNSS-ready receivers and antennas
- Enhancement method: double stations versus replacing existing analysis of GLONASS data (till now, only the minority of the EUREF analysis centers provide GPS-GLONASS products)
- Developing of software (post-processing and real-time) capable to handle multi-GNSS signals.
- Define the optimal procedure to have PCV calibrations available which are consistent between the GNSS systems
- Setting up a time schedule in order to plan the operational switch to RINEX3 which also is in line with IGS.



# A Data Center for the IGS Multi-GNSS Experiment (M-GEX)

**GDC**  
GNSS DATA CENTER

User:   
Password:

Home About Us Data & Products NTRIP Links    Help Project Filter: MGEX

Data & Products > Project Information > Project Maps

## Project Map: MGEX

Map showing station locations for the MGEX project across various continents, including North America, Europe, Africa, Asia, and Australia. The map includes a navigation interface with 'Karte', 'Satellit', and 'Gelände' tabs, a scale bar (2000 Meile/km), and a 'powered by Google' logo.

Kartendaten ©2012 MapLink, Tele Atlas - Nutzungsbedingungen

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## II. EUREF's Infrastructure Galileo Ready

*GNSS Permanent Network (EPN) with 250 stations*

- About 150 stations provides Real Time and GLONASS data

- ⇒ 40 Galileo stations

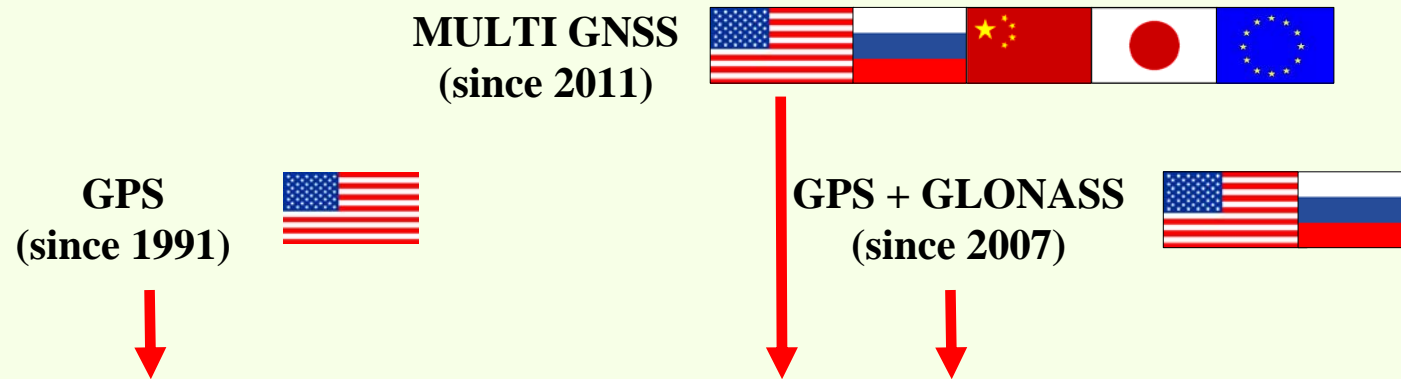




# Double / Triple Station Concept

## Example Zimmerwald (swisstopo, Uni Bern)

Usefull for stations with long time series





## RINEX3 data availability

- **Status October 2012**
  - BKG-EUREF: 18 sites (alac alba axpv bbys cant dyng eglt guip ildx m0se rio1 scoa smne tlmf usal vale ven1 vfch)
  - BKG-IGS: 26 sites (brst brux conz ganp harb hofn lhaz Immf mars mat1 mate nklg nurk ous2 pots reun reyk sass tash tlse ulab warn wind wtzr wtzz zim2)
- **BKG:**
  - Identical upload directory + automatic recognition which RINEX version is submitted
  - Archive under:
    - RINEX3: [ftp://igs.bkg.bund.de/IGS/obs\\_v3/yyyy/ddd](ftp://igs.bkg.bund.de/IGS/obs_v3/yyyy/ddd)
    - RINEX2.11 <ftp://igs.bkg.bund.de/IGS/obs/yyyy/ddd>
- **CDDIS:**
  - Send RINEX2.11 and RINEX3 files to different upload directories
  - Archive under:  
<ftp://cddis.gsfc.nasa.gov/pub/gps/data/rinex3test/daily>



## **III. Reference Frames in Real-Time with PPP-RTK**

### **Why is EUREF Involved in Real-Time GNSS?**

**Support research organizations, universities, national mapping and cadastral agencies:**

- **GNSS performance monitoring**
- **Providing precise positioning data and information**
- **Rapidly detecting, locating, and characterizing hazardous events such as earthquakes and tsunamis**
- **Geophysical hazard detection and warning systems**
- **Space weather forecasting**



## IGS Real-time GNSS Service

- **Real-time IGS Working Group since 2001**
- **Real-time Pilot Project since 2007**
- **Analysis Centers:**  
**BKG, CNES, CTU, DLR, ESA, Geo++, GMV, GZF, NRCan, Wuhan**
- **IGS permanent RT service announced**



## Further RTCM Standardization for PPP

- **Will add messages for global ionosphere and phase biases to allow Ambiguity Resolution**
- **Will add troposphere info to allow PPP-RTK through Regional Augmentations**
- **Approach requires access to a net like EUREF's EPN**
- **Approach requires dense CORS networks from National Mapping Agencies**



## Reference Frames in Real-Time

- Local RTK networks
  - better realisation of ETRS89 in all countries
  - long term maintenance of ETRS89 also in tectonically affected areas
  - a few cm accuracy within a few observation epochs
  - local reference stations and reference frames realization
  - no activity from EUREF in this domain
- PPP-RTK
  - PPP is global approach
  - provide and apply precise SSR information
  - concept doesn't request local reference stations
  - global reference frame realization; if needed transformed to regional or local reference frames
- Added value: basic input for science and safety (e.g., tectonic risk assessment)



# EUREF Real-Time Data Streams

**Legend**

Active      Inactive      Corrupt

**Site selection on map**

- Select a station -

**Site criteria selection**

**Receiver type:**  
AOA  
ASHTech  
JAVAD  
JPS

**Format:**  
RTCM 2.1  
RTCM 2.2  
RTCM 2.3  
RTCM 3.0

**System:**  
GPS  
GLO  
GAL  
SBAS

hold down CTRL for multiple selection

**Active:**  Yes  No  All

**Corrupt:**  Yes  No  All

**Last update :** May 7, 2012 09:24 UTC

Karte    Satellit

Google | 1000 km | 500 Meilen | Kartendaten ©2012 Google, INEGI, MapLink, Tele Atlas - Nutzungsbedingungen



# EUREF Real-Time Product Streams

Message	Contents
1057	GPS orbit corrections to Broadcast Ephemeris
1058	GPS clock corrections to Broadcast Ephemeris
1059	GPS code biases
1060	Combined orbit and clock corrections to GPS Broadcast Ephemeris
1061	GPS User Range Accuracy
1062	High-rate GPS clock corrections to Broadcast Ephemeris
1063	GLONASS orbit corrections to Broadcast Ephemeris
1064	GLONASS clock corrections to Broadcast Ephemeris
1065	GLONASS code biases
1066	Combined orbit and clock corrections to GLONASS Broadcast Ephemeris
1067	GLONASS User Range Accuracy

Caster IP:Port	Mountpoint & Input Streams	Ref. Point	GNSS	Messages	Orbits	Reference System	Analysis Center & SW	Register for access
<a href="http://www.euref-ip.net:2101">www.euref-ip.net:2101</a>	EUREF01	APC	GPS	1059, 1060	IGS Ultra Rapid	ETRF2000	KF Combination BNC	<a href="#">Registration</a>
<a href="http://www.euref-ip.net:2101">www.euref-ip.net:2101</a>	EUREF02	APC	GPS GLO	1057,1058,1059 1063,1064,1065	CODE Ultra Rapid	ETRF2000	KF Combination BNC	<a href="#">Registration</a>

## Helmert Transformation Parameters for Transformation to Regional Systems

Regional System	Tx, Ty, Tz (m)	dTx, dTy, dTz (m/y)	Rx, Ry, Rz (mas)	dRx, dRy, dRz (mas/y)	S (10 <sup>**</sup> -9) dS (10 <sup>**</sup> -9/y)	T0 for Rates
ETRF2000	0.0541 0.0502 -0.0538	-0.0002 0.0001 -0.0018	0.891 5.390 -8.712	0.081 0.490 -0.792	0.40 0.08	2000.0



## PPP-RTK & Open Standards



- **Symposium, March 2012 BKG Frankfurt, 190 participants, 34 countries**
- **RT Workshop at the SIRGAS Symposium, Oct. 2012, Concepcion, Chile, 20 countries**



## IV. EUREF: How to proceed? Summary

- **EUREF supports all satellite navigation systems**
  - data archive extended by RINEX version 3
  - GLONASS recommended in analysis guidelines
  - website at EPN central bureau ready for multi-GNSS
- **EUREF established real-time services**
  - data and product streams
  - permanent PPP monitoring
  - development of tools, e.g., BNC
- **EUREF organizations take part in Galileo developments**
  - Galileo reference frame
  - Galileo geodetic working group



## **EUREF: How to proceed?**

- **EPN stations shall be configured, where possible, with Galileo and GPS L5 signals ready receivers**
- **Regional and local densification of RT infrastructure testing of real-time precise point positioning (PPP) in the ETRS89 with recent available corrections in the RTCM standard for satellite orbits, clocks and biases**
- **Help in developing Open Standard for PPP with Ambiguity Resolution and PPP with Regional Augmentation**
- **Setup/Maintain independent European continental PPP service resources in cooperation with NMAs**
- **Convince manufacturers to support RTCM SSM messages in receiver firmware**



## NMAs: How to proceed?

- **Today's Network RTK resources will not become obsolete, PPP-RTK just develops towards an alternative**
- **Pick up EUREF's PPP product for further dissemination through national Ntrip resources**
- **Test & validate EUREF's PPP in their countries, Open Source software available through BNC and RTKLIB**
- **Consider making use of EUREF's real-time product part of the national real-time product portfolio**

**EUREF prepare a Multi-GNSS-RT-Service**