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NASA Update: GNSS Space Service Volume Providers' Forum

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Benefits of GPS/GNSS to NASA



- <u>Real-time On-Board Navigation</u>: Precision formation flying, rendezvous & docking, station-keeping, Geosynchronous Orbit (GEO) satellite servicing
- <u>Earth Sciences</u>: GPS as a measurement for atmospheric and ionospheric sciences, geodesy, and geodynamics
- <u>Launch Vehicle Range Operations:</u> Automated launch vehicle flight termination; providing safety net during launch failures & enabling higher cadence launch facility use
- <u>Attitude Determination</u>: Some missions, such as the International Space Station (ISS) are equipped to use GPS/GNSS to meet their attitude determination requirements
- <u>Time Synchronization</u>: Support precise timetagging of science observations and synchronization of on-board clocks



GPS capabilities to support space users will be further improved by pursuing compatibility and interoperability with GNSS



The Promise of using GNSS for Real-Time Navigation in the Space Service Volume

Benefits of GNSS use in SSV:

- Significantly improves real-time navigation performance (from: km-class to: meter-class)
- Supports quick trajectory maneuver recovery (from: 5-10 hours to: minutes)
- GNSS timing reduces need for expensive on-board clocks (from: \$100sK-\$1M to: \$15K-\$50K)
- Supports increased satellite autonomy, lowering mission operations costs (savings up to \$500-750K/year)
- Enables new/enhanced capabilities and better performance for HEO and GEO missions, such as:



Earth Weather Prediction using Advanced Weather Satellites



Launch Vehicle Upper Stages and Beyond-GEO applications



Space Weather Observations



Formation Flying, Space Situational Awareness, Proximity Operations



Precise Relative Positioning



Precise Position Knowledge and Control at GEO



Current U.S. Missions using GPS above the GPS Constellation



GOES-R Weather Satellite Series:

- Next-generation U.S. operational GEO weather satellite series
- Series is first to use GPS for primary navigation
- GPS provides quicker maneuver recovery, enabling continual science operations with <2 hour outage per year
- Introduction of GPS and new imaging instrument are game-changers to humanity, delivering data products to substantially improve public and property safety

Magnetospheric Multi-Scale (MMS) Mission:

- Four spacecraft form a tetrahedron near apogee for magnetospheric science measurements (space weather)
- Highest-ever use of GPS; Phase I: 12 Earth Radii (RE) apogee; Phase 2: 25 RE apogee
- GPS enables onboard (autonomous) navigation and potentially autonomous station-keeping

Exploration Mission 1 (EM-1):

 First cis-lunar flight of NASA Space Launch System (SLS) with an Orion crew vehicle equipped with a Honeywell high-altitude GPS receiver as an experiment









U.S. Initiatives & Contributions to Develop & Grow an Interoperable GNSS SSV Capability for Space Users



Operational Users	Space Flight Experiments	
 MMS GOES-R, S, T, U EM-1 (Lunar en-route) Satellite Servicing 	 Falcon Gold EO-1 AO-40 GPS ACE EM-1 (Lunar vicinity) 	
Operational Use Demonstrates Future Need	Breakthroughs in Understanding; Supports Policy Changes; Enables Operational Missions	
SSV Receivers, Software & Algorithms	SSV Policy & Specifications	
 GEONS (SW) GSFC Navigator General Dynamics Navigator commercial variants (Moog, Honeywell) 	 SSV definition (GPS IIF) SSV specification (GPS III) ICG Multi-GNSS SSV common definitions & analyses 	
Develop & Nurture Robust GNSS Pipeline	Definition & Specification	

From 1990's to Today, U.S. Provides Leadership & Guidance Enabling Breakthrough, Game-changing Missions through use of GNSS in the SSV



Current GPS SSV Definition





The GPS SSV is defined by three interrelated performance metrics for the SSV Medium Altitudes and the SSV High/Geosynchronous altitudes:

- Availability
- Minimum received power
- Pseudorange accuracy



GOES-R Series Weather Satellites



- GOES-R, -S, -T, -U: 4th generation
 NOAA operational weather satellites
- GOES-R/GOES-16 Launch: 19 Nov 2016
- 15 year life, series operational through mid-2030s
- Employs GPS at GEO to meet stringent navigation requirements
- Relies on beyond-spec GPS sidelobe signals to increase SSV performance
- Collaboration with the USAF (GPS) and ICG (GNSS) expected to ensure similar or better SSV performance in the future
- NOAA also identifies EUMETSAT (EU) and Himawari (Japan) weather satellites as reliant on increased GNSS signal availability in the SSV



GOES-16 Image of Hurricane Maria Making Landfall over Puerto Rico



GOES-R/GOES-16 In-Flight Performance



GPS Visibility

- Minimum SVs visible: 7
- DOP: 5–15
- Major improvement over guaranteed performance spec

(4+ SVs visible 1% of time)

Navigation Performance

- 3σ position difference from smoothed ground solution (~3m variance):
 - Radial: 14.1 m
 - In-track: 7.4 m
 - Cross-track: 5.1 m
- Compare to requirement: (100, 75, 75) m

Source: Winkler, S., Ramsey, G., Frey, C., Chapel, J., Chu, D., Freesland, D., Krimchansky, A., and Concha, M., "GPS Receiver On-Orbit Performance for the GOES-R Spacecraft," ESA GNC 2017, 29 May-2 Jun 2017, Salzburg, Austria.





NASA's Magnetospheric MultiScale (MMS) Mission



- Discover the fundamental plasma physics process of reconnection in the Earth's magnetosphere.
- Coordinated measurements from tetrahedral formation of four spacecraft with scale sizes from 400km to 10km
- Flying in two highly elliptic orbits in two mission phases
 - Phase 1 1.2x12 R_E (magnetopause) Mar '14-Feb '17
 - Phase 2B 1.2x25 R_E (magnetotail) May '17-present







Using GPS above the GPS Constellation: NASA GSFC MMS Mission



Magnetospheric Multi-Scale (MMS)

- Launched March 12, 2015
- Four spacecraft form a tetrahedron near apogee for performing magnetospheric science measurements (space weather)
- Four spacecraft in highly eccentric orbits
 - Phase 1: 1.2 x 12 Earth Radii (Re) Orbit (7,600 km x 76,000 km)
 - Phase 2: Extends apogee to 25 Re
 (~150,000 km) (40% of way to Moon!)

MMS Navigator System

- GPS enables onboard (autonomous) navigation and near autonomous station-keeping
- MMS Navigator system exceeds all expectations
- At the highest point of the MMS orbit Navigator set Guiness world record for the highest-ever reception of signals and onboard navigation solutions by an operational GPS receiver in space
- At the lowest point of the MMS orbit Navigator set Guiness world for fastest operational GPS receiver in space, at velocities over 35,000 km/h







Signal Tracking Performance During Phase 1 to Phase 2 Apogee Raising (70K km to 150K km)





Signal Tracking Performance Single Phase 2B Orbit (150K km Apogee)



Note: Actual performance is orbit sensitive







- Oct 13: Joint NASA-USAF Memorandum of Understanding signed on civil Space Service Volume (SSV) Requirements
 - Scope is relevant to future GPS-III SV11+ (GPS IIIF) block build
 - As US civil space representative, provides NASA insight into procurement, design and production of new satellites from an SSV capability perspective
 - Intent to ensure SSV signal continuity for future space users, such as GOES S-U



IOAG-ICG Collaboration: Space User Database



- ICG-11 recommendation encourages providers, agencies, and research organizations to publish details of GNSS space users to contribute to IOAG database.
- IOAG database of GNSS space users updated on November 14, 2017 (IOAG-21)
- Please encourage your service providers, space agencies and research institutions to contribute to the GNSS space user database via your IOAG liaison or via WG-B.

Number of Missions / Programs by Agency

ASI	Agenzia Spaziale Italiana	4
CNES	Centre national d'études spatiales	10
CSA	Canadian Space Agency	5
DLR	German Aerospace Center	12
ESA	European Space Agency	17
JAXA	Japan Aerospace Exploration Agency	12
NASA	National Aeronautics and Space Administration	38



GNSS SSV Observations and Forward Priorities



Observations:

- The International Committee on GNSS (ICG) WG-B is establishing an interoperable GNSS SSV through pre-work, analyses and meetings
- Analyses are underway to solidify our understanding of an SSV that combines the capabilities of all GNSS and regional navigation systems
- Despite this, SSV users should not rely on unspecified capabilities from any particular GNSS
 - SSV capabilities that are currently available <u>may not</u> be available in the future unless they are documented in specifications for that GNSS

Forward Priorities:

GNSS service providers, supported by space agencies & research institutions encouraged to:

- Support SSV in future generation of satellites, preferably through the baseline of SSV specifications
- Measure and publish GNSS antenna gain patterns to support SSV understanding & use of the GNSS aggregate signal
- Share SSV user experiences and lessons learned to improve SSV responsiveness to emerging needs



Conclusions



- The SSV, first defined for GPS Block IIF, continues to evolve to meet user needs. GPS has led the way with a formal specification for GPS Block III, requiring that GPS provides a core capability to space users
- Current and future space missions in the SSV are **becoming increasing reliant** on nearcontinuous GNSS availability to improve their mission performance
- Today, we **continue to work** to ensure that the SSV keeps pace with user demands:
 - For GPS, we are working with the Air Force to understand how future GPS block builds will continue to support the needs of emerging GPS-only users like the Geostationary Operational Environmental Satellite - R Series (GOES-R)
 - In partnership with foreign GNSS providers, we are working to characterize, analyze, document, and publish the capabilities of an interoperable multi-GNSS SSV with ultimate goal of provider specification
- Both approaches are equally critical: (1) a robust GPS capability enables and enhances new missions in applications that only rely on GPS signals; while (2) an interoperable GNSS SSV improves on-board PNT resilience and ensures that wider capabilities are available as needed
- NASA and the U.S. Government are proud to work with the GNSS providers to contribute making GNSS services more accessible, interoperable, robust, and precise for all users, for the benefit of humanity. We encourage all providers to continue to support this essential capability.