

Review of the IGS (GNSS) Contribution to the ITRF

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Presenter Chris Rizos

ITRF2014: Input data

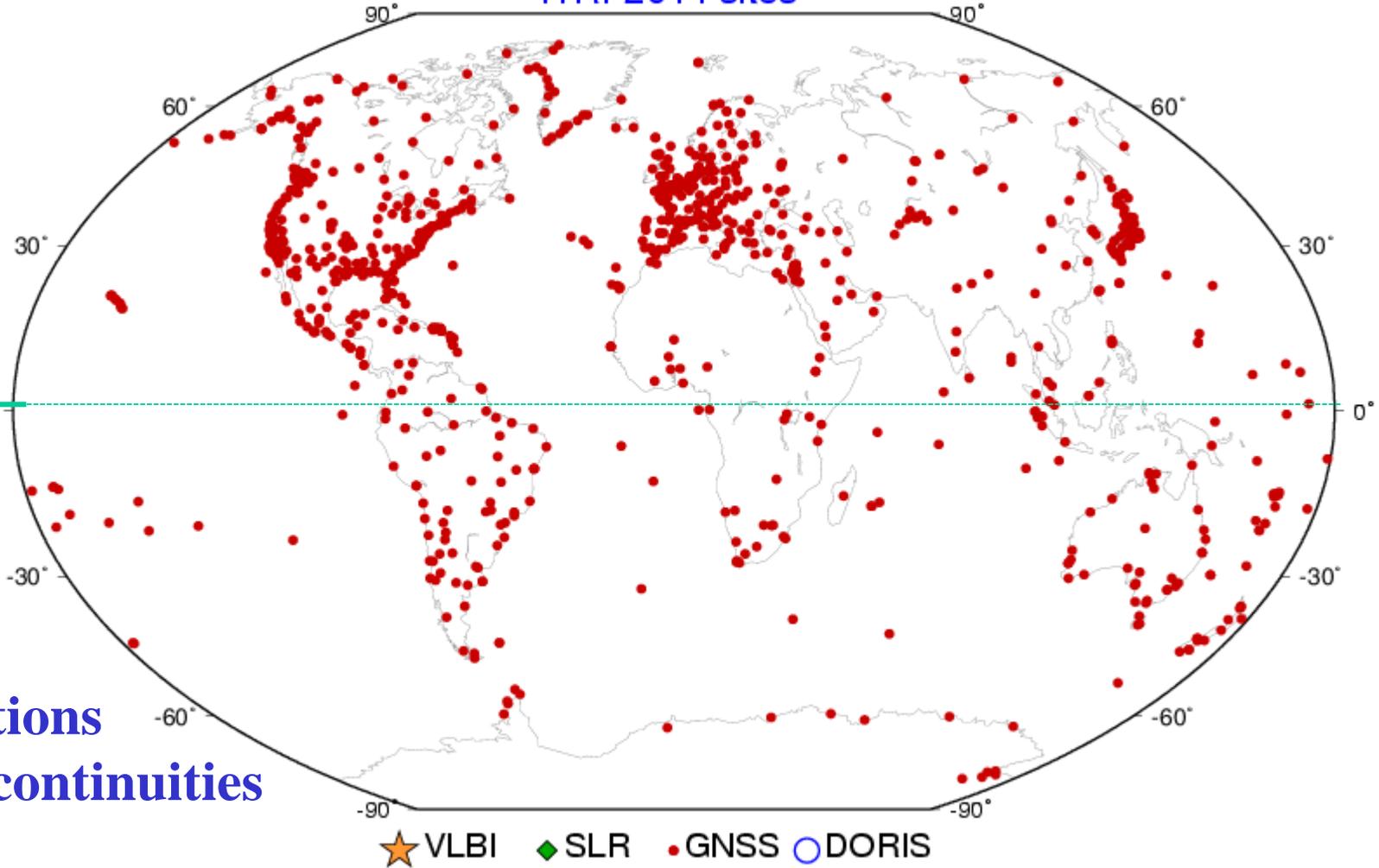
Service/Technique	Number of Solutions	Time span	# of sites
IGS/GNSS/GPS	7714 daily	1994.0 – 2015.1 (21yrs)	884
IVS/VLBI	5328 daily	1980.0 – 2015.0 (35yrs)	124
ILRS/SLR	244 fortnightly	1980.0 – 1993.0	96
	1147 weekly	1993.0 – 2015.0 (35yrs)	
IDS/DORIS	1140 weekly	1993.0 – 2015.0 (22yrs)	71

ITRF2014: GNSS

ITRF2014 sites

Site #
696
188

884 sites
1054 stations
1882 discontinuities

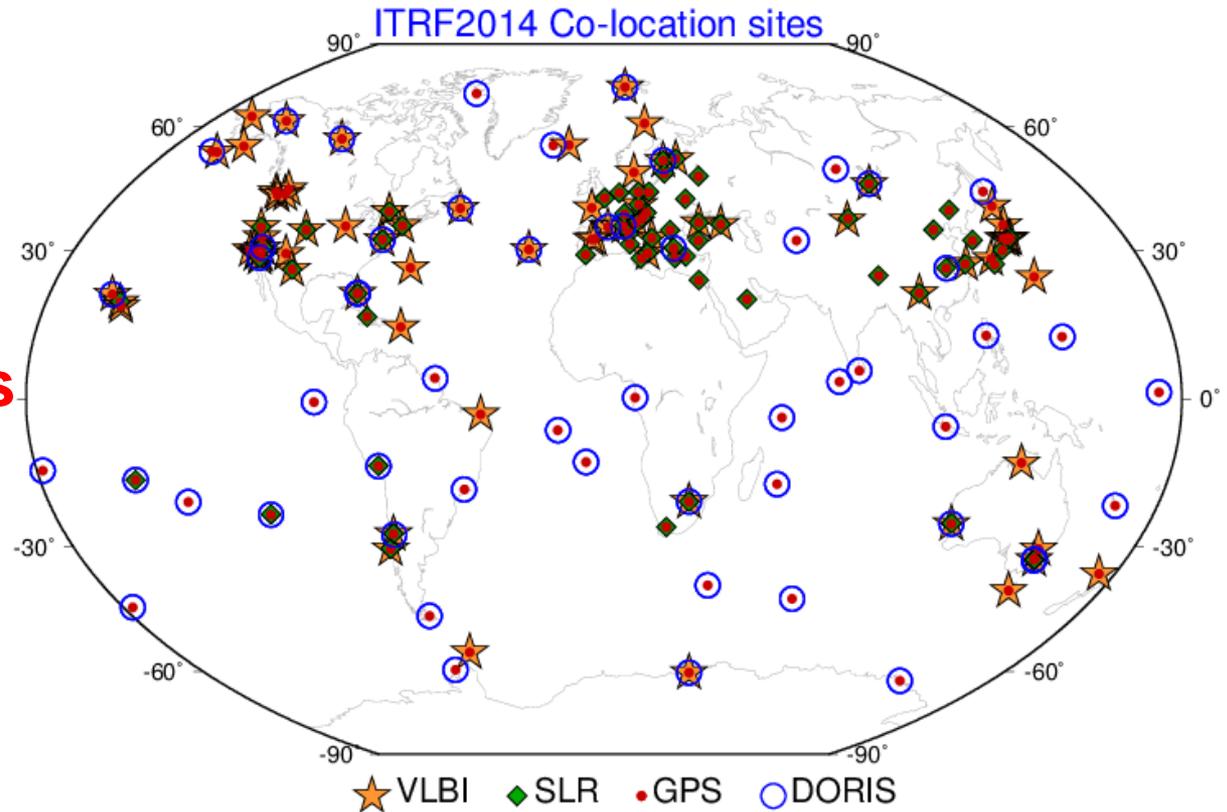


ITRF2014 colocation sites

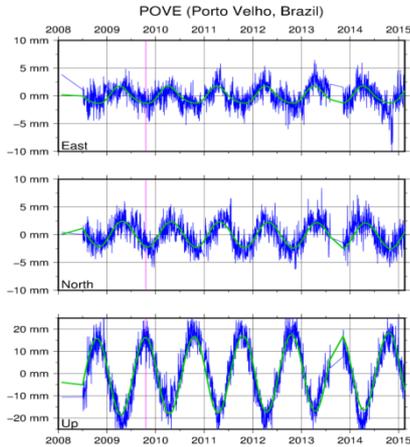
- SLR-VLBI : 11
- SLR-DORIS: 11
- VLBI-DORIS: 12

of local tie vectors
between GNSS &:

- DORIS: 103
- SLR : 56
- VLBI: 62
- Total: 221

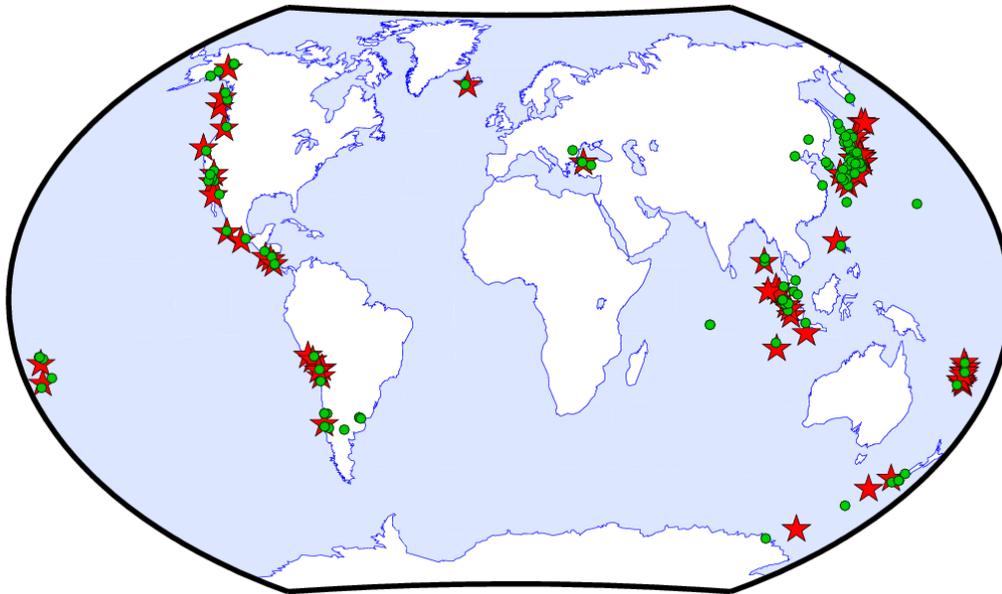
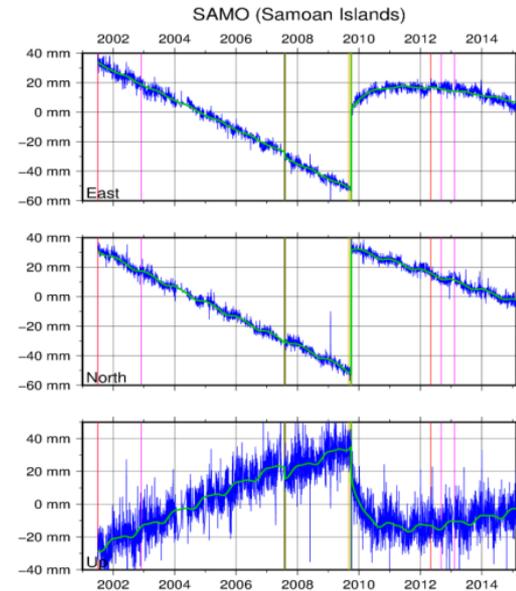


Modelling nonlinear station motions



- Position time series of all stations exhibit periodic signals

- More than 100 sites are subject to Post-Seismic Deformation due to major earthquakes



Red Stars: EQ Epicenters (58)

Green circles: ITRF2014 sites (117)

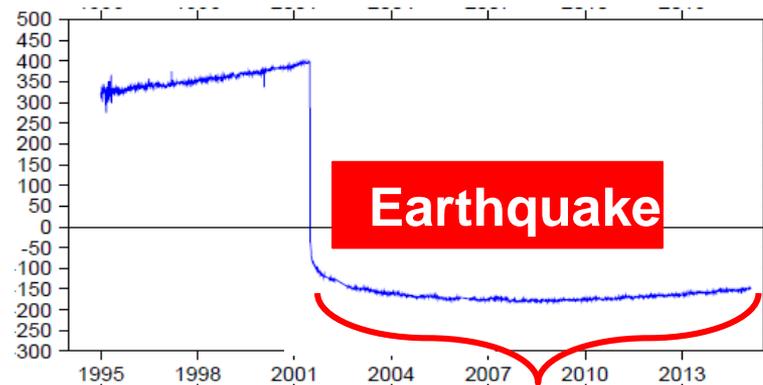
Precisely modelling the above leads to more robust secular frame and site velocities.

Post-Seismic Deformations

- Fitting parametric models using GNSS/GPS data
 - at major GNSS/GPS Earthquake sites
 - apply these models to the 3 other techniques at colocation EQ sites

- Parametric models:

- Logarithmic
- Exponential
- Log + Exp
- Two Exp

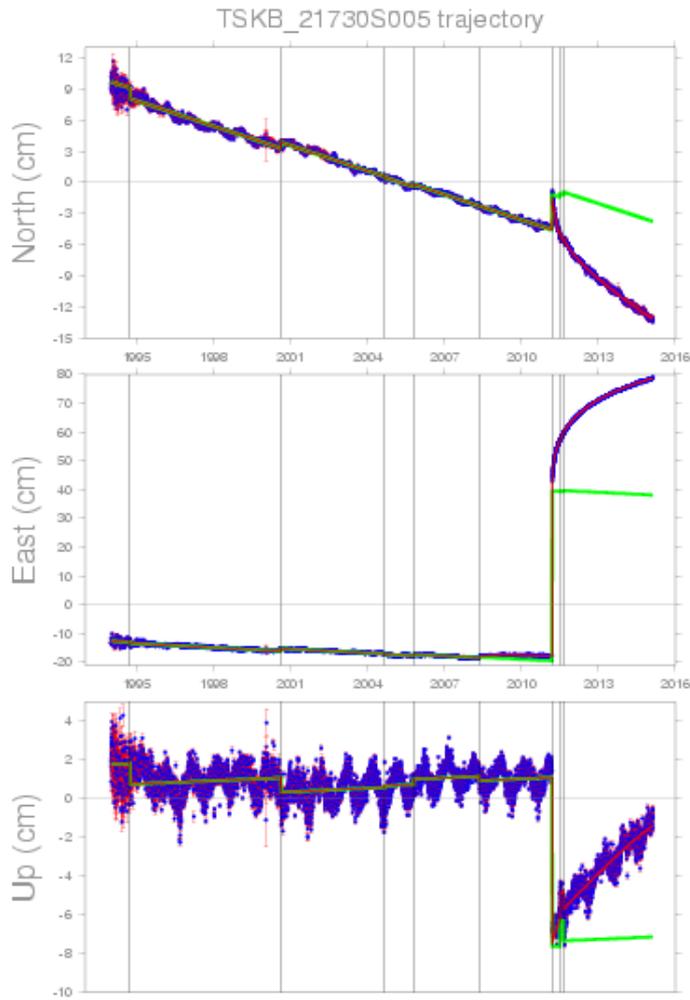


Post-seismic deformation

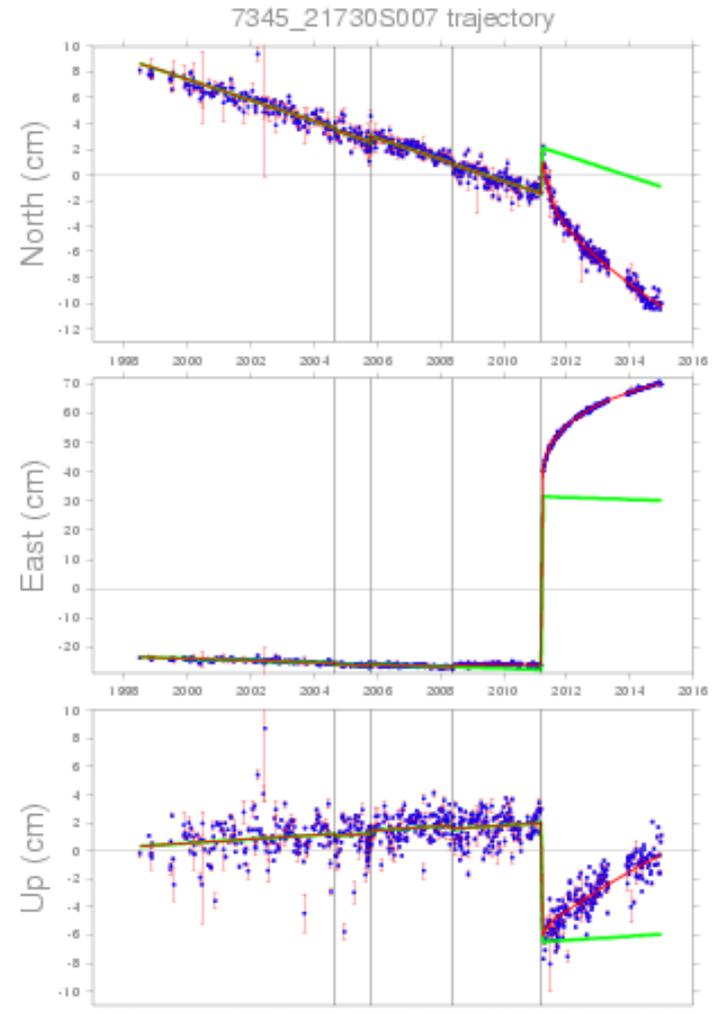
Tsukuba Trajectory

GNSS

VLBI



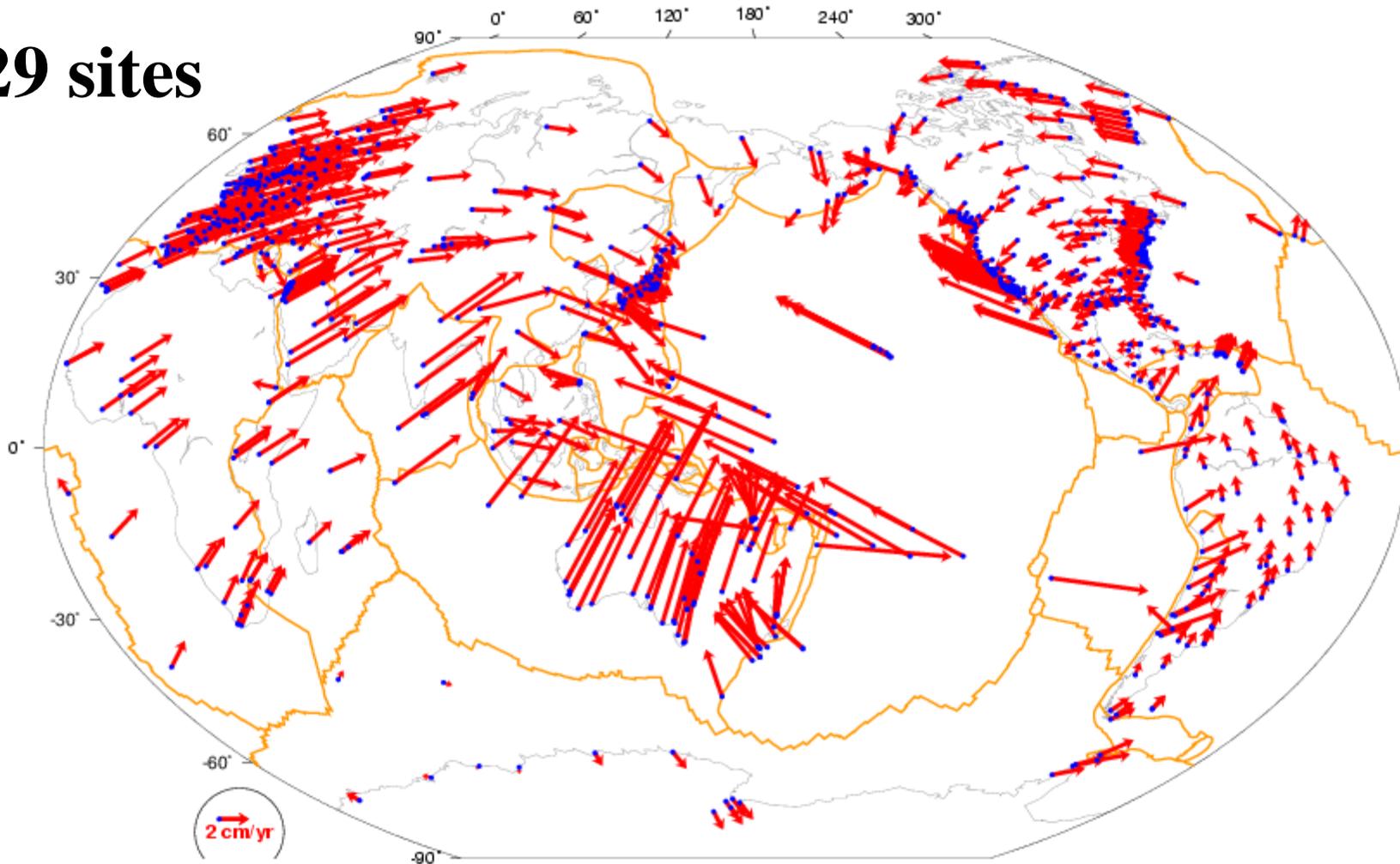
Trajectory : Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities



Trajectory : Blue: Raw, Green: Linear, Red: PSD model
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ITRF2014: Horizontal velocity field

829 sites

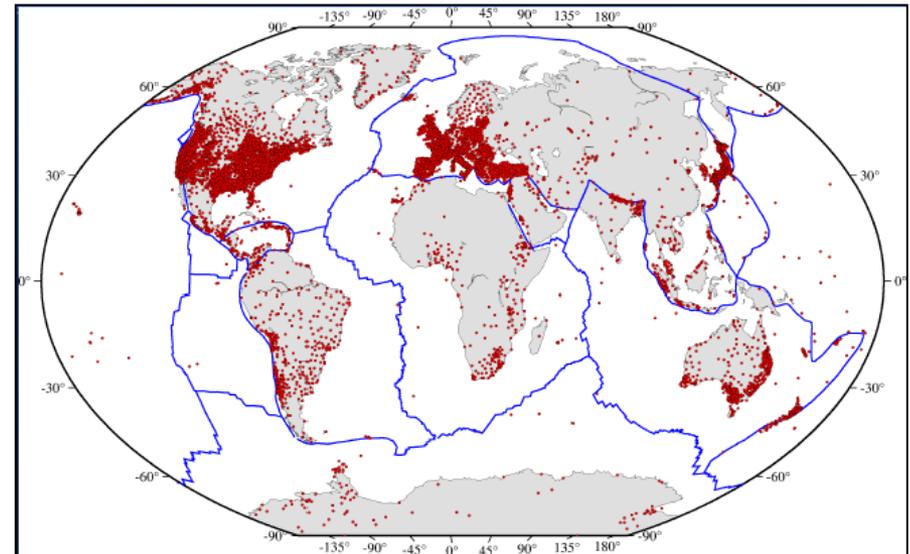


ITRF access & densification through IGS Products

Some facts

- GNSS exponential data explosion
- Local, National & Regional GNSS networks
- Using IGS Products provides universal access to, and densification of, the ITRF

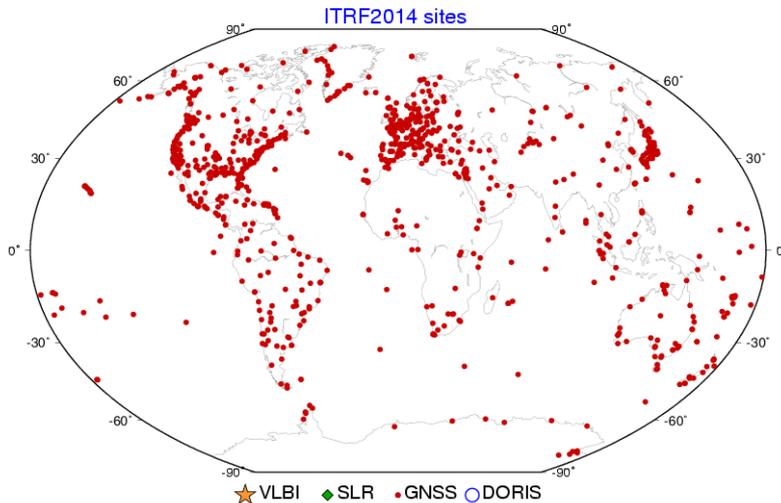
13,400 stations processed by NGL (Blewitt et al., 2015)



ITRF2014:

- 884 GNSS Sites
- Facilitates the alignment of the GNSS-based frames to the ITRF

More than 80% of National RFs are aligned to the ITRF (source: UN-GGIM GGRF questionnaire)



Concluding Remarks

The fundamental contribution of the IGS/GNSS is to:

1. Reinforce the ITRF frame definition (origin, scale & orientation)
2. Determine ITRF2014 Post-Seismic Deformation Models
3. Determine ITRF2014 Plate Motion Model
4. Determine ITRF Polar Motion
5. Allow ITRF Access & Densification