



# GNSS station absolute calibration for Galileo OS timing performances monitoring in the frame of GRC-MS

ICG-13 – 7th Nov 2018

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# OUTLINE

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  - ➤ **ABSOLUTE CALIBRATION AT CNES**
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- **CONTEXT**
  - **GRC-MS**
  - **RESULTS**
  - **SUMMARY**

## Context

Galileo System Time (**GST**) is

- the reference time for the Galileo system
- under responsibility of the Galileo Mission Segment (GMS)
- computed on the ground at the Galileo Control Centre in Fucino (Italy) using the atomic clocks located at the Precise Timing Facility
- steered to UTC
- fully described in the corresponding ICG timing template

## Context

- In order to better support timing applications based on UTC, the Galileo OS nav msg includes additional parameters that enable users to obtain a UTC realization by applying a correction to GST  
→ **UTC\_SiS**
- In order to insure interoperability between GPS and Galileo, their time difference, known as **GPGA** (or **GGTO**), is broadcast in the Galileo nav msg allowing users to benefit from a combined GPS/Galileo positioning
- GPGA can also be estimated by receivers if enough satellites are in view

# GRC and GRC-MS

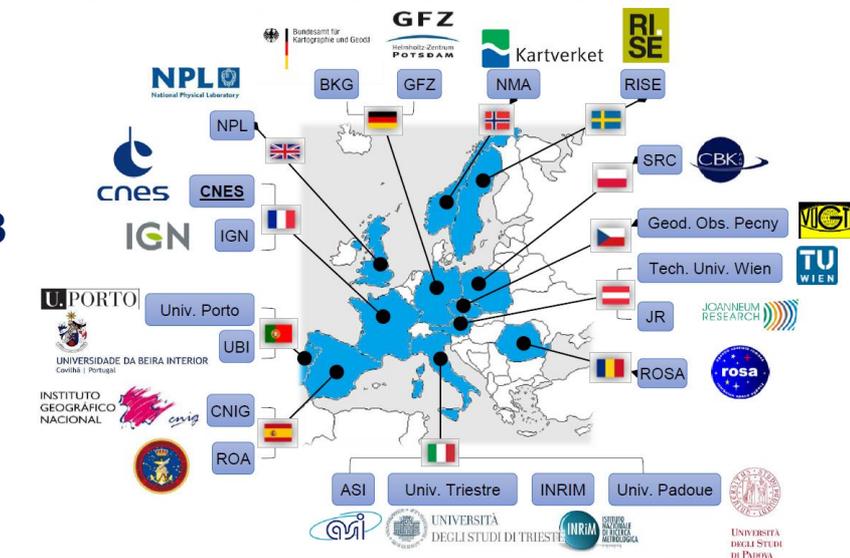


Main task of GRC is to provide the GSA with a means for independent monitoring and assessment of the quality of Galileo Services

The GRC consists of a core facility operated by the GSA and EU member state contributions (GRC-MS)

GRC-MS is a contribution to the Galileo Reference Center by EU member states and associated states :

- coordinator = CNES
- 20 partners from 12 countries
- Specific Grant #1 KO = 11<sup>th</sup> Sept 2018



## GRC-MS and timing

Dedicated Work Package on timing with CNES as coordinator and 4 partners (INRiM, NPL, ROA and RISE)



First quarter analysed is Q4 2018 ► no consortium results to show yet

CNES already monitors (since the Initial Services declaration) three Key Performance Indicators (KPI) :

- ✓ The offset between UTC and Galileo System Time :  $UTC - GST$
- ✓ the OS dual-frequency UTC dissemination accuracy :  $UTC - UTC_{SiS}$
- ✓ the GGTO accuracy

# METHODOLOGY

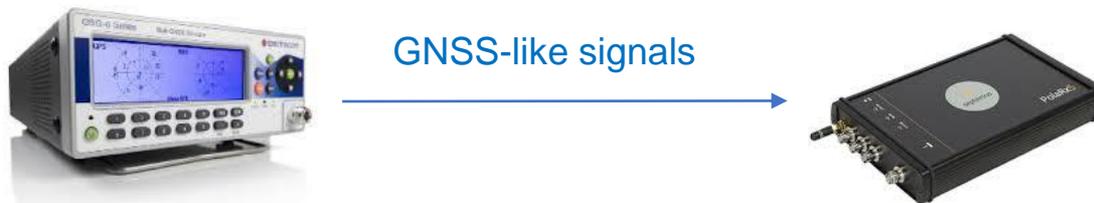


Positioning computation taking into account station delays

provides  
GNSS\_time – UTC(k)  
that can be compared to  
broadcast messages

>> this requires calibration of  
the station

# Absolute calibration of the receiver



Delay of the receiver = PR of the receiver – PR of the simulator

Corrected by :

- the simulator delay
- the delay of the cables
- the delay between the internal reference of the receiver and the external 1 pps

## Absolute calibration - results

Results for a Septentrio PolaRx4 TR PRO using 2 different simulators :

	Spirent 4760	Spectracom GSG-6
GPS P1	36.5 ns ( $\sigma = 0.5$ )	36.0 ns ( $\sigma = 0.5$ )
GPS P2	35.2 ns ( $\sigma = 0.5$ )	35.3 ns ( $\sigma = 0.9$ )
GPS C5	-	42.6 ns ( $\sigma = 0.4$ )
Galileo E1	-	36.1 ns ( $\sigma = 0.4$ )
Galileo E5a	-	43.0 ns ( $\sigma = 0.4$ )

Results agree within 0.5 ns for GPS P1 and P2

# Absolute calibration of a GPS/BeiDou chain (NIM)

Delay of the receiver



(ns)	RxD	AD
C1	-45.5 ( $\sigma = 0.6$ )	20.0 ( $\sigma = 0.6$ )
P1	-44.9 ( $\sigma = 0.4$ )	20.7 ( $\sigma = 0.5$ )
P2	-49.6 ( $\sigma = 0.9$ )	14.8 ( $\sigma = 0.3$ )
B1	-45.8 ( $\sigma = 0.9$ )	22.4 ( $\sigma = 0.7$ )
B2	-40.4 ( $\sigma = 0.6$ )	14.6 ( $\sigma = 0.7$ )

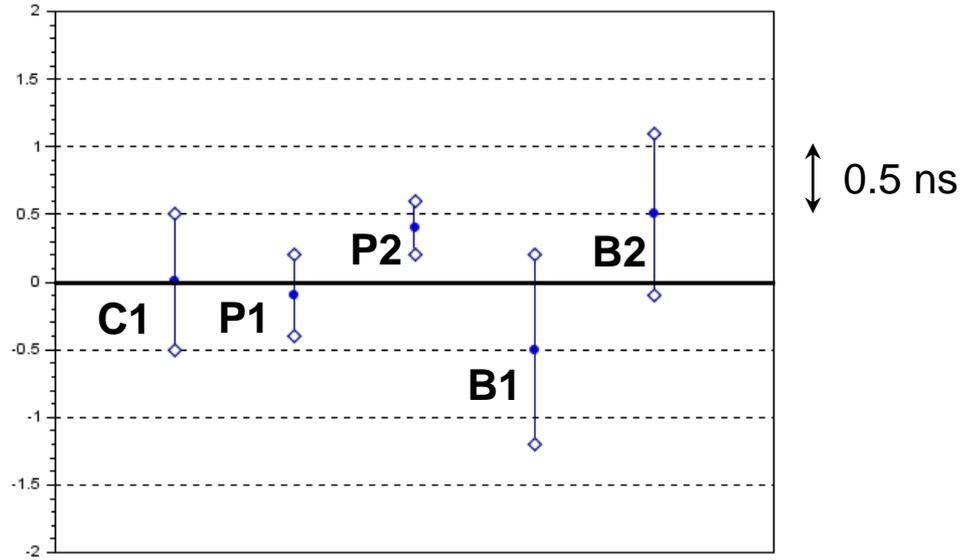
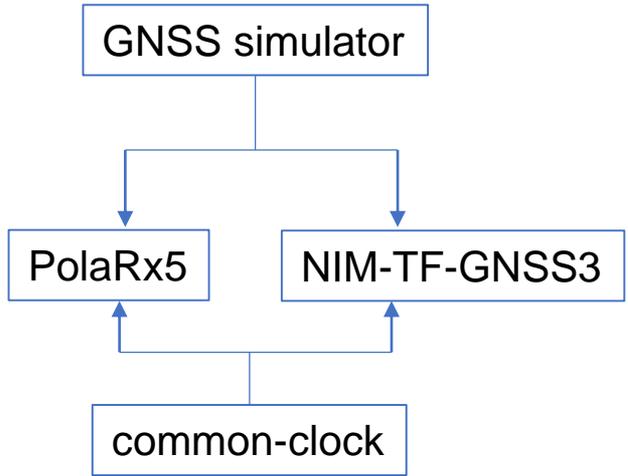
Delay of the antenna




Receiver NIMTFGNSS-3  
Antenna HARXON CSX 601A

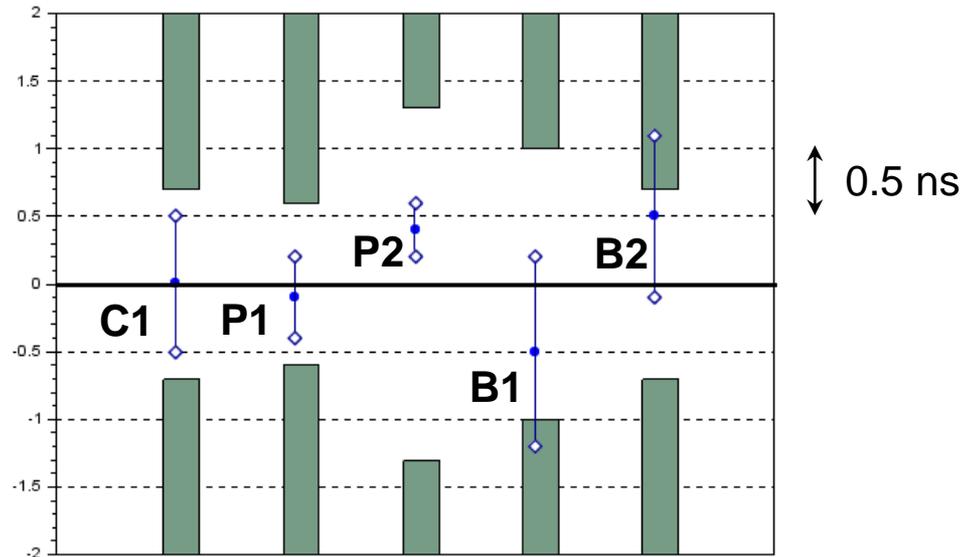
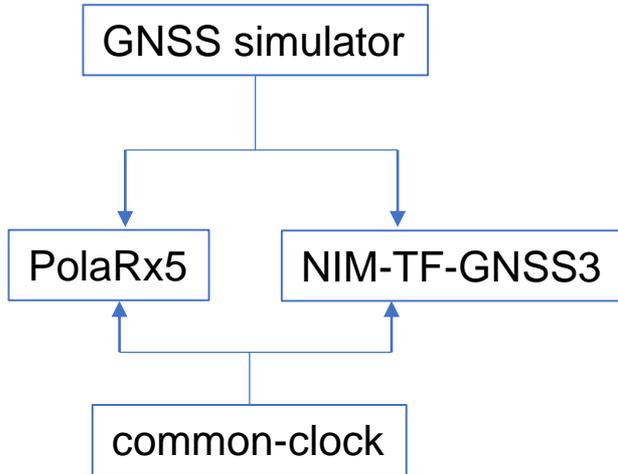
# Absolute calibration of a GPS/BeiDou chain (NIM)

## Validation of the delay of the receivers in CV using a simulator



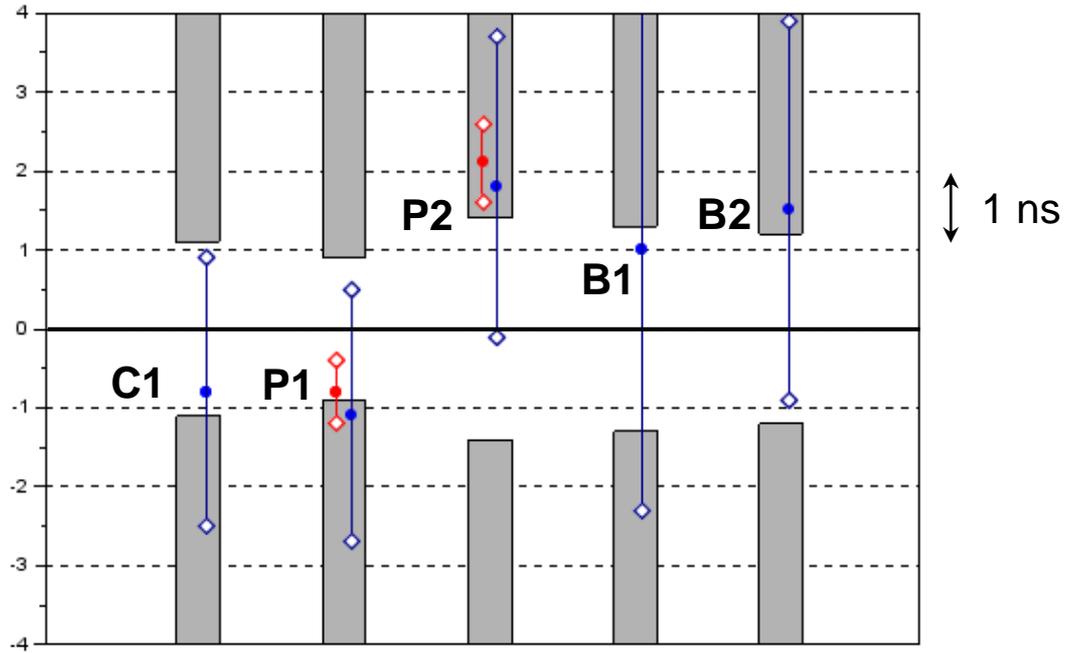
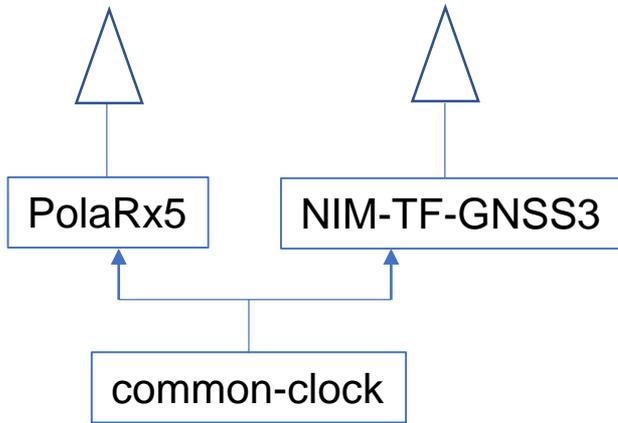
# Absolute calibration of a GPS/BeiDou chain (NIM)

## Validation of the delay of the receivers in CV using a simulator



# Absolute calibration of a GPS/BeiDou chain (NIM)

Overall validation in CV (CGGTTS and RINEX) using real signals



## Means and tools

- **Software**

- R2CGGTTS : ORB software that provides clock solutions for GNSS time transfer in the CGGTTS format
- Alternative Software for RINEX to CGGTTS conversion will be used (SPRING, ROA, RISE-GNSS)

- **Stations**

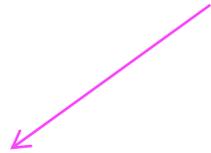
- CNES : absolute calibration for GPS P1, P2 and Galileo E1, E5a (since 7<sup>th</sup> June 2017) [1]
- INRiM, NPL, ROA and RISE :
  - GPS P1, P2 : relative calibration vs. their reference station
  - Galileo E1 considered as equal to GPS P1 [1]
  - Galileo E5a : calibrated using the original technique developed by ORB [2]

[1] « Progress on absolute calibrations of GNSS reception chains at CNES », J. Delporte et al. , Proc. of IFCS 2016

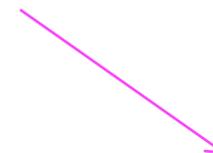
[2] « Advances on the use of Galileo signals in time metrology: calibrated time transfer and estimation of UTC and GGTO using a combined commercial GPS-Galileo receiver », P. Defraigne et al., Proc. of PTTI 2013

# KPI#1 : UTC-GST offset

$$\text{UTC} - \text{GST} = (\text{UTC} - \text{UTC}(k)) + (\text{UTC}(k) - \text{GST})$$



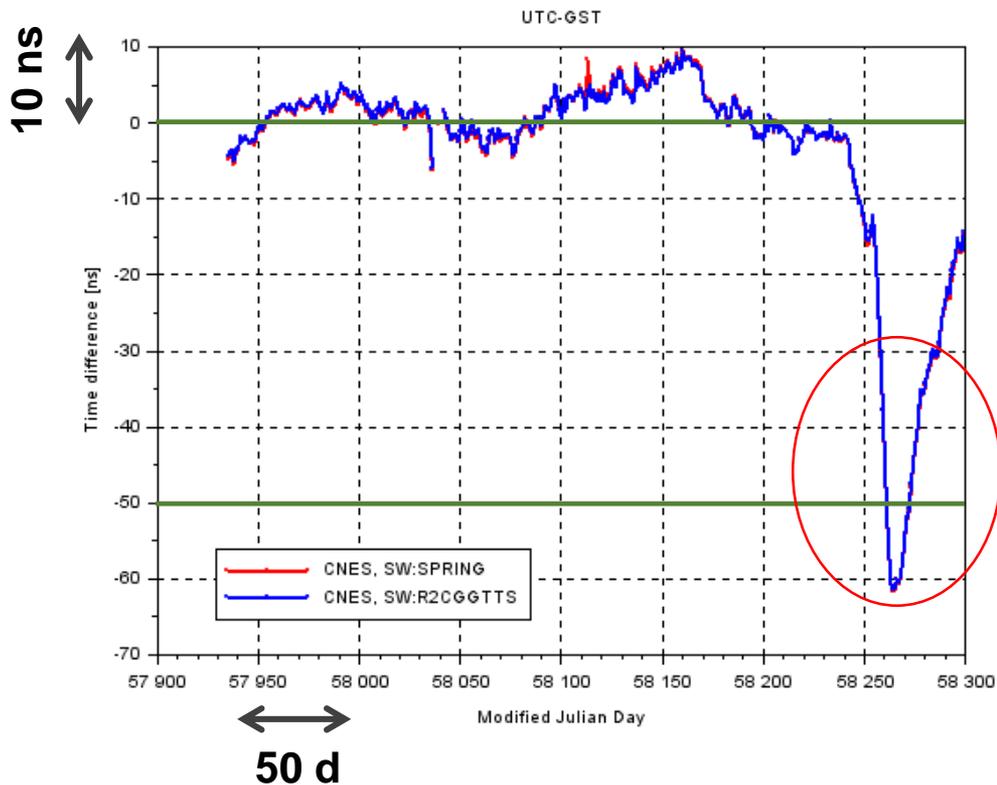
from BIPM circular T  
(daily values obtained by  
interpolation)



computed at 00:00:00  
(by linear regression)  
using SPRING and  
R2CGGTTS software

# KPI#1 : UTC-GST offset

## CNES station (June 2017 to June 2018)



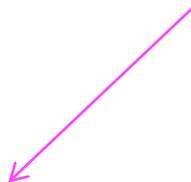
Mean : -3.8 ns  
Std : 14.0 ns  
95% : 37.5 ns

Behavior accurately reflected  
in the UTC-GST brdc info

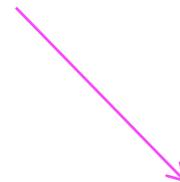
- ▶ no impact to users  
(see next slides)

## KPI#2 : UTC - UTC\_SiS offset

$$\text{UTC} - \text{UTC\_SiS} = (\text{UTC} - \text{GST}) - (\text{UTC\_SiS} - \text{GST})$$



computed as previously  
explained

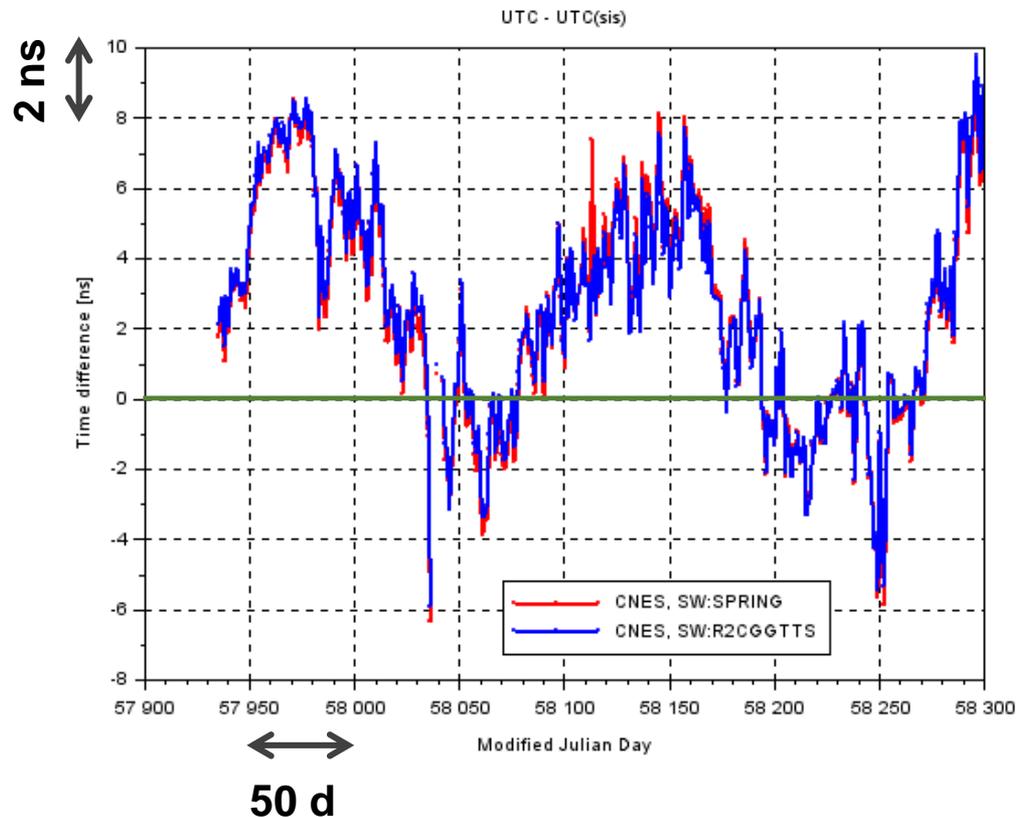


from GAUT broadcast values in the  
Galileo RINEX nav file

# KPI#2 : UTC - UTC\_Sis offset

## CNES station (June 2017 to June 2018)

**Initial Services Requirement  
< 30 ns, 95 % over all age of  
data, normalised annually**



Mean : 2.5 ns  
Std : 3.1 ns  
95% : 7.7 ns

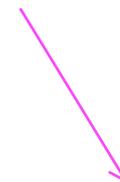
OK

## KPI#3 : GGTO accuracy

$$\text{GGTO accuracy} = \text{GGTO\_computed} - \text{GGTO\_SiS}$$



computed as :  
 $(\text{GST} - \text{UTC}(k)) - (\text{GPST} - \text{UTC}(k))$



from GPGA broadcast values in the  
RINEX nav file

## RINEX v3.04

### Up to v3.03, the RINEX navigation file header showed :

- GPUT = GPS to UTC
- GAUT = GAL to UTC
- GPGA = GPS to GAL ... but was in fact GAL – GPS

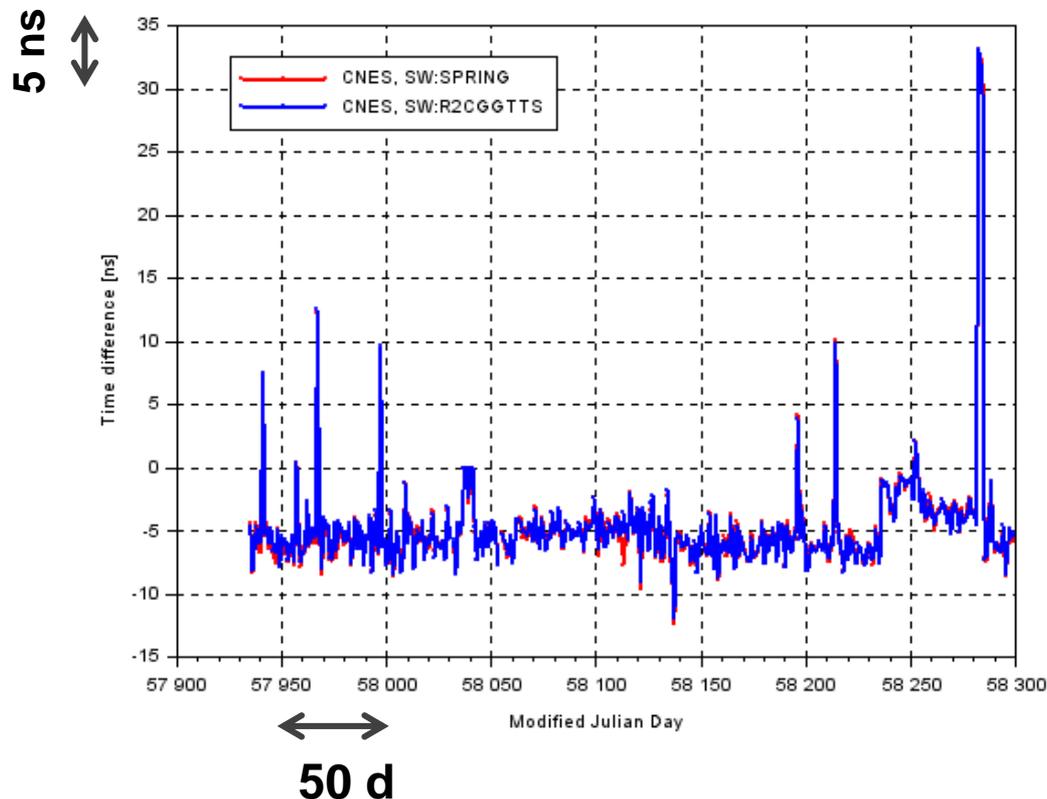
### New v3.04 will clarify :

- GPUT = GPS – UTC
- GAUT = GAL – UTC
- **GAGP** = GAL – GPS

**New formulation in v3.04 is no more ambiguous**

# KPI#3 : GGTO accuracy

## CNES station (June 2017 to June 2018)



**Initial Services Requirement**  
**< 20 ns, 95% of average daily**  
**offset, normalised annually**

Mean : -5.4 ns  
Std : 1.8 ns  
95% : 8.2 ns

OK

## **SUMMARY**

- **The GRC-MS will monitor independently the performances of Galileo, and in particular of GST**
- **This monitoring requires absolute calibration of the station**
- **CNES has already started the monitoring of 3 timing KPIs, that are up to now compliant to the Galileo OS time requirements**
- **GST has underwent a drift in May-June 2018 but the broadcast information GST – UTC remained accurate, inducing no impact to users**

**Thank you for your attention**

**Questions ?**



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