





A Unique Scheme for NavIC and INS Measurements Synchronization for High Accuracy Integrated Navigation System

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In launch vehicle, integrated navigation system is used for high accuracy navigation, especially for multi orbit missions □ INS error are estimated using NavIC/GPS solution and these errors are periodically corrected to ensure high accuracy The guidance algorithm uses aided state vectors to achieve mission accuracy in meter level In order to have proper integration of INS and NavIC, the measurements from these complimentary systems shall be synchronized









- Launch vehicle avionics system has two modes of operation, flight mode and pre-flight/monitor mode.
- □ In flight mode, the on-board computer (OBC) is the master clock.
- All remote terminals (including navigation system) has to be synchronized with OBC during flight mode
- Integrated navigation algorithm requires synchronization between INS and NavIC receiver measurements; avoiding extrapolation of data from one system to other.
- In pre-flight mode (when OBC is not active), NavIC receiver measurements are to be decoupled from OBC timeline.
- Receiver time base (TIC) shall be dynamically adjusted during the mode transition(flight mode/monitor mode), ensuring continuous NavIC solution availability.





- □ In the new method, the total timing is based on OBC clock
- The uncertainty on OBC clock is measured using high stability NavIC receiver clock (TCXO/OCXO) and is accounted in NavIC measurements.
- Time base signal(TIC) is continuously steered to align with OBC timer during flight mode
- Integrated Carriers Phase measurement time interval may slightly vary depending on OBC clock drift.
- Drift in OBC clock is measured using high stability NavIC clock and this information also used for velocity computation.
- This achieves the INS-NavIC measurement synch with an accuracy of 50ppm (The accuracy of OBC clock) and NavIC measurement accuracy of <1ppm(accuracy of TCXO)</p>















