



Realising CS42 with WGS84

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GEODETIC PROBLEMS OF UZBEKISTAN

•State Geodetic Network of the former Soviet Union was developed by prof. Krasovsky more than 60 years ago. The Republic of Uzbekistan was part of the former Soviet Union.

• Geophysical services of Uzbekistan use the coordinate system of 1942 (SC-42, a starting point "PULKOVO").

•Distortions in the current datum up to 10 m have been recognized

•This network is static, its points remain stationary.

•Insufficient density of network ITRF for the decision of geodynamic problems

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CATS-Network and Major Active Faults Junggar B. Kasakhstan Platform 44°-Issyk Kul Kizil Koum Tien Shan 40° TarimB. Pamirs Tadjik Depr. Hindu Kush. Kun Lun 36° **Tibet Plateau** 77° 65° 69° 73° 81° transcurrent convergence thrust ▲ GPS-sites rotation fault fault direction





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GPS network in Uzbekistan

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Central-Asian GPS network

- **Russia**
- Kazakhstan
- Kyrgistan
- Uzbekistan
- China

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The Molodensky method

$$B_{84} = B_{42} + \Delta B$$

$$L_{84} = L_{42} + \Delta L$$

$$H_{84} = H_{42} + \Delta H$$





$$\Delta B = \frac{\rho''}{M + H} [-T_X \sin B \cos L - T_Y \sin B \sin L + T_Z \cos B + \Delta a_E (Ne^2 \sin B \cos B) / a_E + \frac{N\Delta e_E^2}{2} \left(\frac{N^2}{a_E^2} + 1\right) \sin B \cos B] + (1 + e_E^2 \cos 2B) (\omega_X \sin L - \omega_Y \cos L) - \rho'' e_E^2 \mu \sin B \cos B;$$

$$\Delta L = \frac{\rho''}{(N+H)\cos B} (-T_X \sin L + T_Y \cos L) - tgB (1 - e_E^2) (\omega_X \cos L + \omega_Y \sin L) + \omega_Z;$$

$$\Delta H = T_X \cos B \cos L + T_Y \cos B \sin L + T_Z \sin B - \frac{a_E \Delta \alpha_E}{N} + \frac{\Delta^2_E N \sin^2 B}{2} + e_E^2 N \sin B \cos B \left(\frac{\omega_X}{\rho''} \sin L - \frac{\omega_Y}{\rho''} \cos L\right) + \mu (N + H - e_E^2 \sin^2 B).$$





The Helmert method

$$\begin{bmatrix} X \\ Y \\ Z \end{bmatrix}_{CK-42} = \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}_{WGS-84} + \begin{bmatrix} T_X \\ T_Y \\ T_Z \end{bmatrix} + \begin{bmatrix} m & \omega_Z & -\omega_Y \\ -\omega_Z & m & \omega_X \\ \omega_Y & -\omega_X & m \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}_{WGS-84}$$





Coordinates difference between WGS-84 and SC-42 for CATS points in Uzbekistan







Coordinates difference between WGS-84 and CK-42

dx = 28, dy = -130, dz = -95World Geodetic System 1984. NIMA, 2000







dx = 24, dy = -141, dz = -81 GOST 51794-2001







Coordinates difference between WGS-84 and CK-42

DATUM TRANS.	ΔΧ	ΔΥ	ΔZ	Method	Comments
CS42-WGS84	+15	-130	-84	Molodensky	NIMA
CS42-WGS84	+43	-108	-119	Helmert	NIMA (Caspian)
CS42-WGS84	+28	-130	-95	Molodensky	NIMA
CS42-WGS84	+25	-141	-80	Helmert	GOST(RU)
CS42-WGS84	+22	-123	-83	Molodensky	Bazlov(RU)
CS42-WGS84	+23	-125	-87	Molodensky	Fazilova(UZ)





Velocity of Kitab station in 1994-2000







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Continental moving







DORIS network







GPS station in Kitab

$φ=39^{\circ} 07' 59'', λ=66^{\circ} 52' 57.0'', H=657 \text{ m.} (CS-42)$ $φ=39^{\circ} 08' 05'', λ=66^{\circ} 53' 07.6'', H=622 \text{ m.} (WGS-84)$





1992-1996

The international program CATs(GFZ,Germany)

- RMS: 1-3mm. for x, y
- RMS: 5mm. for H.
- RMS: 1-2cm. for Global network



IGS network



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THANK YOU for attention