

S2VSE - SYSTEM AND SERVICE VOLUME SIMULATION ENVIRONMENT SEBASTIAN BERNHARDT, FLORIAN EISELBRECHER 23.10.23 HELSINKI

> Galileo Kompetenzzentrum



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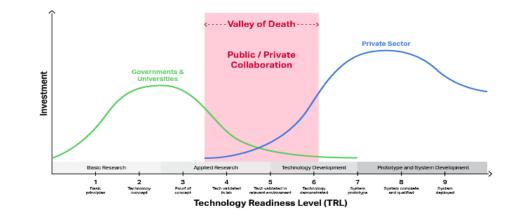
FOR A PRECISE AND SAFE FUTURE

### **Galileo Competence Center**



#### Goals

- Evaluate the design of future systems
- Identification of future key technologies
- Identification of the most effective upgrades or modifications to existing satellite navigation systems
- Assessment of the significant value technologies can have
- Assessment of market potential of technologies
- Bridge the gap between research and industry



#### **GK in numbers:**

- Founded on 28th June 2019
- Fully established by 2024
- Planned number of employees 120-150



### **Galileo Competence Center**

#### **Goals Performance Analysis and Simulation**

- Analysis of existing GNS Systems (focus on Galileo) and services via
  - Assessment of user requirements
  - Evaluation of current system performance
  - Evolution of existing concepts
- Simulation, analysis and validation of new technologies and subsystems
- Conception of new architectures to support the development of Galileo and future generations of EGNOS, including their services





# S2VSE - SYSTEM AND SERVICE VOLUME SIMULATION ENVIRONMENT

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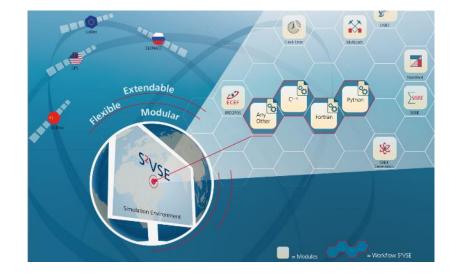
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#### **General Objectives**

Modular and flexible simulation and performance analysis tool for space, ground and user applications

- Reproduction, analysis and study of current and future GNSS structures and operational scenarios
- Evaluation of the system performance under different conditions and influencing factors (constellations, propagation effects, technologies, ...)
- Assessment and prediction of Key Performance Indicators (KPIs: accuracy, integrity, coverage, continuity and availability)







#### **Module Design**

- Each module is based on one or multiple libraries, both parts are implemented in **Python**
- Both the module and the library functions are unit tested using PyTest
- Technical documentation for each function is automatically generated using **Sphinx**
- All modules are kept under version control with Git







### Modules (ca. 100) are separated into three categories:

Core functionalities (50%)

Core functionality includes conversions, error models, integrity, orbit generation, parser, receiver grid generation and more

Visualisation (35%)

Visualization modules provide pre-defined graphs and plots

Utilities (15%)

Utility components provide features to improve the flow of each scenario and the overall quality of the simulation

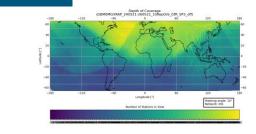




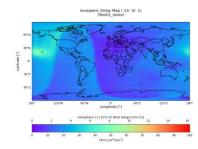


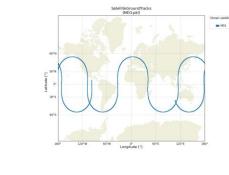
#### Visualisations

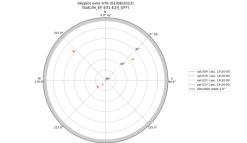
- Depth-Of-Coverage (DOC)
- Total-Electron-Content (TEC) maps
- Differences in orbit
- Ground tracks
- Sky plots
- Visibility times
- Dilution-Of-Precision (DOP), etc.



ce for E01 (07/08/2021, 23:59:42 - 08/08/2021, 22:59:42 (GFR0821)







180.0" Skyplot for 0h over 476 (Lat: 45.0" / Lon: -105.0")

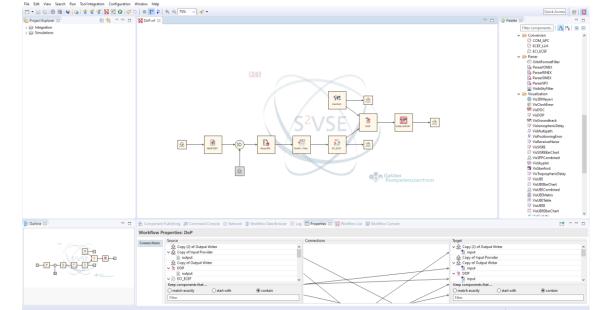






#### Simulation environment: Remote Component Environment (RCE)

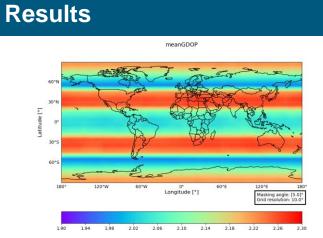
- Developed by DLR's Institute of Software Technology (SC)
- Open source Java software based on Eclipse Editor
- Enables simulation module distribution and remote execution



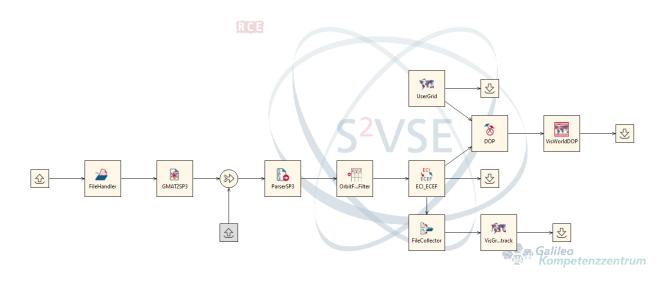


#### **KPI:** Dilution-Of-Precision (DOP)

- Dependent on the satellites in the line of sight of the receiver
- Geometry between satellites in correlation to the receiver impacts the position error
- Input: Receiver positions and satellite orbits



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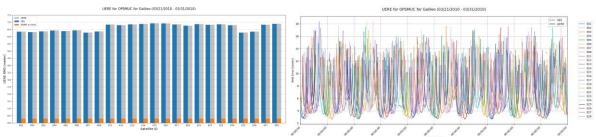


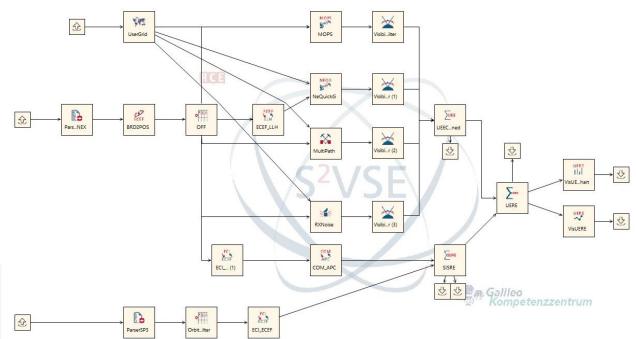


#### KPI: User-Equivalent-Range-Error (UERE)

- Describes the total error affecting the pseudorange
- Contains Signal in Space Ranging Error (SISRE) and User Equipment Error (UEE)
- Input: Receiver positions, Ephemerids and precise orbits

#### Results





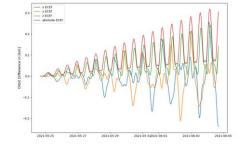


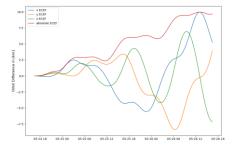
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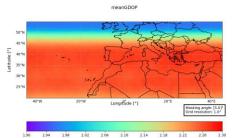


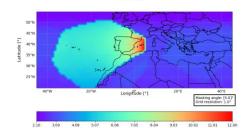
#### **Current Projects**

- Impact of solar radiation pressure and space weather on orbit determination 1.
- Impact of Satellite End-of-Life on Galileo 2.
- Constellation generation to compare different constellations in an urban 3. environment

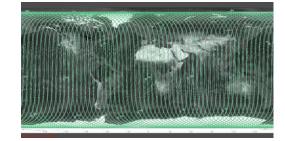


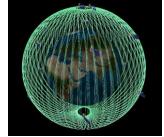






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#### **Current Use Cases**

#### **Automotive – Precision** Farming

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#### **Planned Use Cases**

- Evaluation of new services and innovative applications
- Use of a customized open module design with individual parameter control

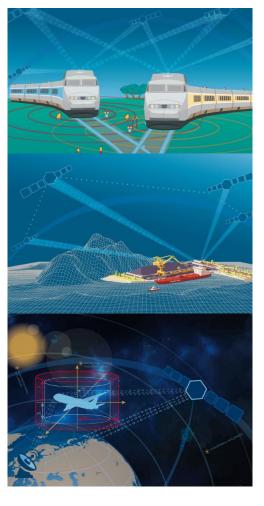
#### **Future Module Development:**

- Extended orbit propagation
- Modular position solver
- User equipment simulation
- More environmental models

Rail – Collision Avoidance

Maritime – Docking of a vessel

Aviation – Precision Landing









# THANK YOU FOR YOUR ATTENTION

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