



# United Nations Workshop on the International Space Weather Initiative

Vienna, Austria (26 – 30 June 2023)



## Session 6: Space Weather Effects on Technology

# Effects of Equatorial Plasma Bubbles on Performances of Real-Time Kinematics (RTK)

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# Outline

- ⇒ Introduction
- ⇒ Equatorial Plasma Bubbles (EPB)
- ⇒ Effects of EPBs on RTK Performances



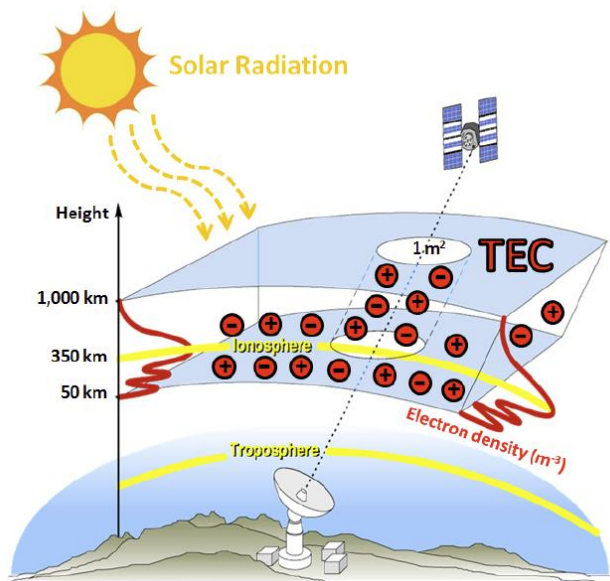
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พระจอมเกล้า  
ลาดกระบัง



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Weather

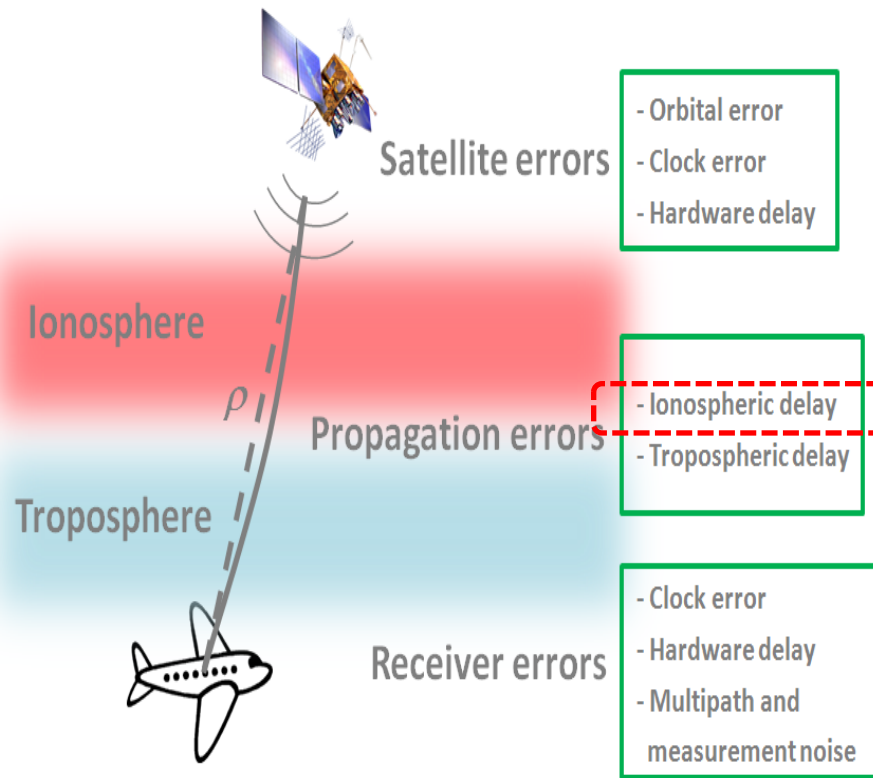
# Equatorial Plasma Bubble (EPB) Phenomenon

# Ionospheric Delay

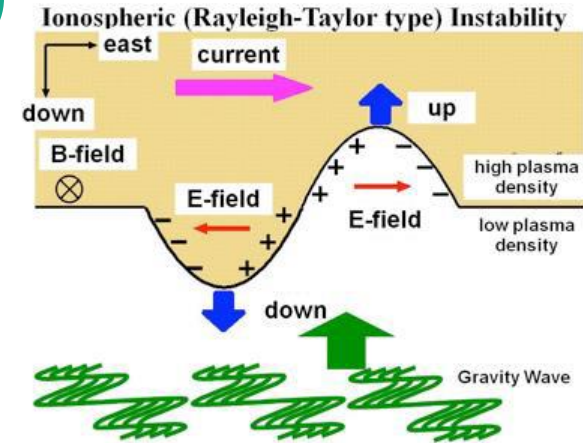
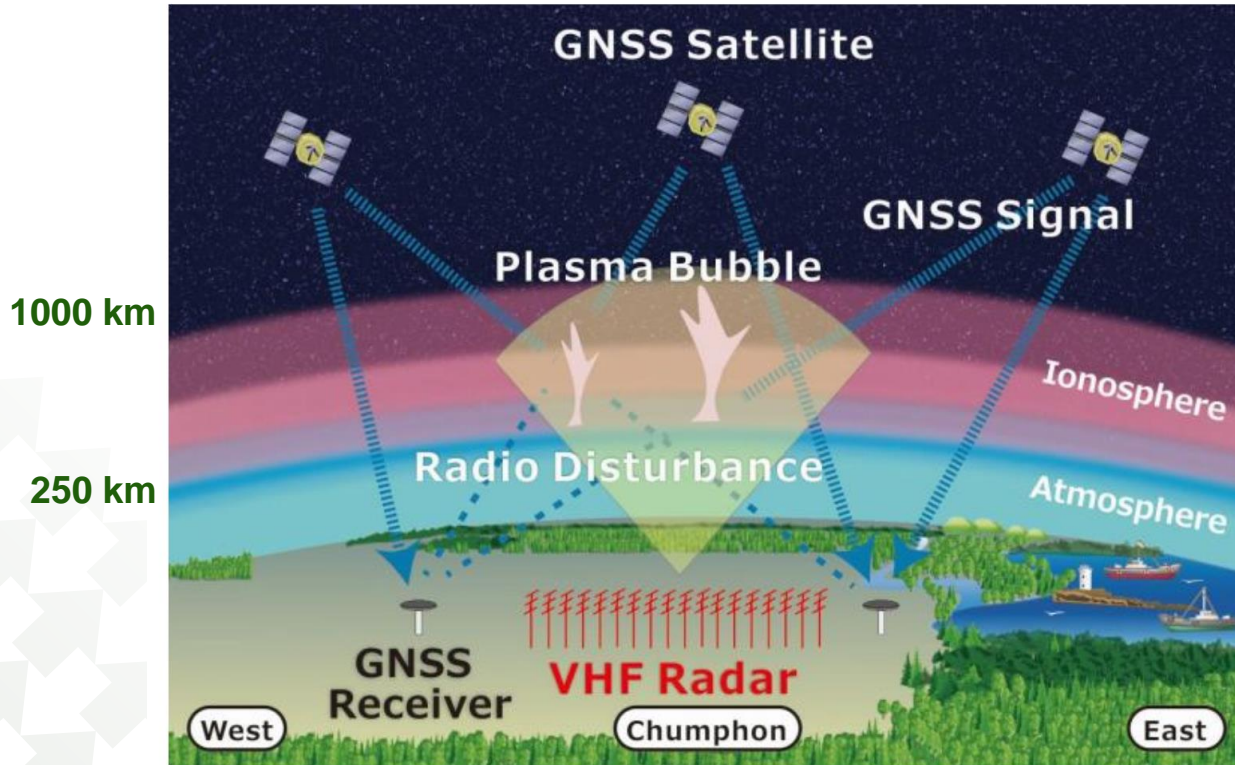


$$dTEC = \frac{40.3 \text{ STEC}}{f^2}$$

STEC = slant total electron content (eI/m²)



# Equatorial Plasma Bubbles (EPB)



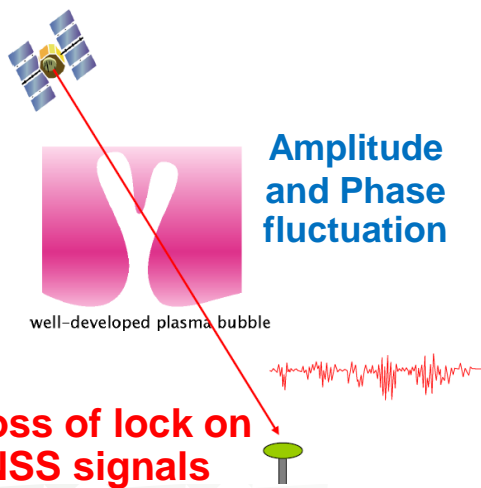
## Local ionospheric disturbance

- driven by global disturbance (e.g. magnetic storms)
- local irregularity
- occurs after sunset, near magnetic equator

# Effects of EPB

VHF Comm.

Scintillation



## Could Plasma Bubble Have Doomed U.S. Copter in Afghanistan Battle?

A U.S. military rescue mission in Afghanistan went horribly wrong when a crucial radio message wasn't received.

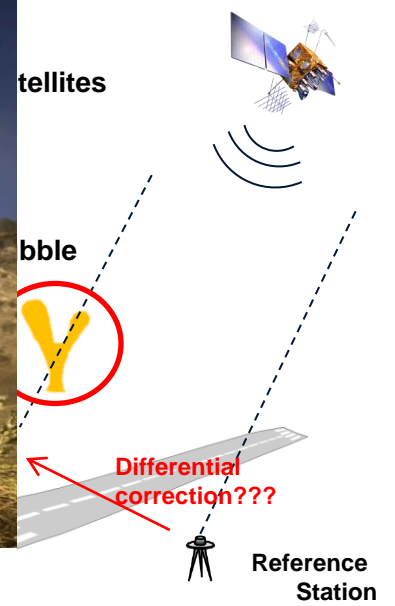


## Could Plasma Bubble Have Doomed U.S. Copter in Afghanistan Battle?

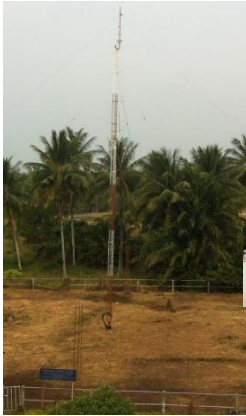
A U.S. military rescue mission in Afghanistan went horribly wrong when a crucial radio message wasn't received.



ical navigation



# Research Facilities



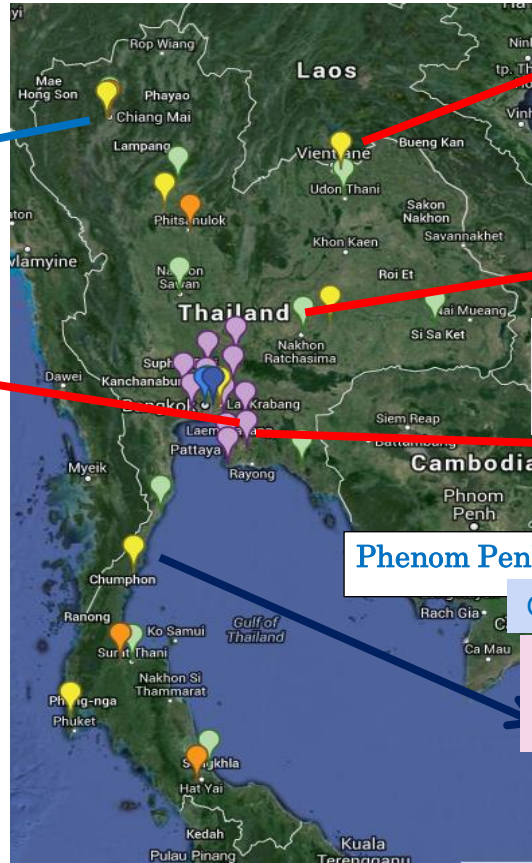
Ionosonde  
GNSS receiver  
Beacon receiver



Chiangmai  
(CHM)

Bangkok (STFD)

GNSS receiver



Vientiane  
(Laos)

GNSS receiver



Nakhon  
Ratchasima  
(NKR)

GNSS receiver



Bangkok  
(KMITL)

GNSS receiver  
Beacon receiver



Phnom Penh

GNSS receiver

Chumphon  
(CPN)

Ionosonde  
GNSS receiver  
Beacon receiver  
VHF radar

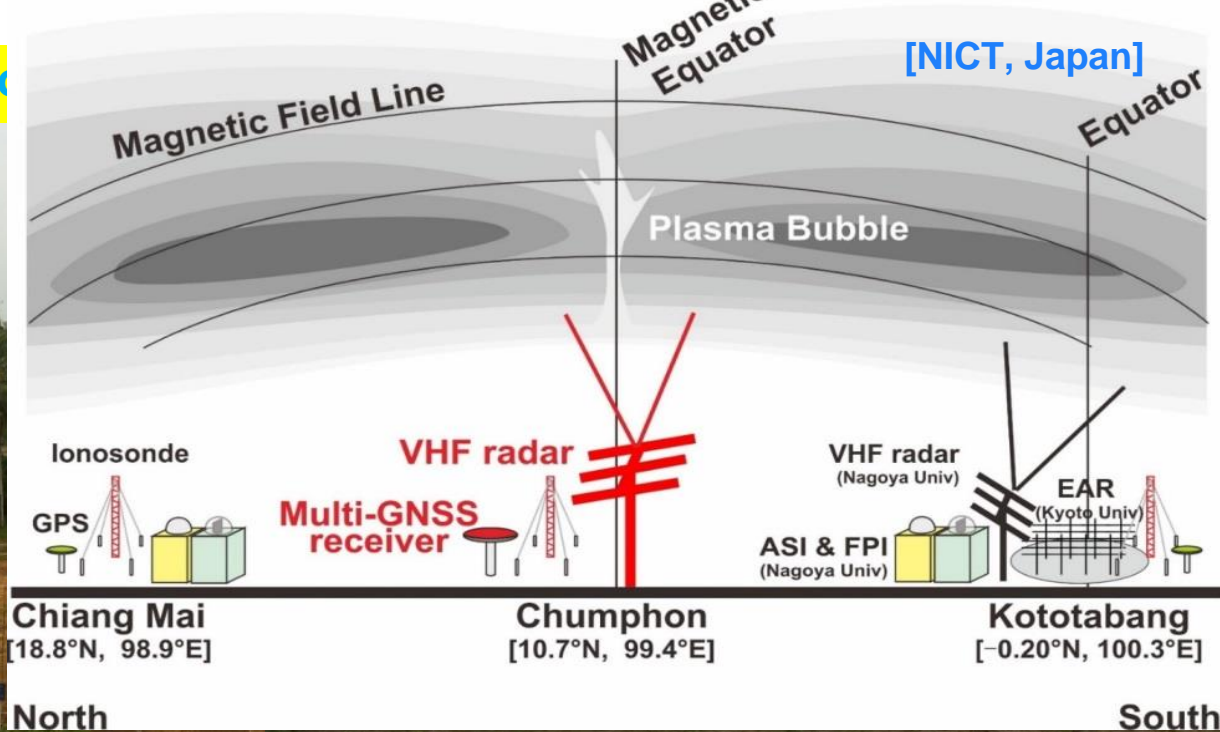


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# Chumphon observatory (10.7°N, 99.4°E, Magn. Lat. 3°)



Magnetometer



Optical Sky Imager



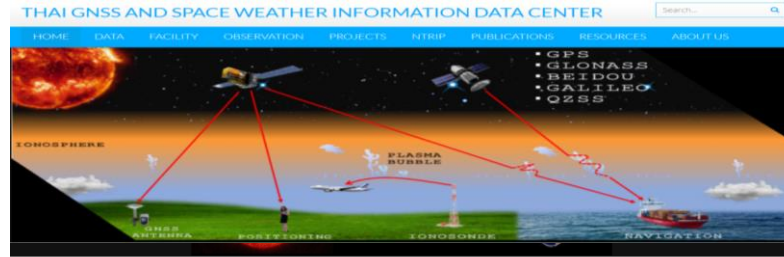
GNSS receiver





# Thai GNSS and Space Weather Information Center

<http://iono-gnss.kmitl.ac.th>



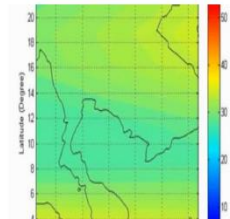
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## WELCOME

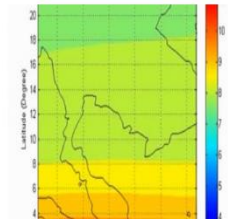
Welcome to the Thailand GNSS and Space Weather Information Data Center hosted at King Mongkut's Institute of Technology Ladkrabang (KMITL)



KNOWLEDGE



VTEC IRI MODEL



FOF2 IRI MODEL

Current status of GNSS and ionospheric monitoring networks and the efforts to create a GNSS and ionospheric database in Thailand. These data are used for various applications such as the ionosphere, Troposphere, GPS/GNSS technology, Geodesy and applications on the aeronautical navigation, satellite communication, and space weather. At present KMITL, Chulalongkorn University, Chaingmai University, NICT as well as Kyoto University, Japan have cooperated to install a monitoring equipment such as ionosondes, all-sky imager, magnetometer as well as GNSS receivers in various locations of Thailand such as Koh, and Phuket. Other GPS networks and ionosonde stations exist, whereby each network is owned and operated independently. For example, there are 11 stations, the Royal Thai Navy owns three ionosonde stations, the Thai Meteorological Department houses 5-7 GPS receivers and the Department of Land owns 3-4 GPS receivers. We aim to create the database of GPS data and ionospheric parameters in the Thailand location. In our plan, the data from various universities and agencies is being foreseen. At present, Thai GNSS and Space Weather Information Data Center is collecting the data from all the ionosonde stations by using the script at each station to send the raw data through the Internet to the server at KMITL. The database is used for TEC and enhances the study of the ionosphere.

# Ionospheric Disturbances

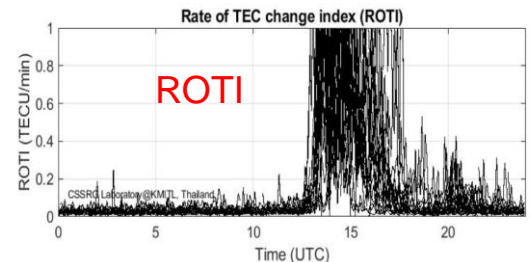
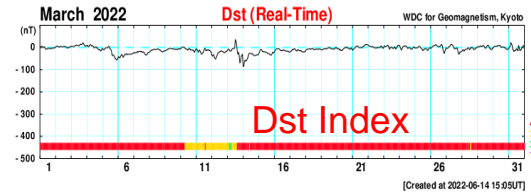
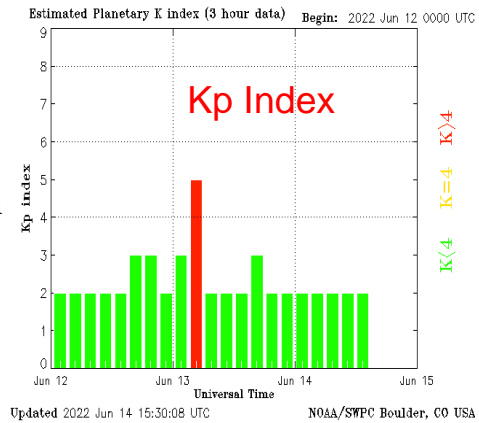
- The electron density in the ionosphere varies with time, location, and solar and geomagnetic activities
- **Global Condition (earth's geomatic activity)**
  - Kp - Planetary K-index
  - Dst – Disturbance Strom Time indices

## Local Ionospheric Conditions

- Rate of TEC Change Index (ROTI)

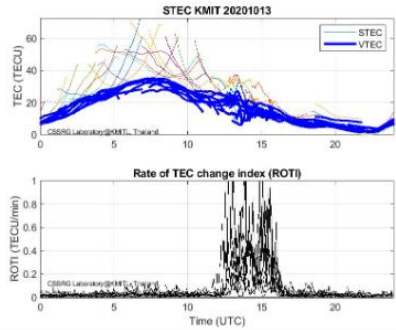
$$ROTI = \sqrt{\frac{1}{N} \sum_{i=1}^N (ROT(i) - ROT)^2}$$

$$ROT(i) = STEC(i + 1) - STEC(i)$$

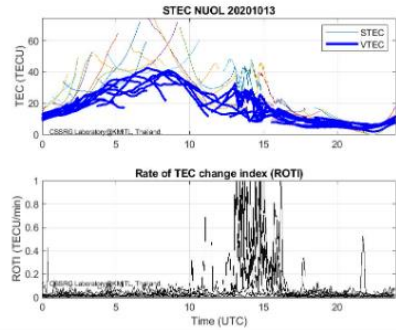


# Daily TEC/ROTI Plots

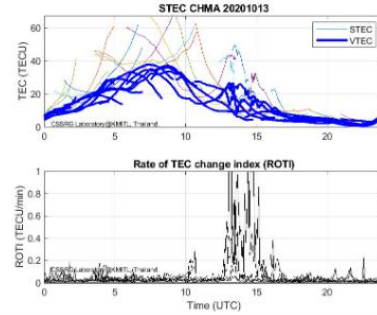
## Bangkok (KMITL)



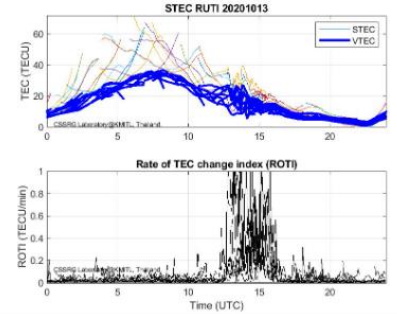
## Vientiane (NUOL)



## Chiangmai (CHMA)

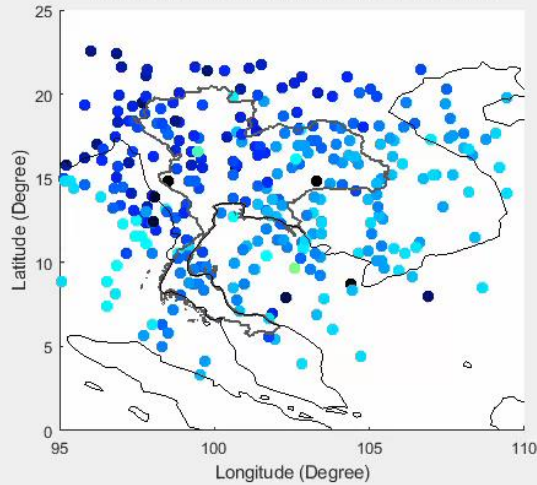


## Nakhon Ratchasima (RUTI)

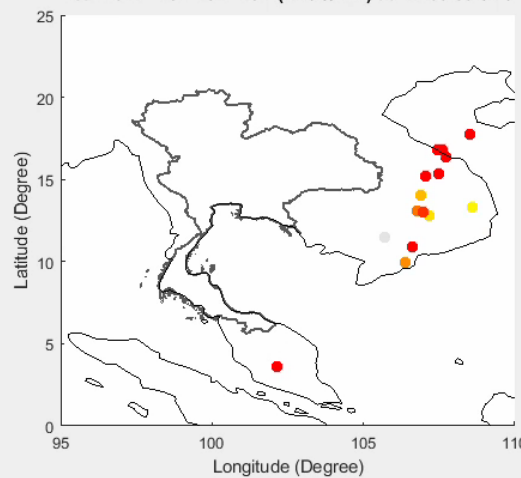


# 2-D TEC/ROTI Map

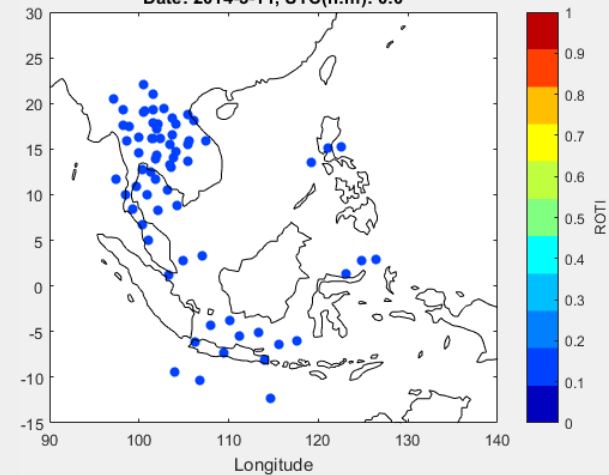
## Year 2022 DOY 284 TEC(TECU) at 0:05:00 UTC



## Year 2022 DOY 284 ROTI(TECU/min) at 12:05:00 UTC



## Date: 2014-3-11, UTC(h:m): 0:0





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ลาดกระบัง

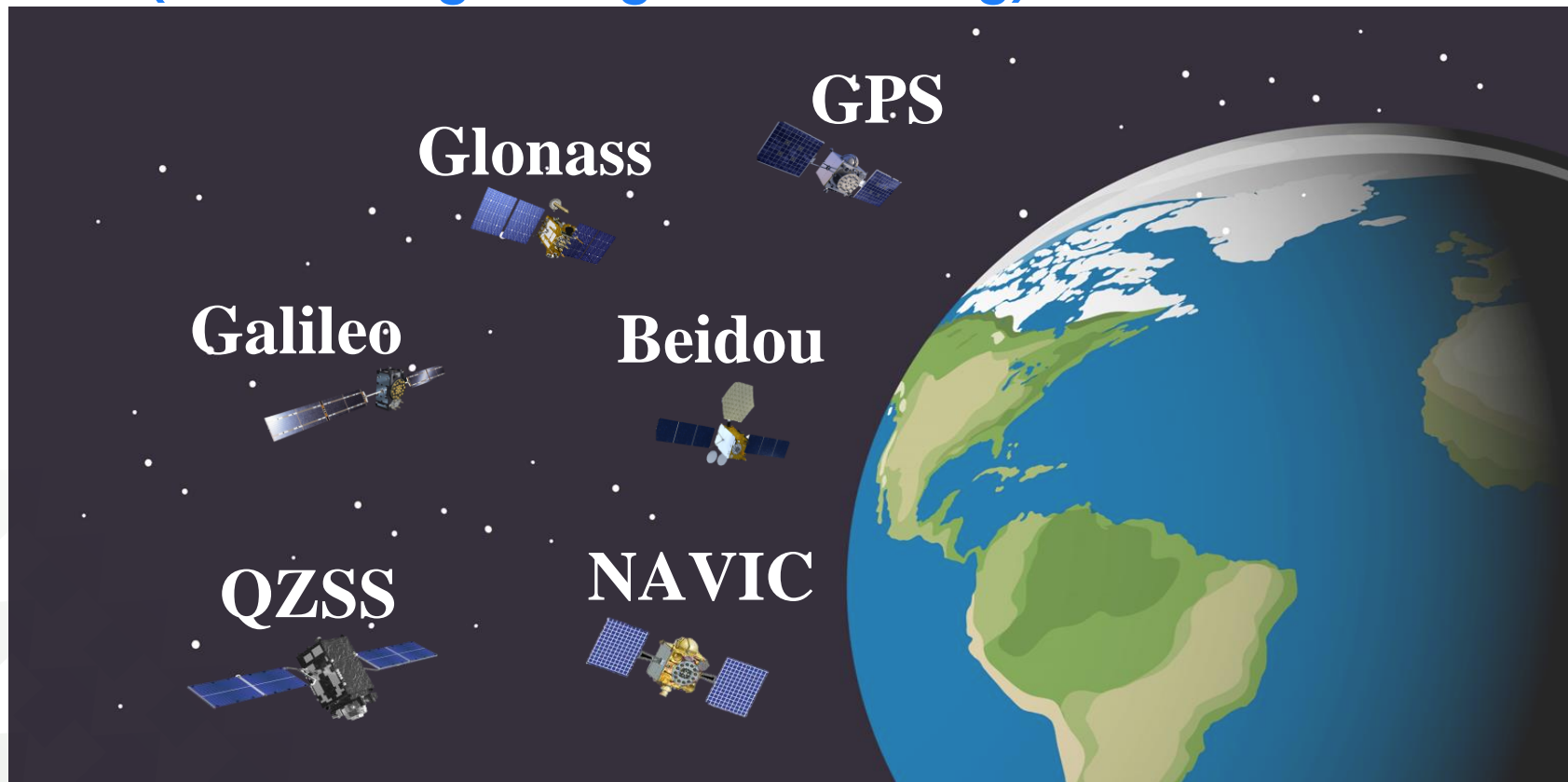


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# Real-time kinematics (RTK) Technology

# GNSS System – National PNT Infrastructure







(Positioning, Navigation, Timing)



Ref. [Uragan-K \(GLONASS-K, 14F143\) - Gunter's Space Page \(skyrocket.de\)](#), Artwork: The European Commission is about to place an order for more Galileo spacecraft, [QZSS.go.jp](#), [ilrs.gsfc.nasa.gov](#)

**United Nations Workshop on the International Space Weather Initiative (26 – 30 June 2023)**

# GNSS Frequency Bands

	E5/L5 Band	L2 Band	E6 Band	E1/L1 Band
 <b>GPS</b>	1176.45 MHz L5-BPSK	1227.6 MHz L2-BPSK		1575.42 MHz L1-BPSK
 <b>Glonass</b>	1176.45 MHz L5OC	1246.0 MHz BPSK 1248.06 MHz L2OC		1602.0 MHz BPSK 1575.42 MHz L1OC
 <b>Galileo</b>	1176.45 MHz E5		1278.75 MHz E6-BPSK	1575.42 MHz E1-CBOC
 <b>Beidou</b>	1207.14 MHz E5		1268.52 MHz B3 1278.75 MHz B3-A	1561.098 MHz B1 1575.42 MHz BOC
 <b>QZSS</b>	1176.45 MHz L5	1227.6 MHz L2C	1278.75 MHz LEX-BPSK	1575.42 MHz L1
 <b>NAVIC</b>	1176.45 MHz IRNSS-BPSK			

# Pseudorange ( $R$ )

⇒ The pseudorange  $R(t)$  at time  $t$  (at the receiver)

$$R(t) = c\tau + c(b_s^j - b_r) + \varepsilon_{mult}(t) + n$$

$$R(t) = \underbrace{\rho(t, t-\tau)}_1 + \underbrace{\delta_{ion}(t)}_2 + \underbrace{\delta_{tro}(t)}_3 + c \underbrace{(b_s^j - b_r)}_{4 \quad 5} + \varepsilon_{mult}(t) + n$$

$t$  = arrival time at the receiver

$t-\tau$  = emission time from the satellite

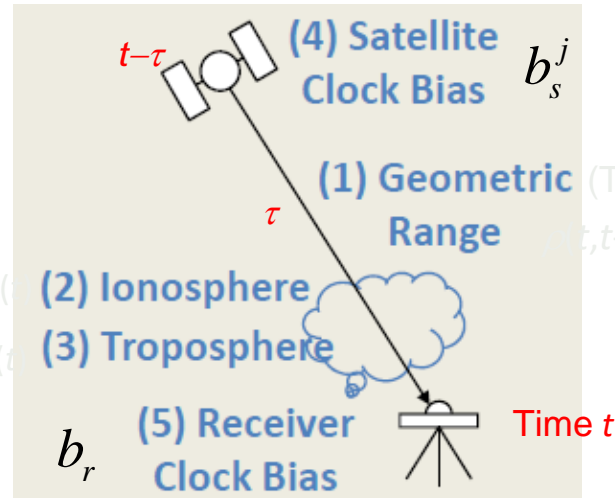
$\tau$  = transit time

$\delta t_r$  = receiver clock bias

$\delta t_s^j$  = satellite clock bias

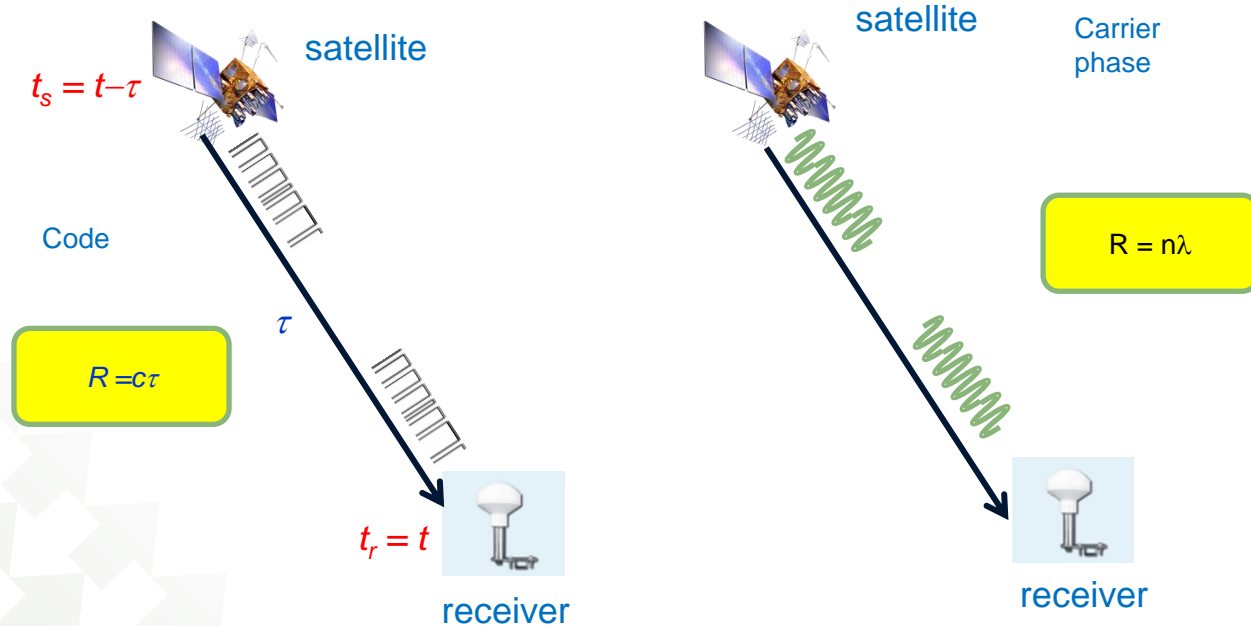
$\varepsilon_{mult}(t)$  = multipath

$n$  = errors



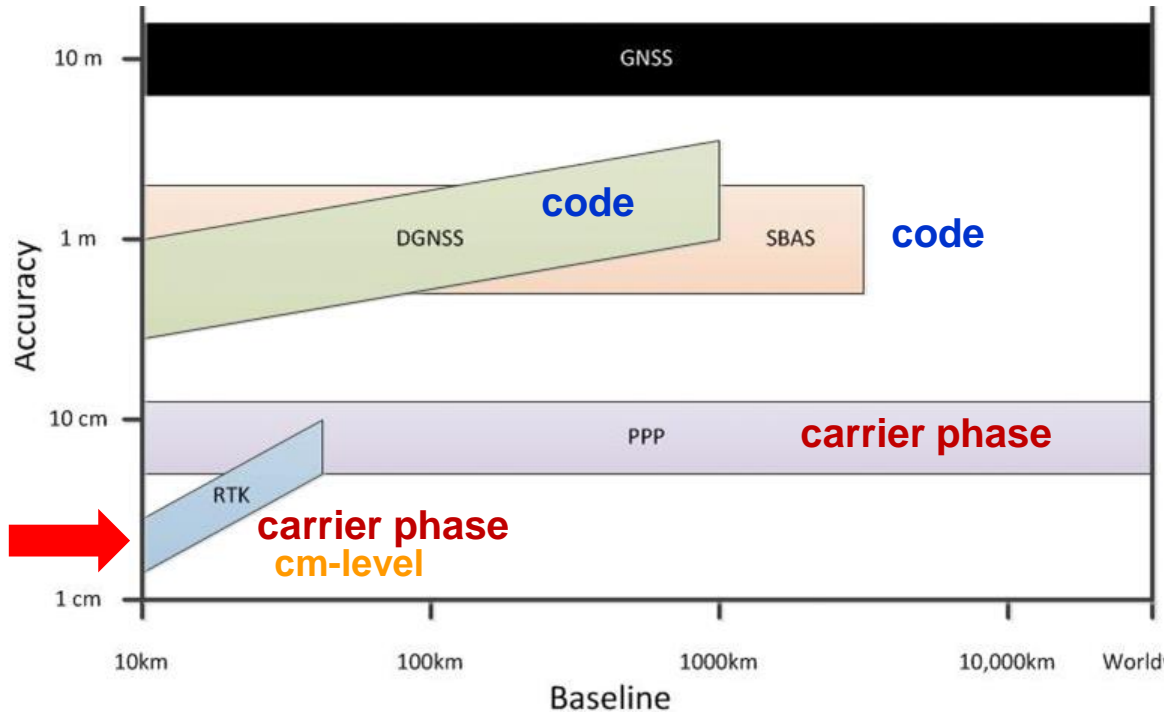
# Code vs. Carrier phase pseudorange

⇒ Pseudorange (R) can be computed from 'code' or 'carrier phase'





# Positioning accuracy levels



Single-Point  
Positioning (SPP)  
meter-level

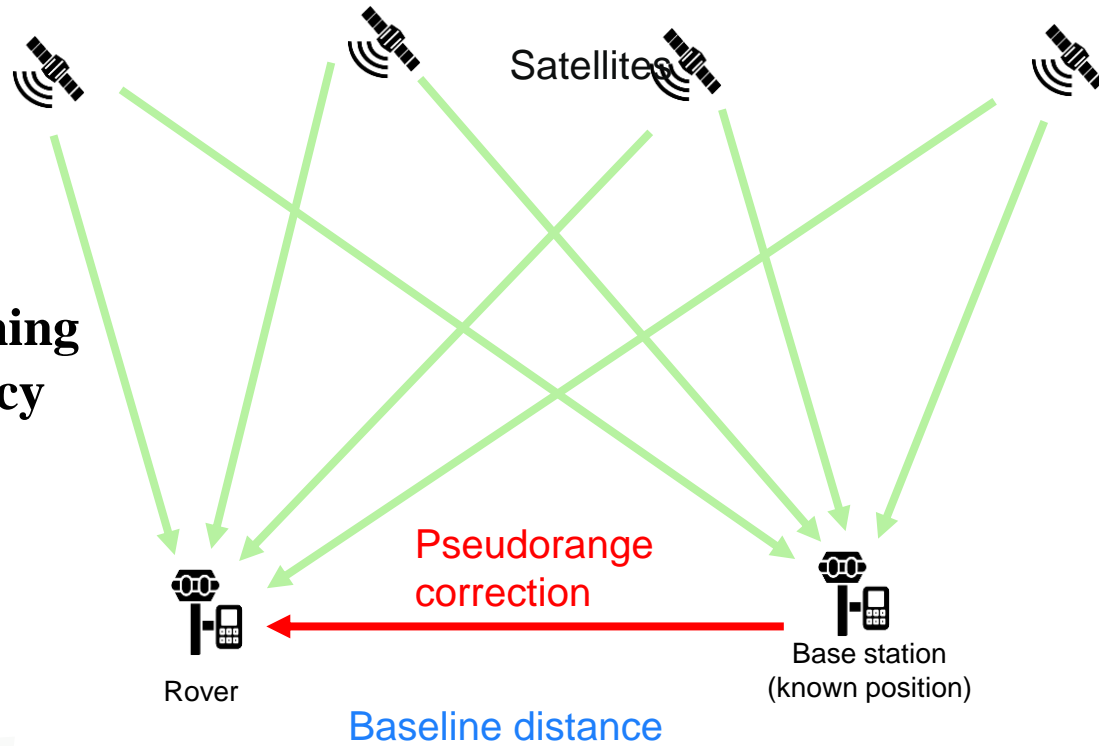
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Weather



# Real-Time Kinematic Positioning (RTK)

**Relative Positioning**  
**cm-level accuracy**

- Base
- Rover (User)





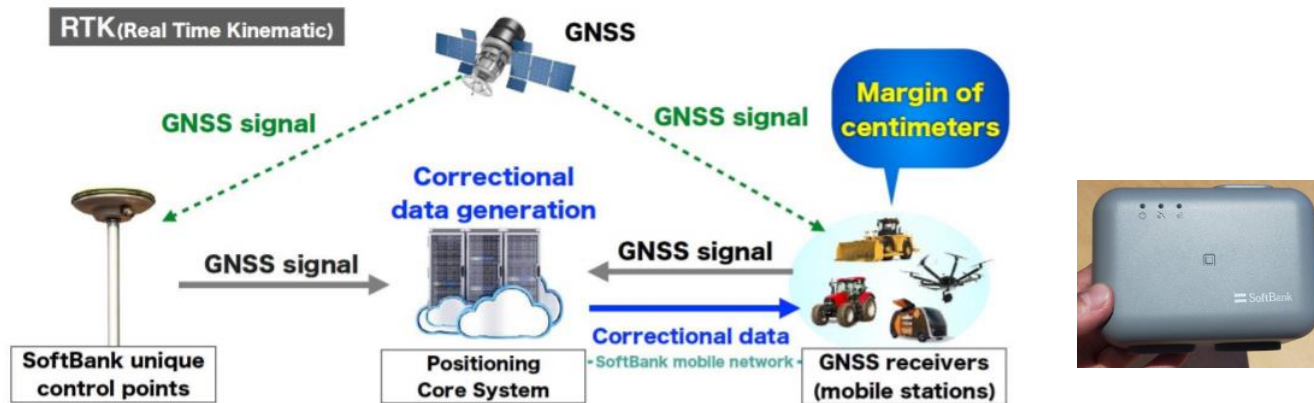
KMITL  
 ศูนย์วิจัยและวิจัย  
 วิศวกรรมศาสตร์  
 (www.kmitl.ac.th)

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 Weather

# RTK service by Softbank company

- Since November 2019
- 3,300 control points



From [www.softbank.com](http://www.softbank.com)

# Urban traffic management (UTM)

Source: <https://www.kiast.or.kr/>



Manned & Unmanned  
Integrated Airspace

Lower than 150m

Safe & Efficient Airspace  
Management

Specified Operation Rules for  
Vehicle Types



High Speed Route

## Unmanned traffic management (UTM)



Prohibited Area

Major Infra  
Protection

Airports /  
Military zones /  
Nuclear power  
plant areas



Security

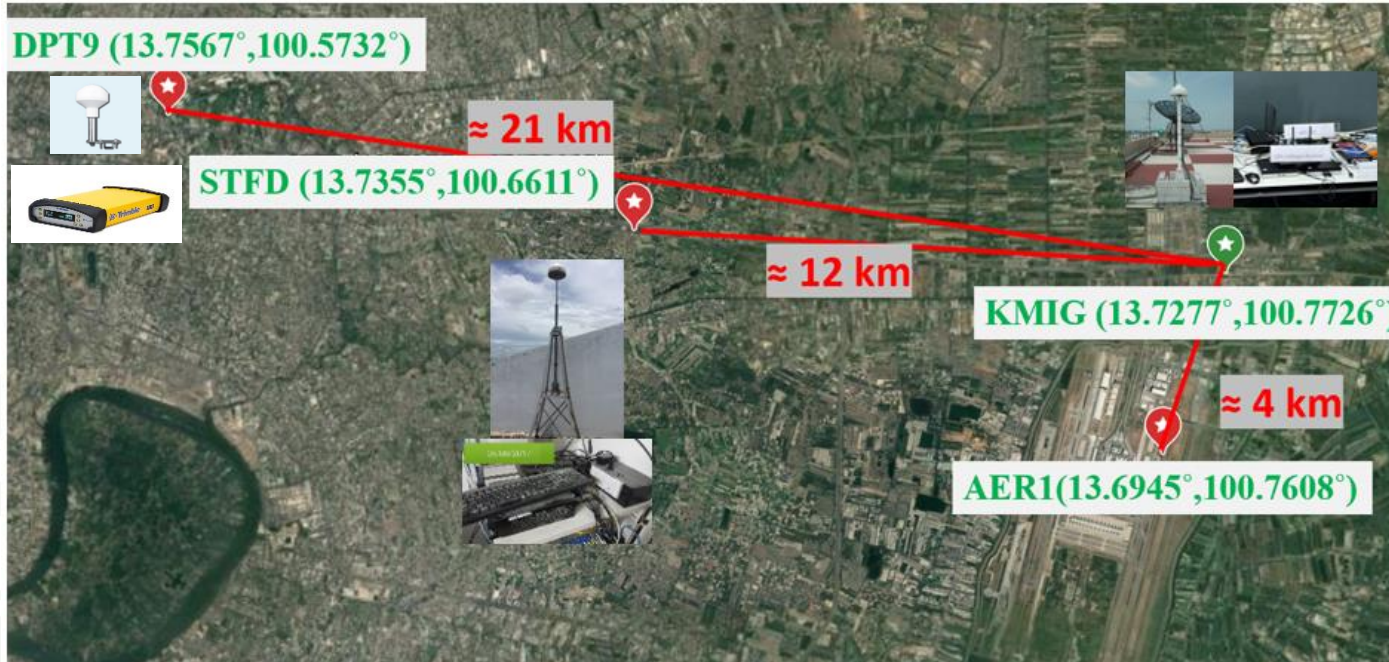
Illegal Flight  
Surveillance  
& Counter  
Action



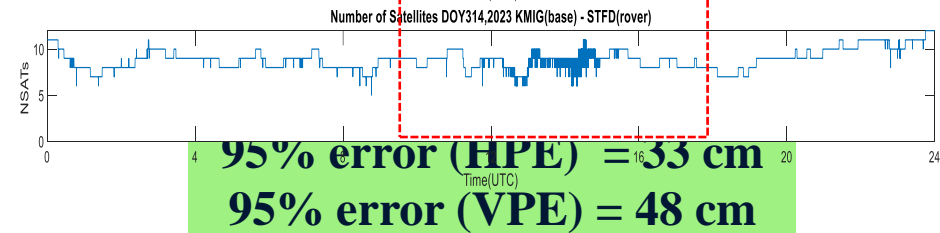
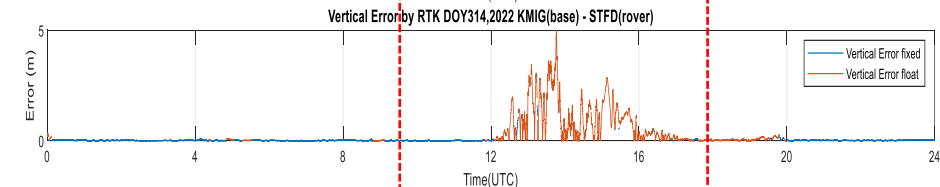
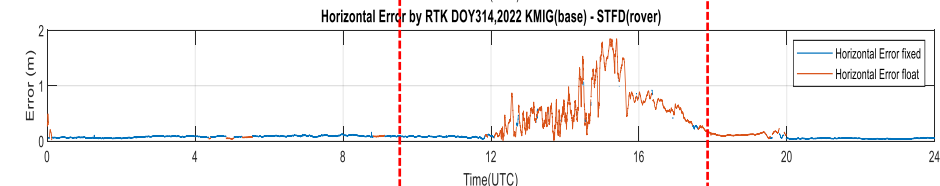
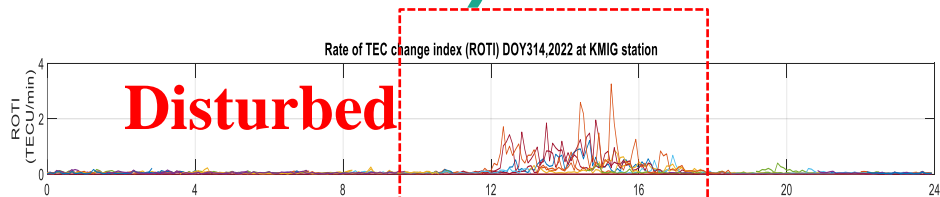
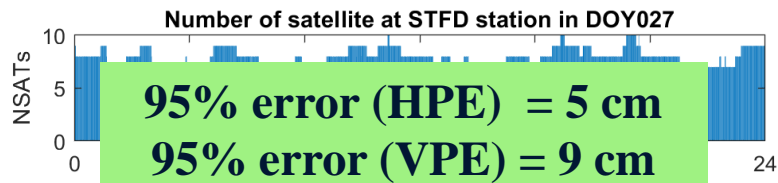
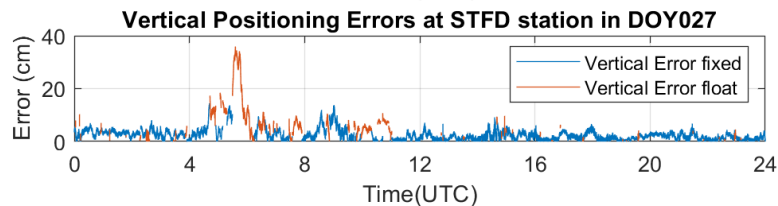
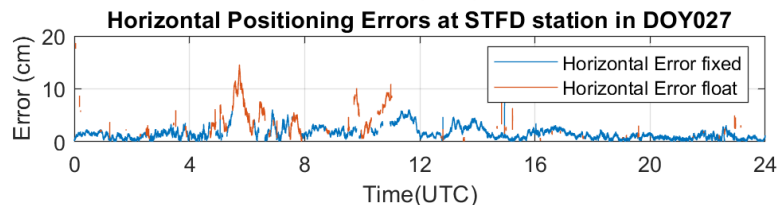
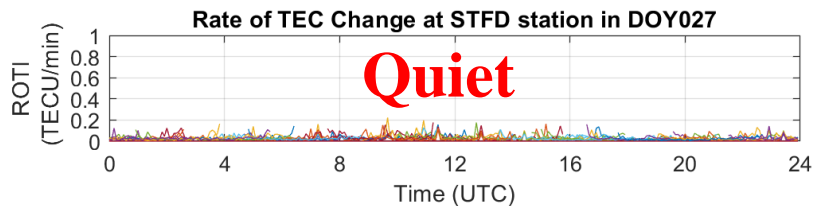
Low Speed Route

Safe Traffic Management  
under High Density  
Traffic

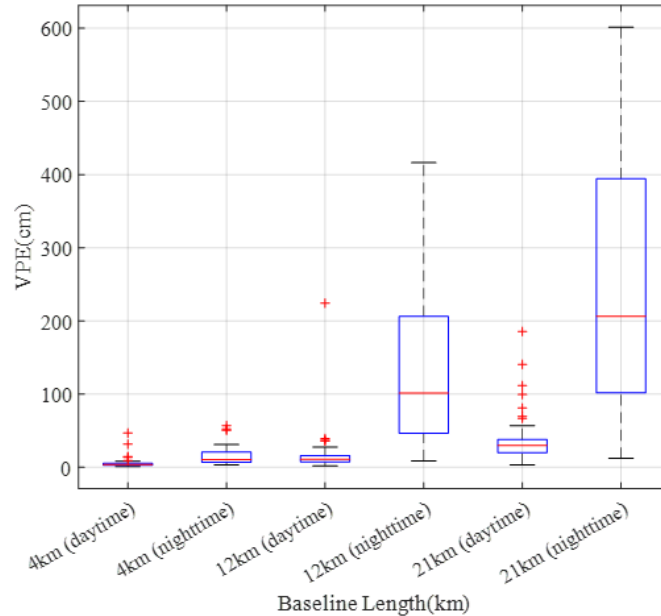
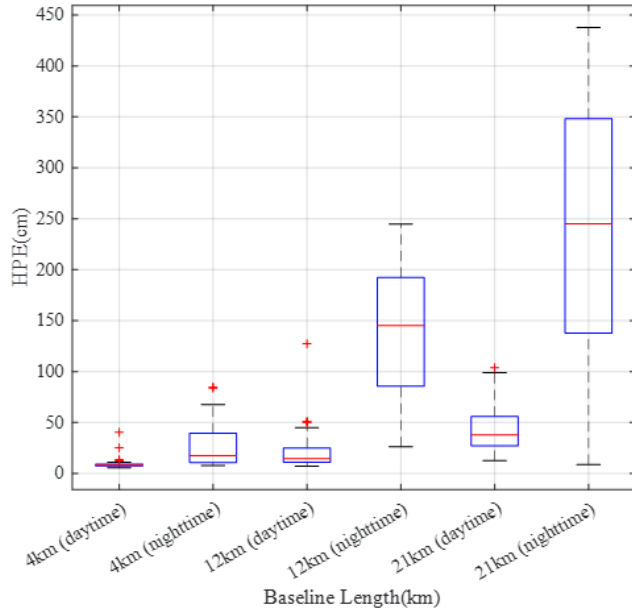
# RTK Experiments



# RTK Performances (12-km baseline)



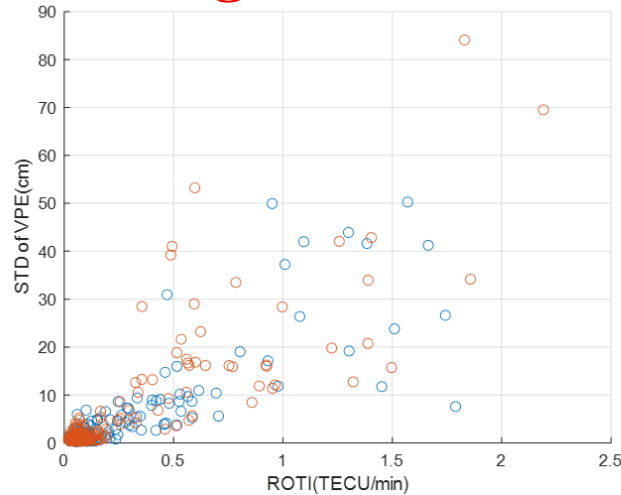
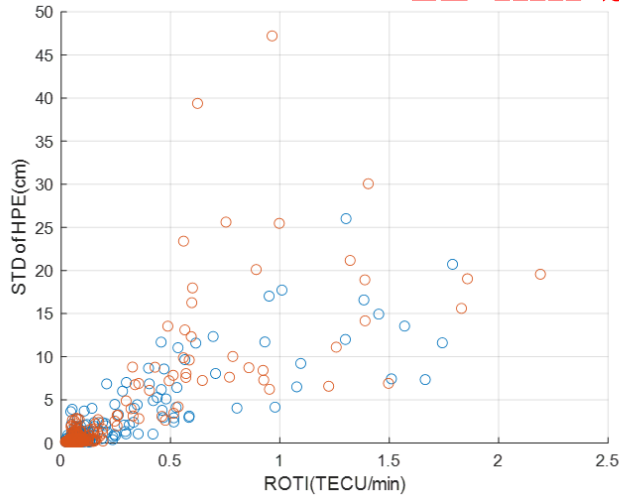
# RTK Performances at each baseline length



[ION GNSS+ 2023]

# RTK Performances vs. ROTI

## 12-km baseline length

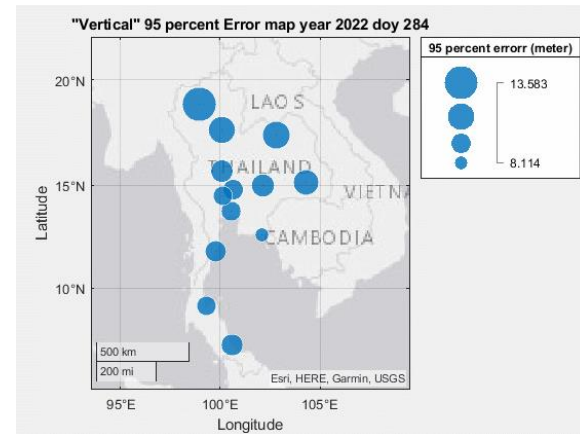
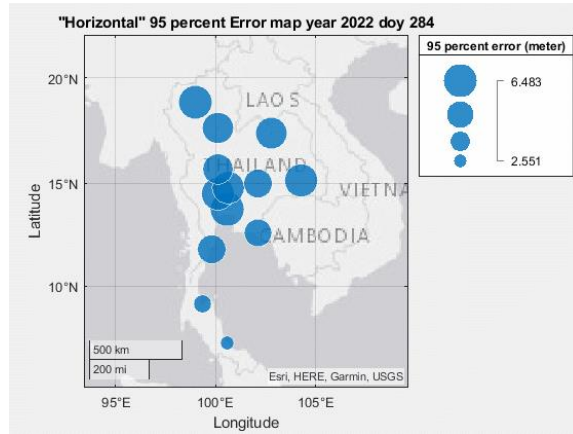


[ION GNSS+ 2023]

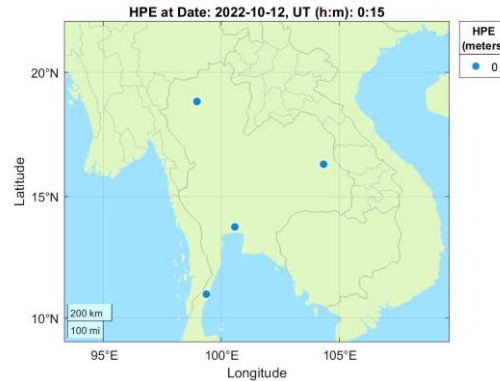


# Positioning Error Map

**Single-point  
positioning  
meter-scale**



**RTK  
positioning  
cm-scale**



# Open Problems

- ⇒ EPB detection
  - Multi-constellation, multi-frequency
  - Hybrid data sources
  - Near real-time detection/prediction
- ⇒ EPB Mitigation in positioning and navigation

# Available Software Download

- ⇒ TEC computation software (MATLAB)
- ⇒ Single-frequency Positioning (MATLAB):
- ⇒ TEC gradient computation (MATLAB)
- ⇒ Kalman filters for positioning with data (sensor) fusion (MATLAB)
- ⇒ L1-SBAS positioning (MATLAB)



<http://iono-gnss.kmitl.ac.th>



<https://www.ukm.my/aoswa/>

# The 6th Asia-Oceania Space Weather Alliance Workshop (AOSWA 2023)

9-11 October 2023 | Bangi Resort Hotel, Selangor, Malaysia

**Abstract deadline: June 30<sup>th</sup>, 2023**

## Sessions:

1. Connect the Local Observation to Global Network
2. CGMS Efforts to Improve User Access to Operational Space Weather Data
3. Education/Space weather awareness to the community through education
4. Application of Artificial Intelligence (AI) in Space Weather
5. Ionosphere-Thermosphere Dynamics and Coupling
6. Technique and Validation of Space Weather Forecast
7. Space Weather Impacts
8. General Topics of Space Weather

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# Thanks!

Homepage : <https://sites.google.com/site/pornchaisupnithi/>



GNSS and Space Weather Information Center:

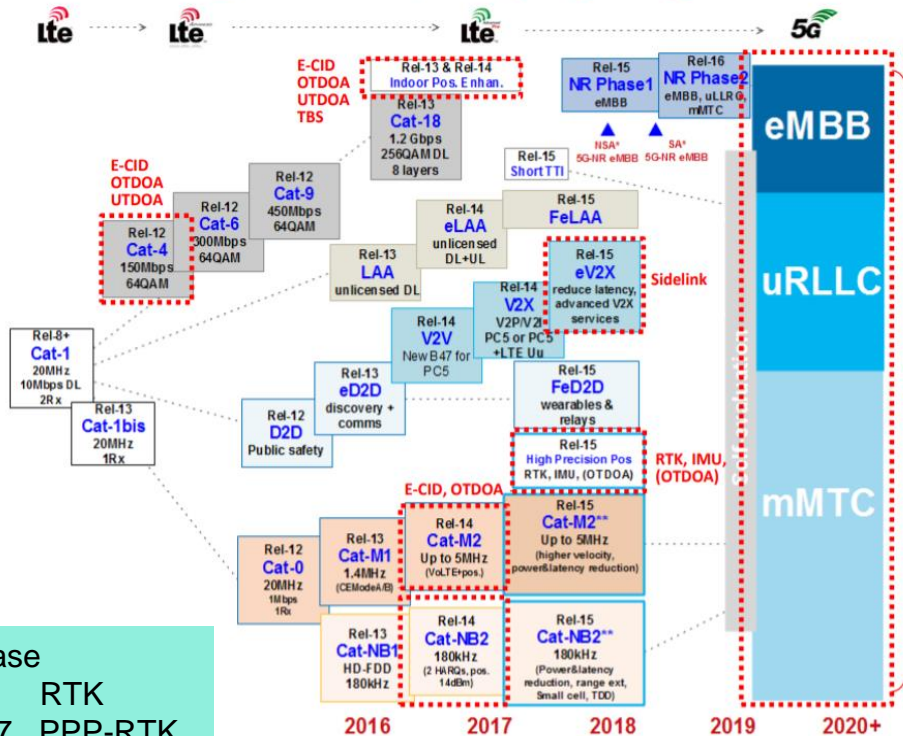
Center of Excellence in GNSS and Space Weather:

<http://iono-gnss.kmitl.ac.th>



# Positioning in LTE/5G

## 3GPP Technology Roadmap – Highlighting Cellular Positioning



**NR Positioning**

**Observations**

- Since 3GPP Rel-11, OTDOA & E-CID have been the flagship cellular positioning technologies
- Additional D2D based ranging solutions are gaining momentum in V2X use cases

**Looking forward, 5G cellular positioning will evolve based on existing E-CID, OTDOA, UTDOA or D2D positioning solutions**

In addition, leveraging RAN-independent technologies, incl.: GNSS, RTK, IMU, Wi-Fi, TBS, Bluetooth, towards hybrid solutions, to cover a wider range of use cases

Release  
15 RTK  
16, 17 PPP-RTK

S. Lu, "5G standards overview&3GPP Tech Evolution Trends. CW SIG Event Sep 2018