



Realistic Ionosphere

with concepts for AI-driven ionosphere forecast

Ivan Galkin and RION Science Team

Realistic Ionosphere, United Nations ISWI
Space Science Laboratory, UMass Lowell
Global Ionosphere Radio Observatory
Lowell Digisonde International, LLC
GAMBIT Situation Room



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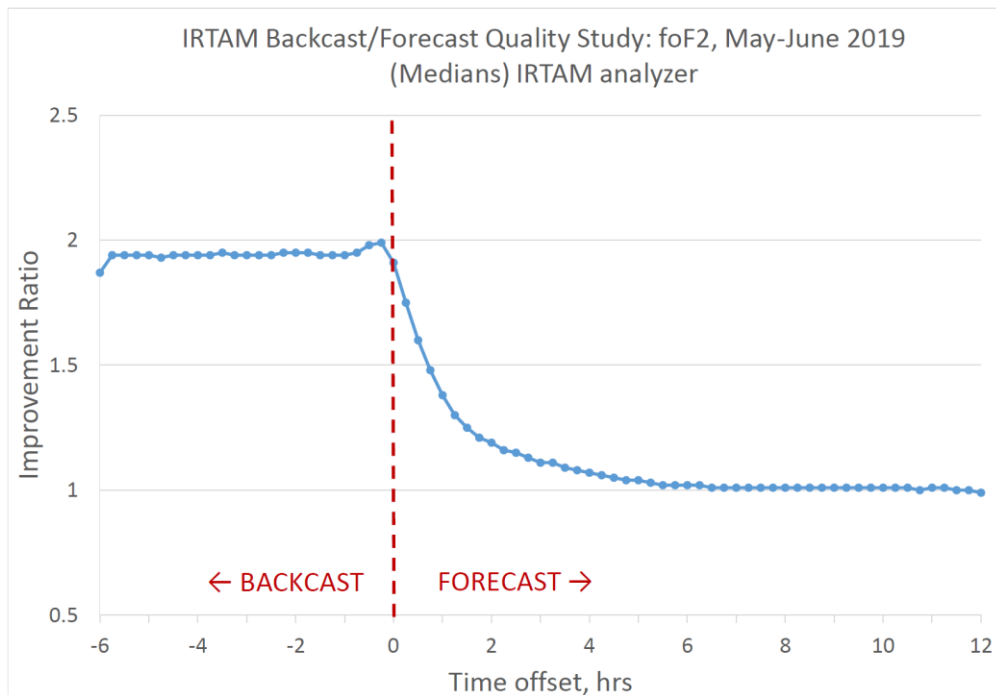
- Ryan Hamel
 - David Kitrosser
 - Steve Mendonca

Prelude



Ionosphere (*def.*): a major operational nuisance. © AFRL

Prelude (cont.)



- Ionosphere does not inform itself about its future state
- 4-hour old sensor data are useless
- 1-hour old sensor data lose 50% of their value

Outline

- RION “Instrument” **Suite** at UN ISWI
 - Review of its “weather monitoring” value
 - **Ionograms**: DIDBase with Portal and SAO Explorer
 - New: D-region specification
 - **IRTAM and GAMBIT**: Database and Explorer
 - HF Depression Analytics for ICAO
 - IRTAM maps of MUF(3000)
 - GAMBIT maps of Slab Thickness
 - **RayTRIX**: HF signal propagation modeling by raytracing
 - **TID Explorer**: detection and evaluation of TIDs
 - **SkyLITE**: plasma drift monitoring
- Natural Language Processing: a concept study for **forecasting** the ionosphere

RION is Home of Digisonde 4D



ADVANCES IN DIGISONDE DEVELOPMENT



Opening by Prof. Bodo W. Reinisch

University of Massachusetts Lowell
Environmental, Earth, & Atmospheric Sciences Department
Center for Atmospheric Research

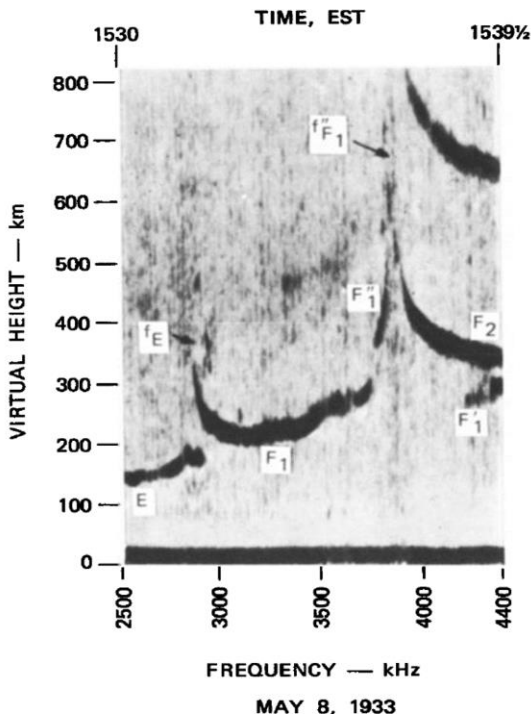


XI INTERNATIONAL DIGISONDE FORUM
30 APRIL TO 3 MAY 2007

- 1925: First ionosondes
 - Two models in UK and US
- 1936: Four ionosondes in the world
- 1957 (IGY): ~135 ionosondes
- 1969: First Digisonde
- Total ionosondes built: ???
 - Total ionosonde sites in NOAA: 231
 - so, maybe 500-600?
- 192 Digisondes built in Lowell; ~ 1/3 of world production

67 Digisonde 4D units built since 2007

Ionogram in 1933 and nowadays



Lowell Digisonde

foF2 5.97
foF1 N/A
foF1p N/A
foE 1.96
foEp 0.91
fxI 7.60
foEs 2.25
fmin 1.00

MUF 16.64
M 2.784
D 3000

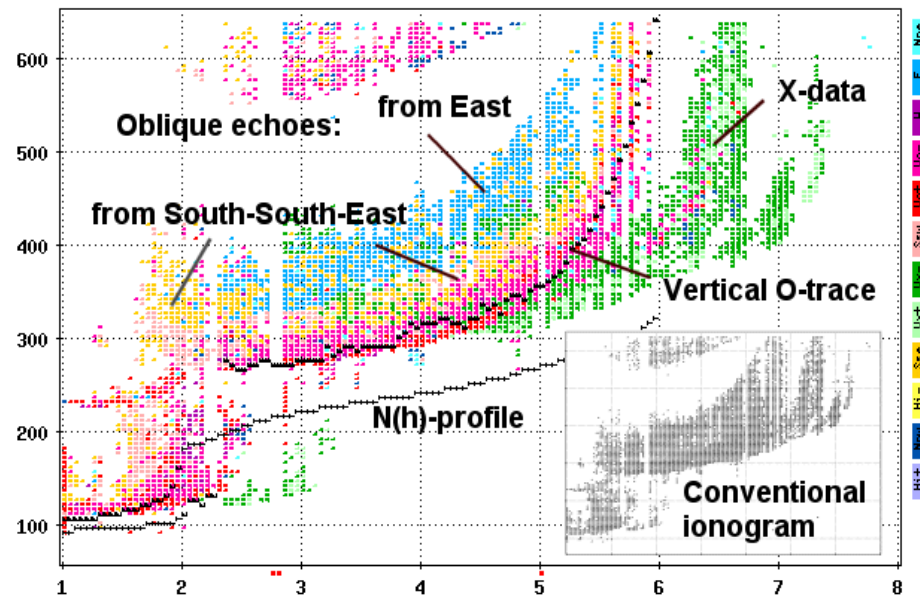
h'F 265
h'F2 N/A
h'E 110
h'Es 125

zmF2 326
zmF1 N/A
zmE 105
yF2 111
yF1 N/A
yE 15
B0 112.0
B1 2.26

C-level 2

Autoscaled
data

STATION YYYY DAY DDD HHMM P1 FFS S AXN PPS IGA PS
Tronso 2002 Apr-07 097 1916 MM 000-1 715 200 -0+ B2



	D	100	200	400	600	800	1000	1500	3000	[km]
MUF	6.7	6.8	7.0	7.4	7.9	8.7	11.0	16.6		[MHz]

Credits to: Theodor Gilliland, NBS, USA

Digisonde data courtesy of Chris Hall, UIT

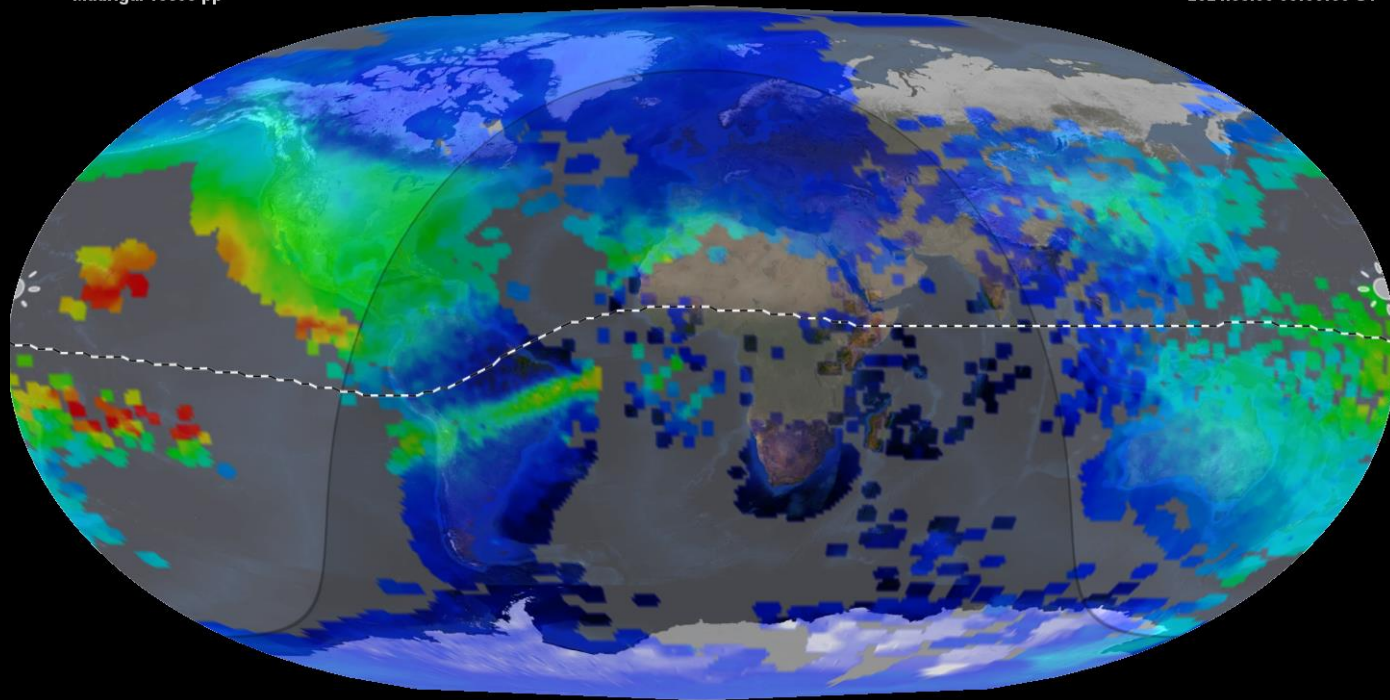
GIRO as of June 12, 2024



GIRO vs VTEC in CEDAR Madrigal

Madrigal 15895 pp

2024.05.06 00:00:00 UT



Not a real-time VTEC

Map: VTEC, TECU



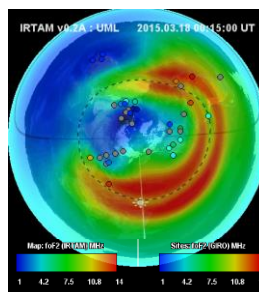
1 25.8 50.5 75.2 100

VTEC data courtesy of Anthea Coster, MIT Haystack Observatory

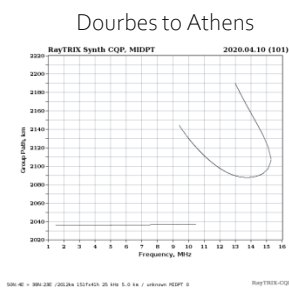
UML Realistic Ionosphere



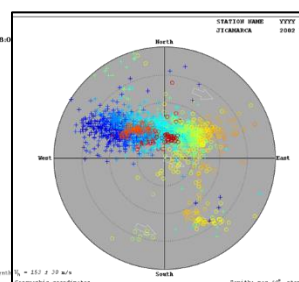
GIRO
including DIBase



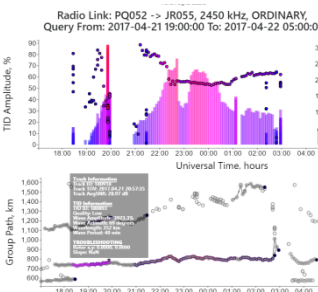
GAMBIT
including IRTAM 3D



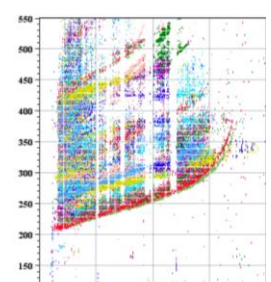
RayTRIX



SkyLITE



TID Explorer



IDI

0. Measurements

1. Global Weather Modeling

2. HF Signal Raytracing

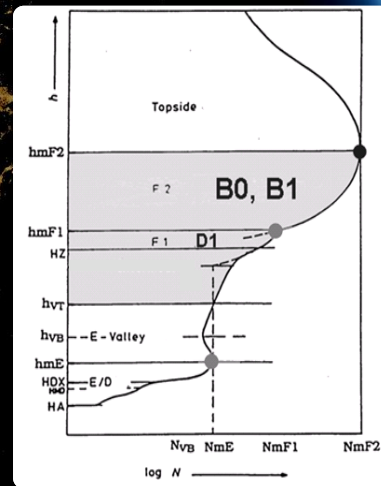
3. Plasma Drifts

4. TID Warnings

5. Disturbance Indicator

1. Real-Time IRI

- Real-Time IRI Task Force
 - founded in 2009
 - concept: tweak IRI using available observations
 - To make a good model better
 - Not necessarily an assimilation
 - Real-time IRI" simply refers to application to space weather
- IRTAM is IRI-based Real-Time **Assimilative** Model
 - A GRAY BOX approach (physics-informed)
 - IRI background is responsible for capturing underlying geophysics with solar, seasonal, and geomagnetic field dependencies
 - IRTAM merely **adjusts** IRI background 1-DITL
 - IRTAM **represents observations** faithfully
 - IRTAM **gradually returns to the background** over no-sensor regions

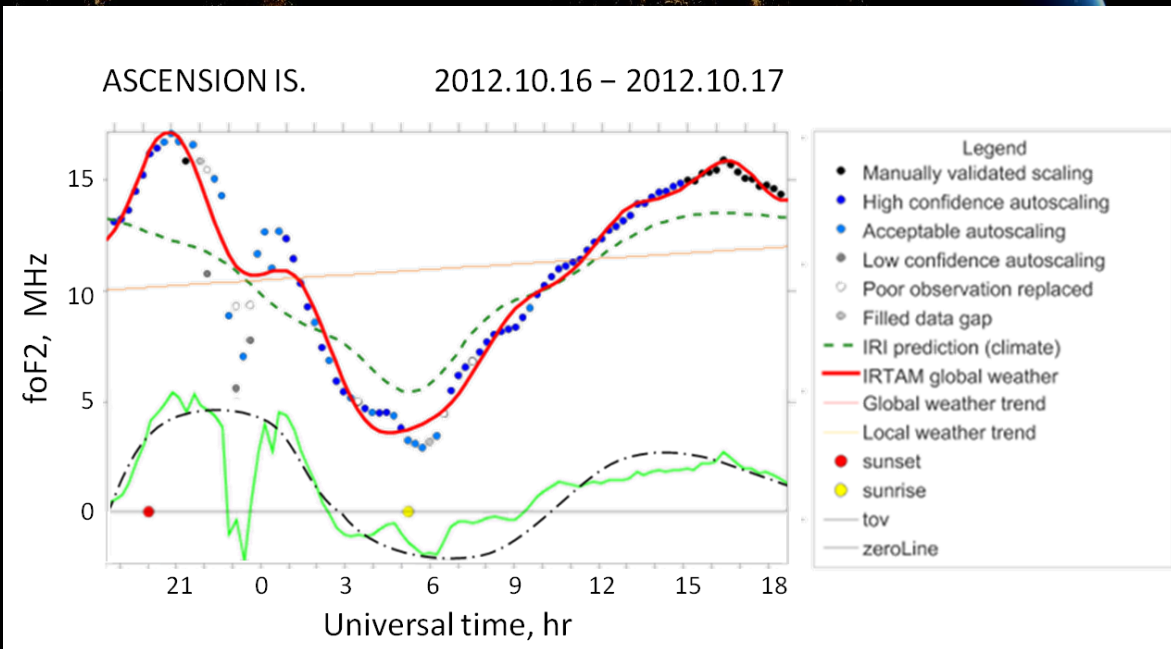


The vertical profile of plasma density:

16 "anchor" parameters



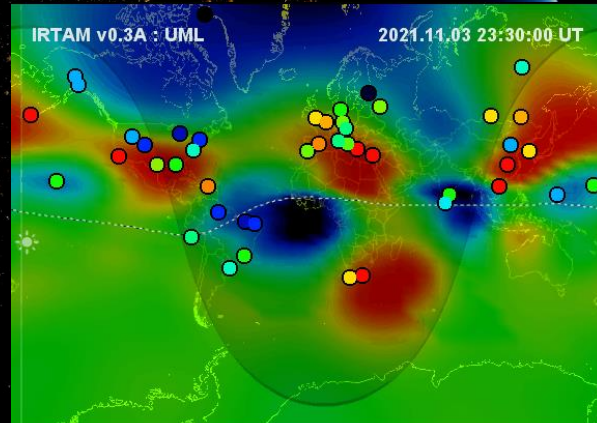
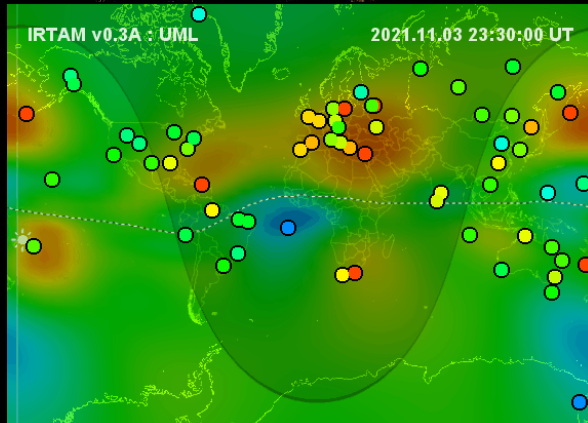
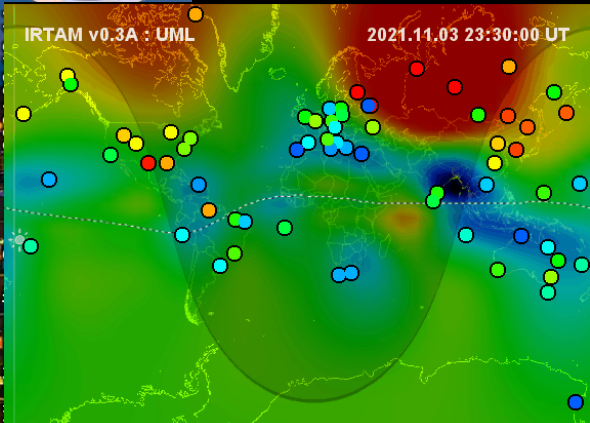
- NECTAR is not quite a Kalman filter
 - Significantly 4DDA
 - 24 hours of previous anomaly as observed at sensor sites
 - And then use diurnal harmonics as these anomalies
- Suppose a GIRO ionosonde detects a significant 12-hour deviation Δ . Question: how far from the site this correction shall extend?
 - How about 4-hour harmonic?



Nov 4, 2021 Storm, Kp ~ G3..G5

GIRO ionosondes only, IRTAM 3D assimilative model

NOT A SIMULATION



Δ foF2

Δ hmF2

Δ B0

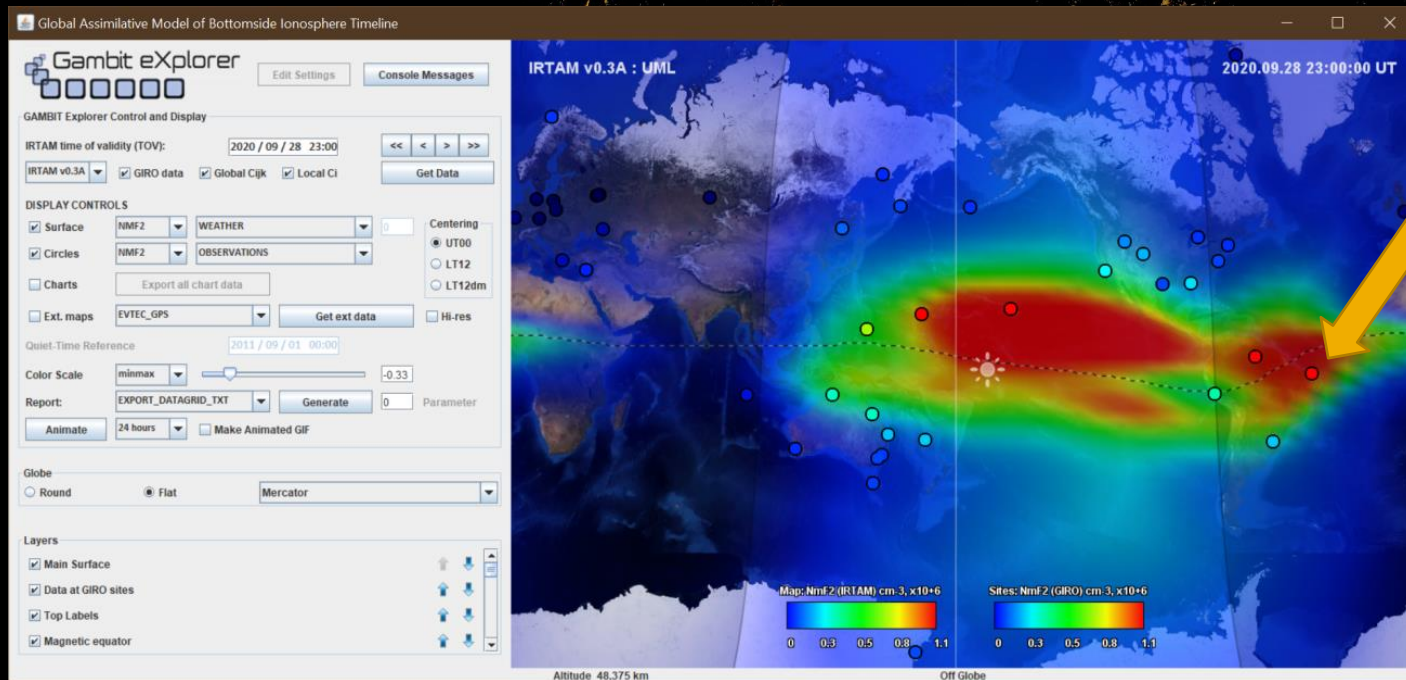


"Anomaly map" = Percent Deviation from Quiet Conditions

Free for academic use: GAMBIT Explorer UserApp 1.0A
Download from <https://giro.uml.edu/GAMBIT/>

GAMBIT EXPLORER

ACCESS TO IRTAM DATA

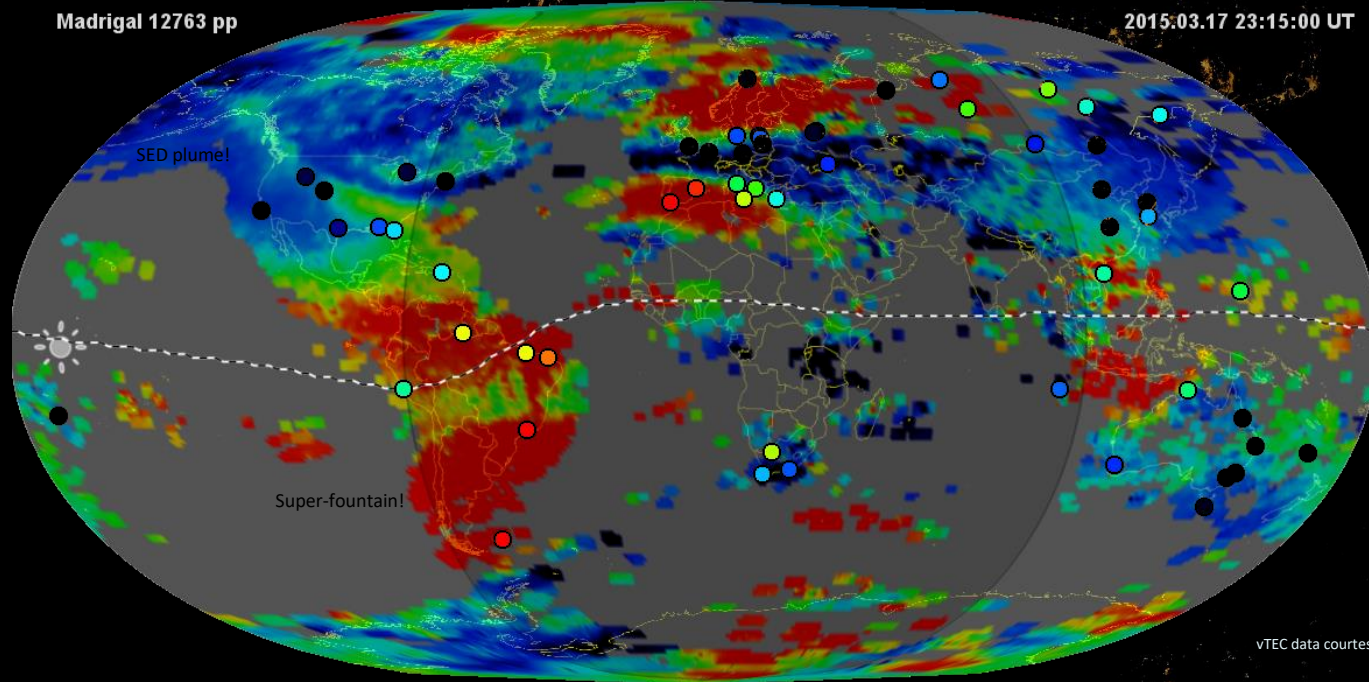


CLICK FOR
DETAILS

+ source code to integrate IRTAM coefficients from GAMBIT database with user applications

Anomaly maps by IGS and GIRO

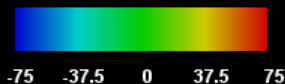
St. Patrick storm of March 17, 2015 23:15



Gambit eXplorer
giro.uml.edu/GAMBIT

VTEC data courtesy MIT Haystack Madrigal Repository

Sites: NmF2 (GIRO-IRI)/IRI %



Map: Delta-VTEC, %



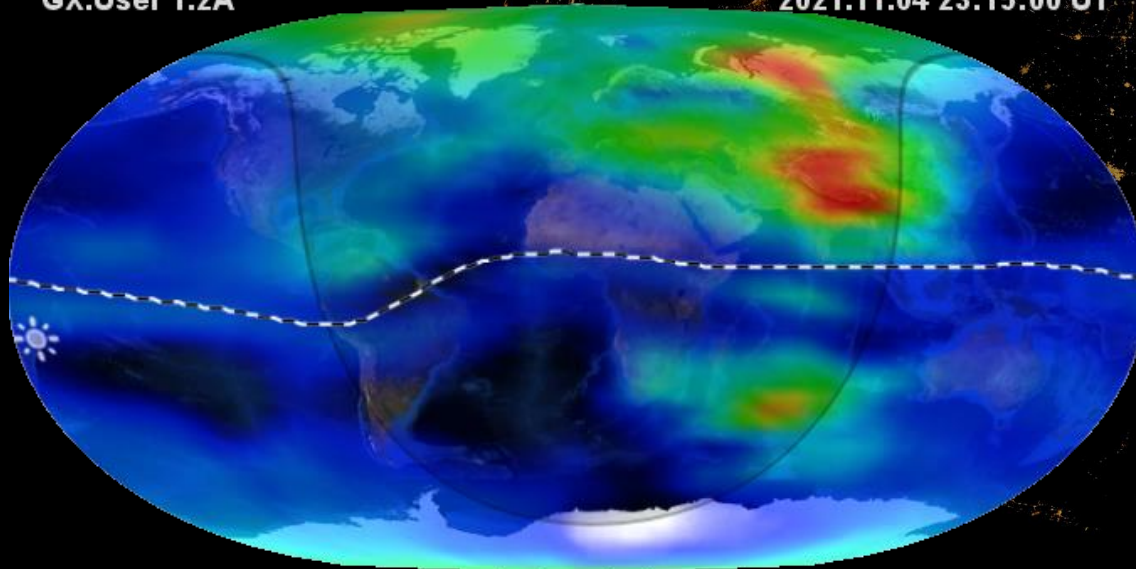
Δ NmF2 @ 60 GIRO sites

Δ VTEC @ 6342 GNSS sites

Slab Thickness Climatology

GX.User 1.2A

2021.11.04 23:15:00 UT



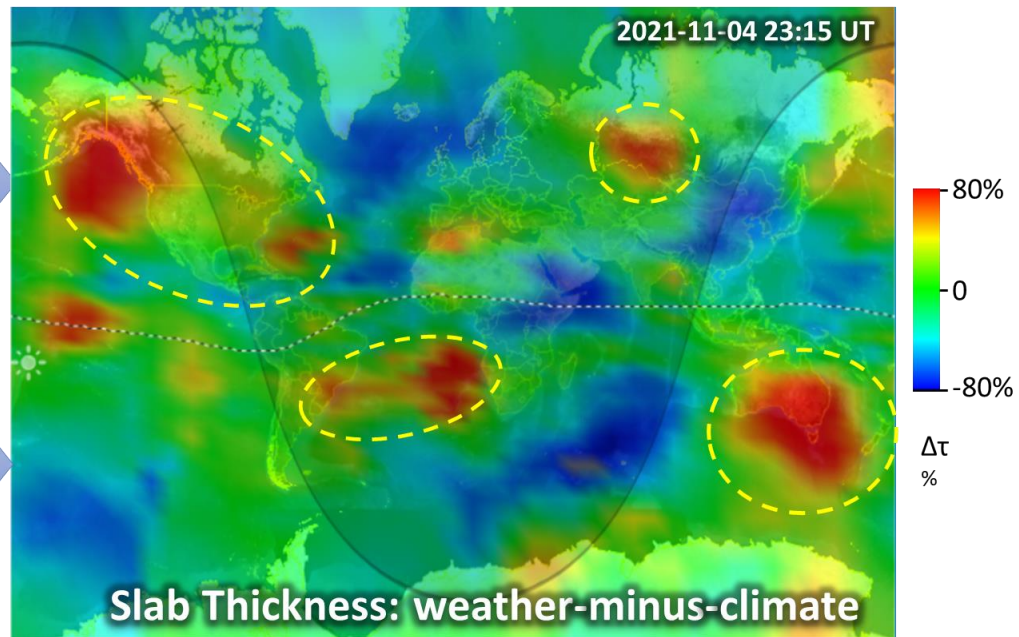
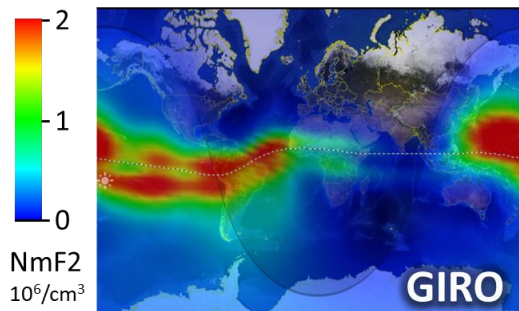
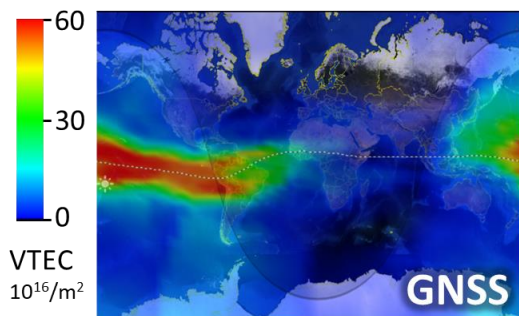
NmF2: IRI foF2 model (climate)
VTEC: IGS 30-day median VTEC

[Fron *et al.*, 2020]

Map: TAU-average km



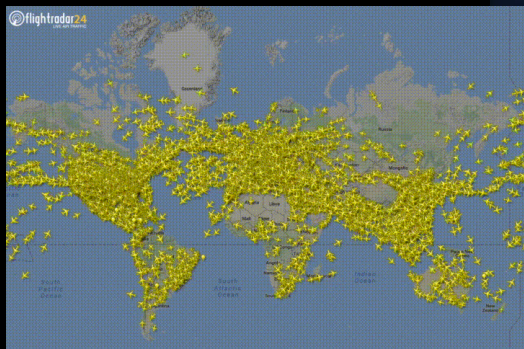
Real-time Anomaly Slab Thickness



2. RayTRIX CQP



~5 sec running time



RayTRIX
Ray Tracing through
Realistic Ionosphere Explorer

OBLIQUE TRACE SYNTHESIZER

Choose station pair or
type coordinates below.

Station Pair PQ052 to JR055

Transmitter Coordinates:

50 N (-90..90)
14.6 E (0..360)

Receiver Coordinates:

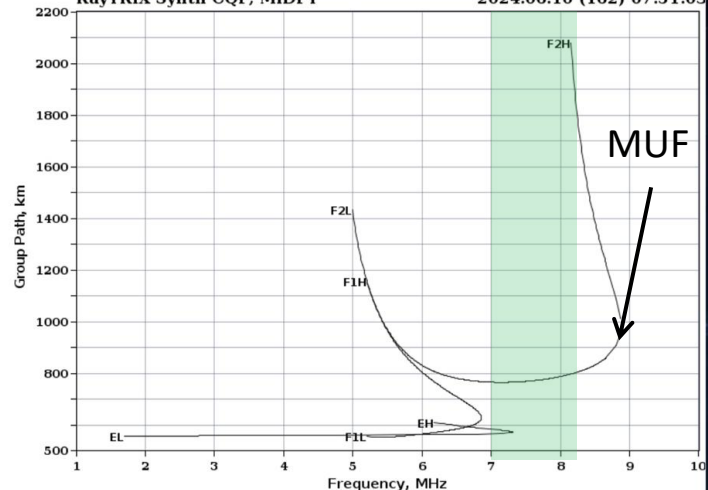
54.6 N (-90..90)
13.4 E (0..360)

☒ Use Current Date and Time

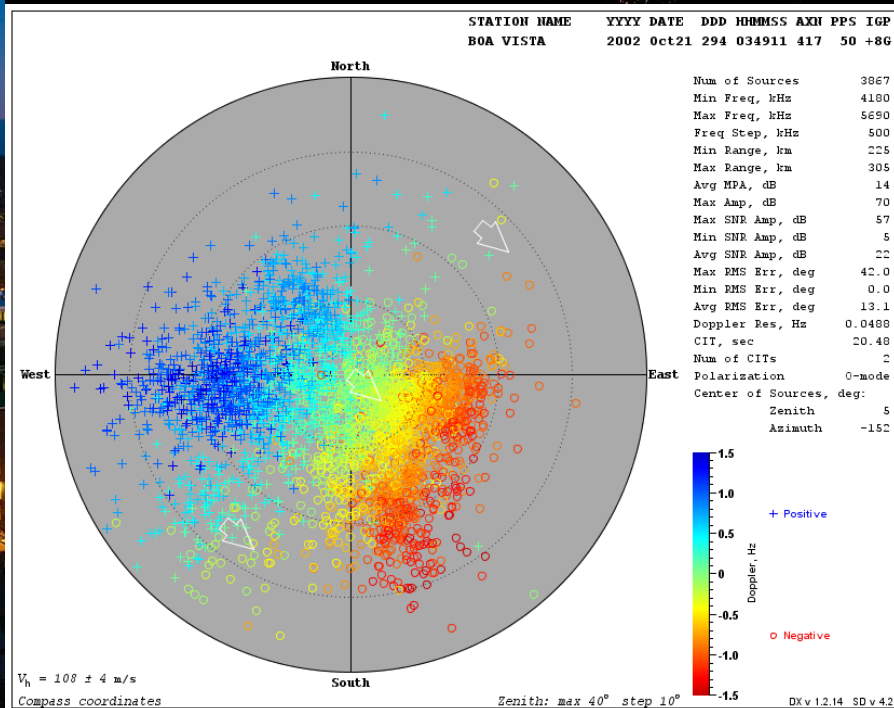
Date mm/dd/yyyy

RayTRIX Synth CQP, MIDPT

2024.06.10 (162) 07:51:03

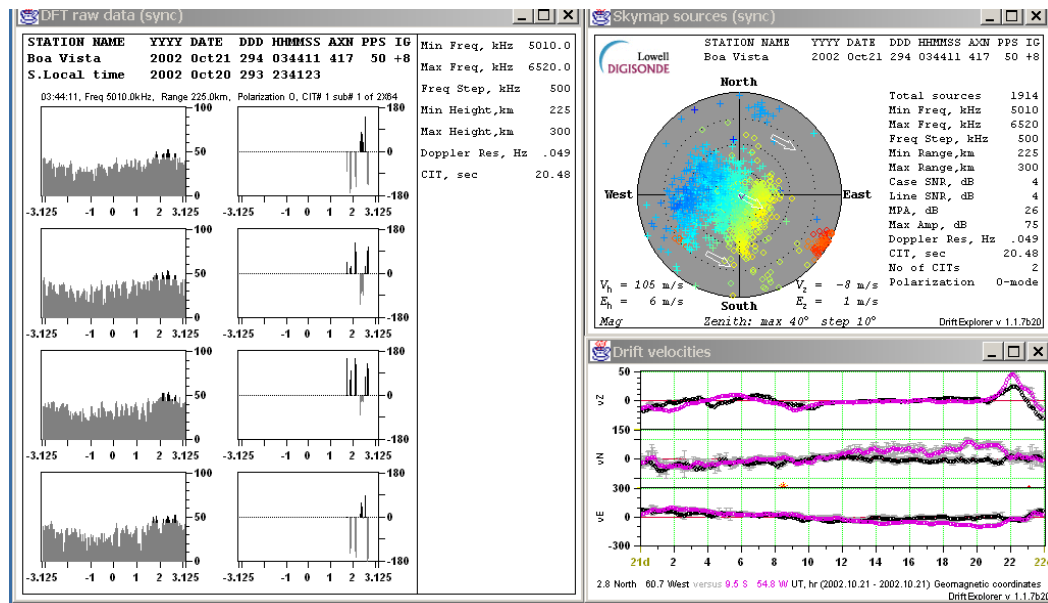


3. Doppler Skymapping of Ionosphere



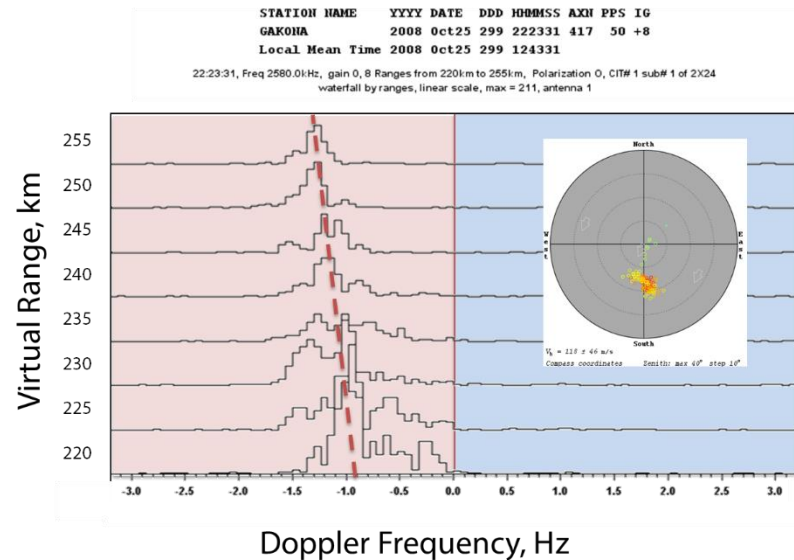
- Digisonde illuminates all sky above the station
- If the ionosphere is flat and undisturbed, the only echoes will come from the zero zenith in the skymap center
- Off-vertical echoes are possible if plasma irregularities exist of the right scale and orientation
- Doppler frequency analysis allows determination of the plasma density drift vector

Plasma Drift and SkyLITE



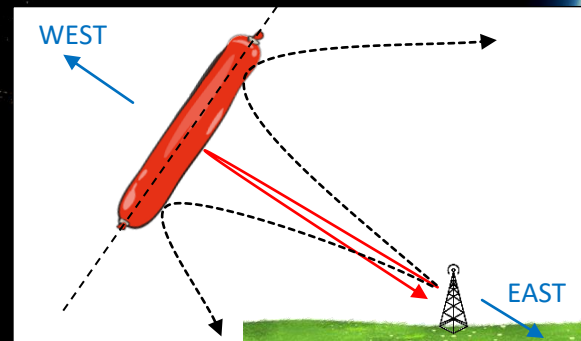
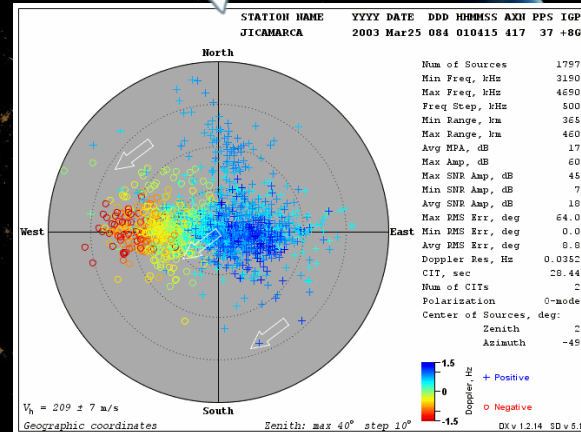
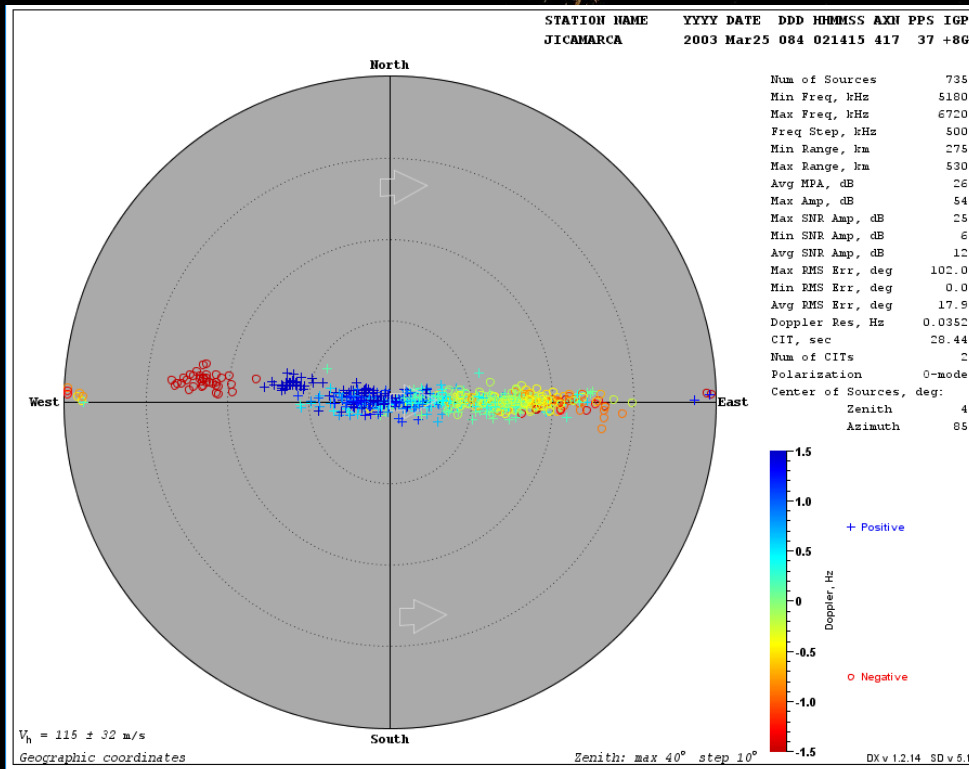
4-channel data

Skymap & Vector Drift Velocity



HAARP Heating Experiment

Sausages in the Sky?

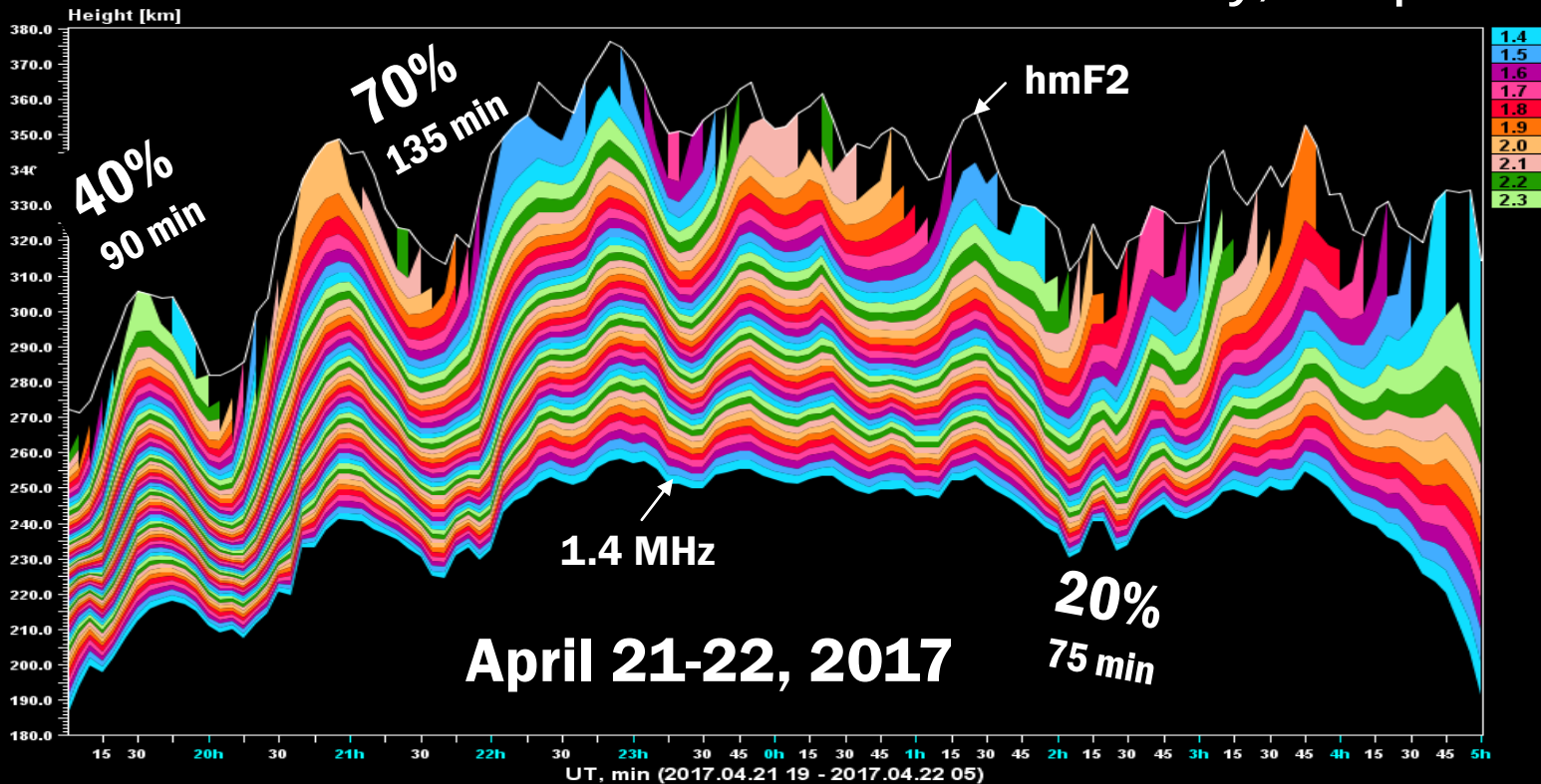


Jicamarca skymaps courtesy of Oscar Alfredo Veliz Castillo, JRO

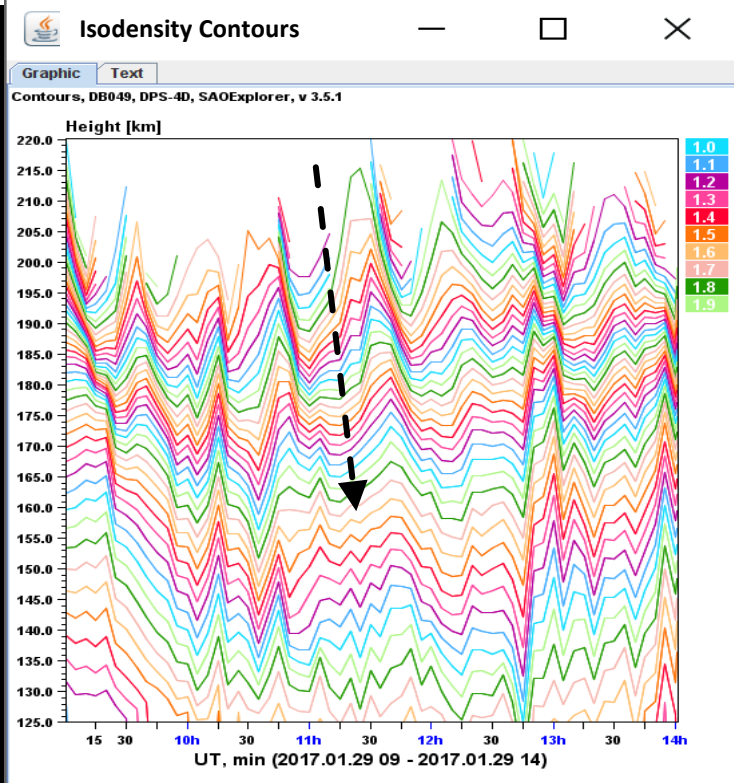
4. TID Detection

Ebro Observatory, Roquetes

Contours, EB040, DPS-4D, SAOExplorer, v 3.5.1



HF versus other TID sensors

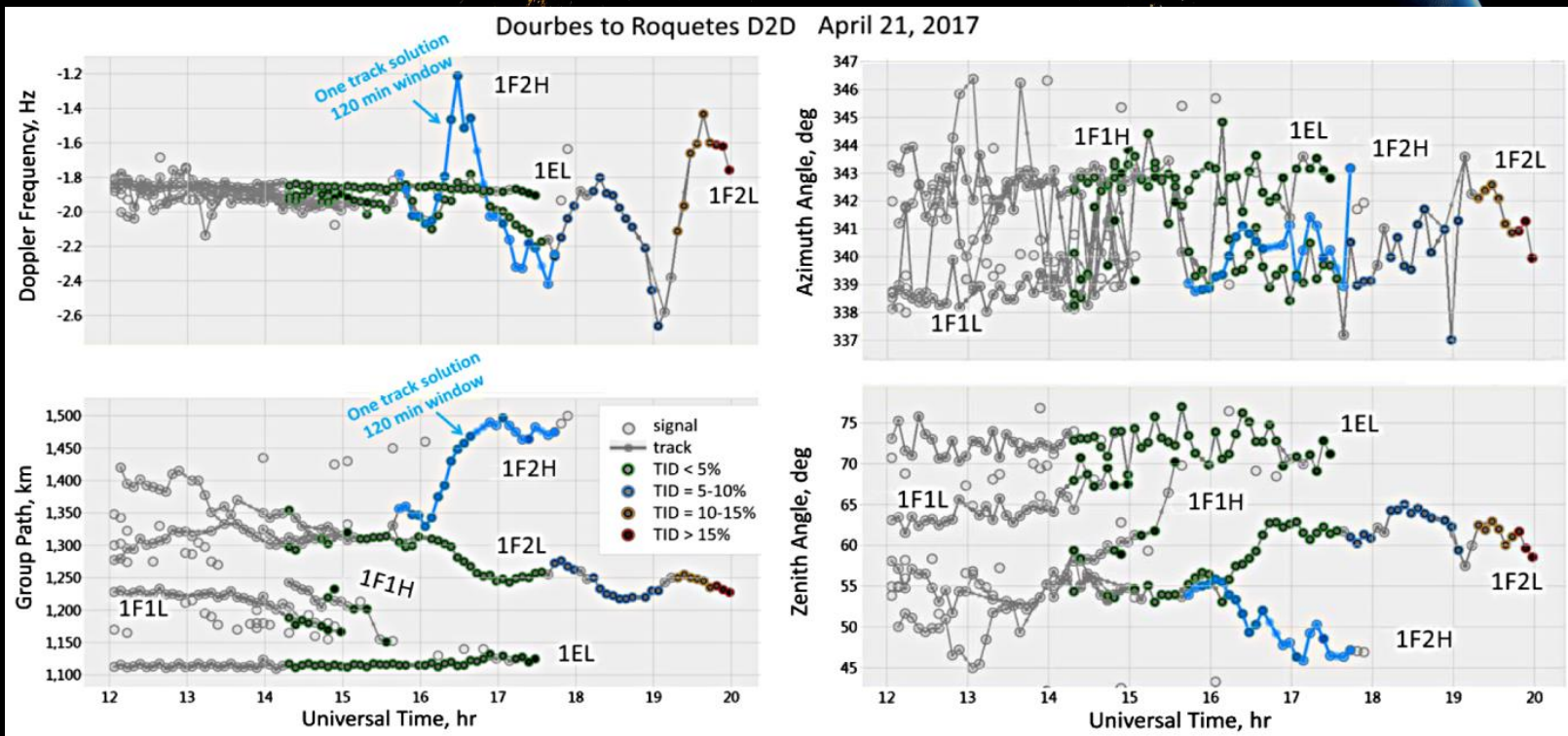


Data courtesy Tobias Verhulst, RMI

- **1D Altitude profile of TID**
 - Detailed view of propagation along z-axis
 - Pin-point to particular altitude region
- **Sensitivity**
 - Detection of a 5% TID vs underlying density
 - “TID are always present” < 1%
- **Direction, Velocity, Wavelength**
 - HF-TID method
- **Direct measurement**
 - Static platform (no motion effects)
 - No slant-to-vertical transformation needed
- **24/7 operations with automatic intelligent system analysis**
 - Replicate human intelligence

Automatic Signal Tracking

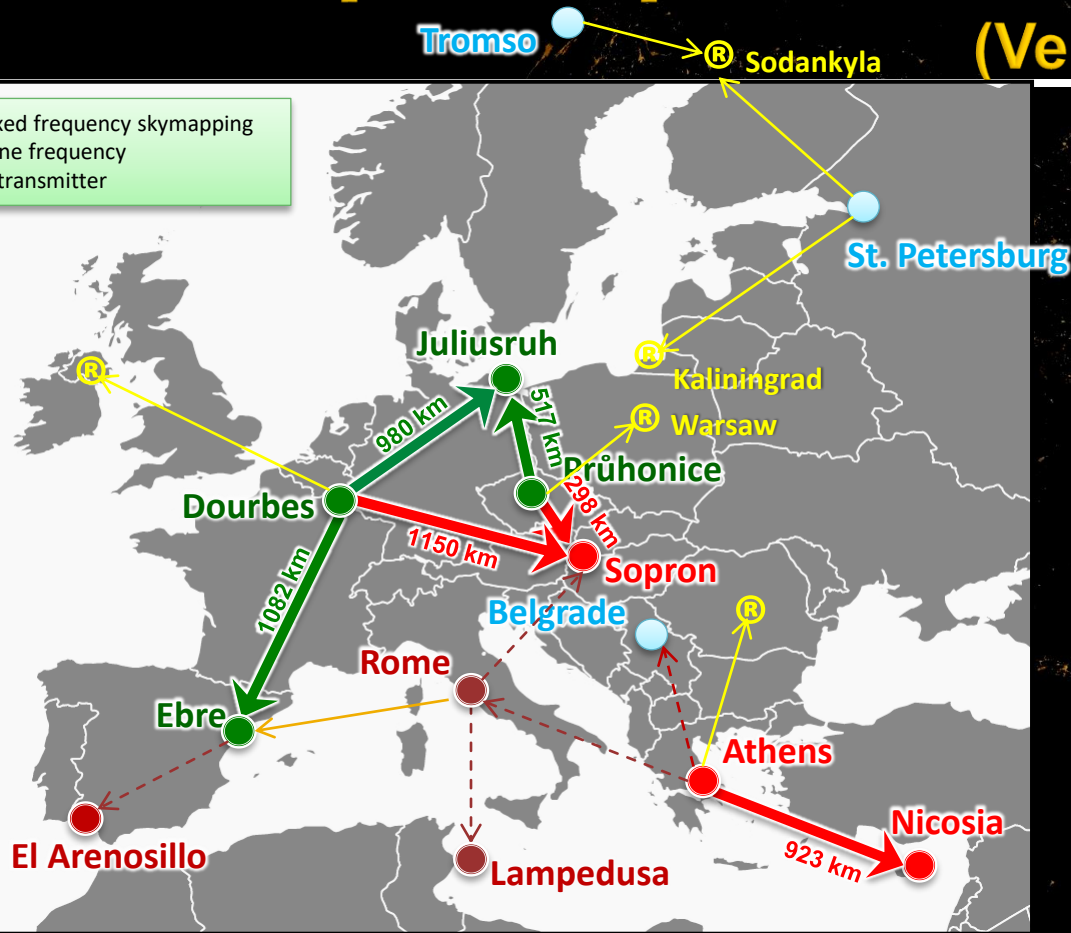
Dourbes to Roquetes link (1082 km) ["southern link"]



European pilot D2D network

(Verhulst et al., 2017)

TID tracking: D2D fixed frequency skymapping
One transmitter – one frequency
One receiver – one transmitter



- ➔ Phase I links
- ➔ Phase II links
- Upcoming DPS4D sites
- Potential DPS4D sites
- Ⓜ Possible DPSR sites



Forecasting Ionosphere

Using Natural Language Processing (NLP) approach

“Triggered” storm option in IRI

$\Delta N_m F_2$



quiet

storm
onset
time

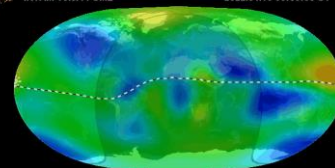
quiet-time behavior

remembered “average” storm behavior
(adjust 1024 expansion coefficients)

time

IRITAM v0.3A : UML

2022.04.10 00:00:00 UT



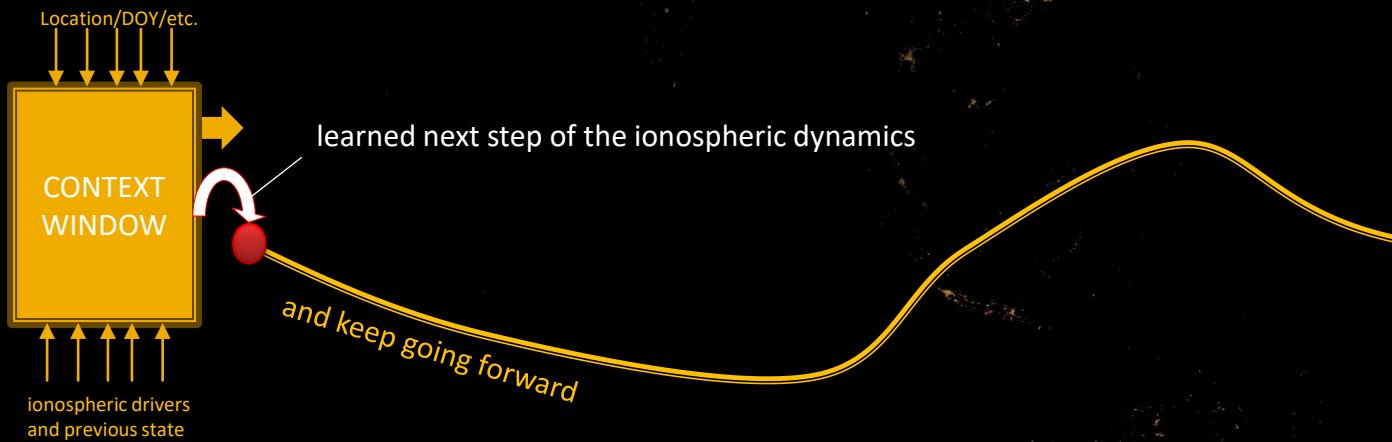
Forecast by analogy to an average “anomaly” storyline

Next: Library of the storm storylines

instead of the “average storm timeline”

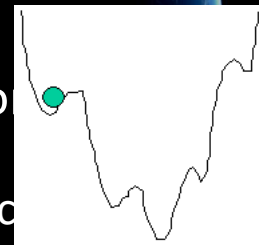
- Instead of an “average” storm, keep a library of previous storylines of $\Delta N m F 2$ anomalies
 - NOT to build a least-square regression on 1024 unknowns
 - NOT to build a back-prop feed-forward NN with 1024 outputs
 - Just memorize them, *cleverly*
 - To forecast, **look for the most relevant storm $\Delta N m F 2$ in the library**
- Each library storyline must be relevant **in the context** of the ionospheric drivers
 - i.e., not just replay of the storm using one “trigger”
 - Need to build them against an external storyline of events in the heliospace and geospace
- Need good ideas for
 - The storm library
 - Search-and-retrieval algorithms
 - *Tweaking the library copy to current conditions*

"ChatGPT" for capturing the context

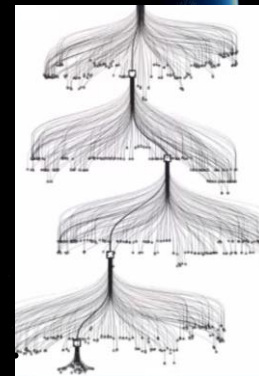
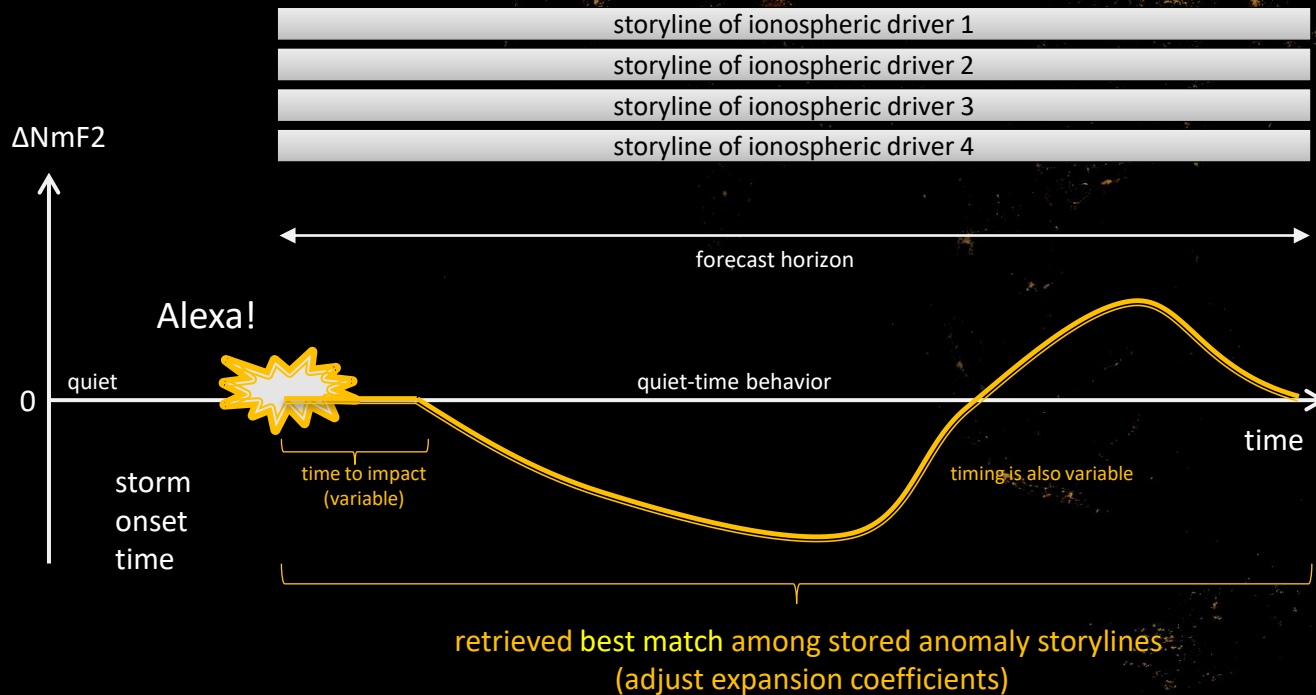


Alexa, play Yesterday by The Beatles

- “Yesterday” is interpreted in the context of “play”
 - Not a reference to time
 - Fetched from the database of song titles
 - The song is played to the asker
- **DEEP LEARNING**: multi-layered recurrent (feed-back) network topologies
 - Support interpretation of subelements **in the context** of other context
 - Seems matching to the idea of interpreting ionospheric dynamics in the context of the external forces acting on it
 - Context: reports of ongoing Sun-Earth activity
 - Output: ionospheric dynamics fetched from the historical record database
 - What is different? Deep Learning of how activity processes interplay

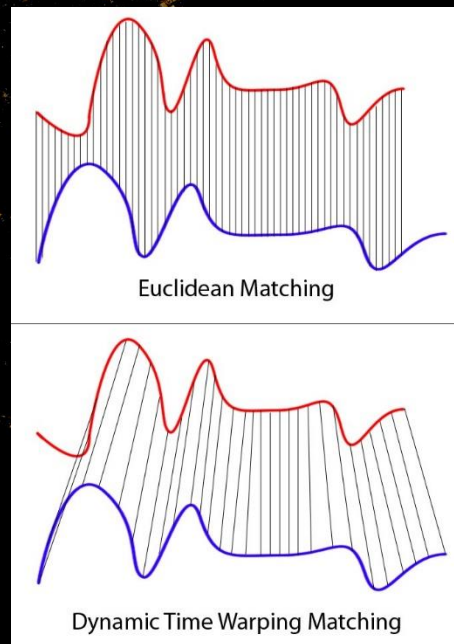


Concept of the “Alexa” storm options

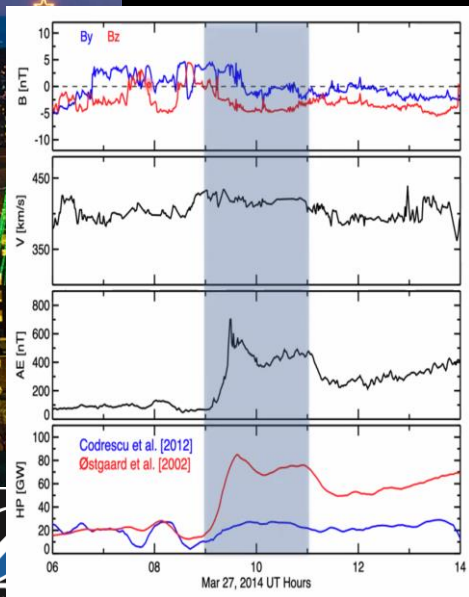


Dynamic Time Warping (DTW)

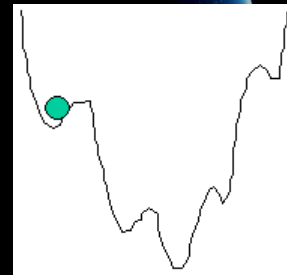
- Library-provided storm storyline of the ionosphere needs adjustment for the driver storyline
 - DTW finds a similarity between 2 storylines:
 - actual (red)
 - library (blue)
 - Assumption: driver storylines is indicative of *how different* the actual storm timing is from the library copy
 - Detected time warping is later applied to the library $\Delta N m F2$ to correct for **actual-vs-library timing**



Associative memory for partial driver info



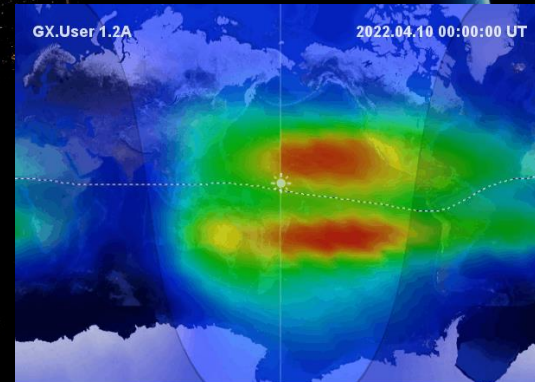
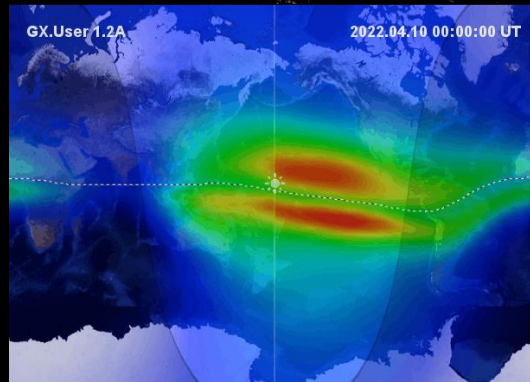
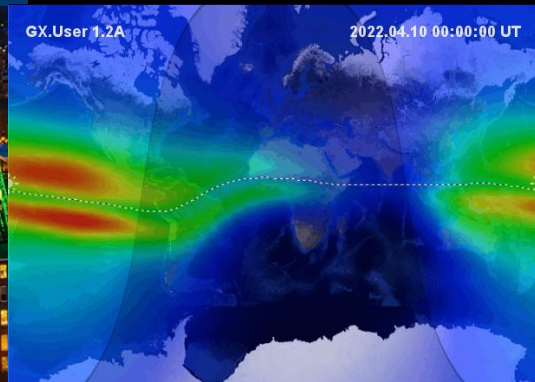
- Real-life: driver timelines are available only partially after the storm commencement
 - **Associative memory** for restoring the full timeline from its fragment
 - Based on the recurrent feed-back NN
 - Used for recognition of **hand-written text**
 - fragmentary, distorted pattern is provided
 - Memory associates the pattern with one of the [previously stored] alphabet
 - Used for **image imputation**
 - Partial pattern is filled using identified closest match
 - **Correct shape recognition is improved with time** as a greater fragment of the driver storyline become available
 - Especially, the amplitude of perturbation is relevant



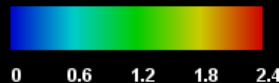
Tricks to standardize storms

- Standard timing of library storylines with **DTW** upon retrieval
- Switch to local time (TBR)
 - Are anomalies corotating or LT-fixed to the Sun?
- “Demagnetization” of the library ionosphere storylines
 - Transform geomagnetic poles to geographic poles reference
 - Use **modip** transformation
 - Very common in modeling the ionosphere
 - Then the storyline is re-magnetized using current geomagnetic configuration
 - Using IGRF

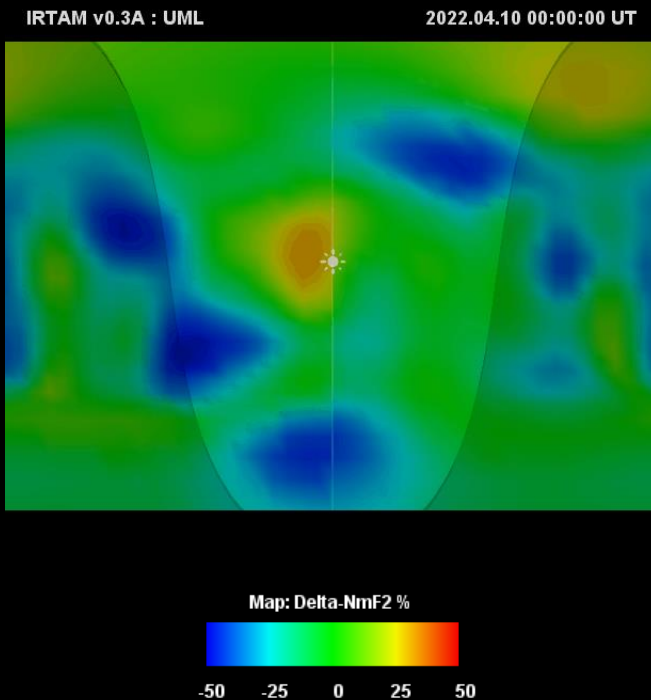
Trick: Remove Earth Rotation



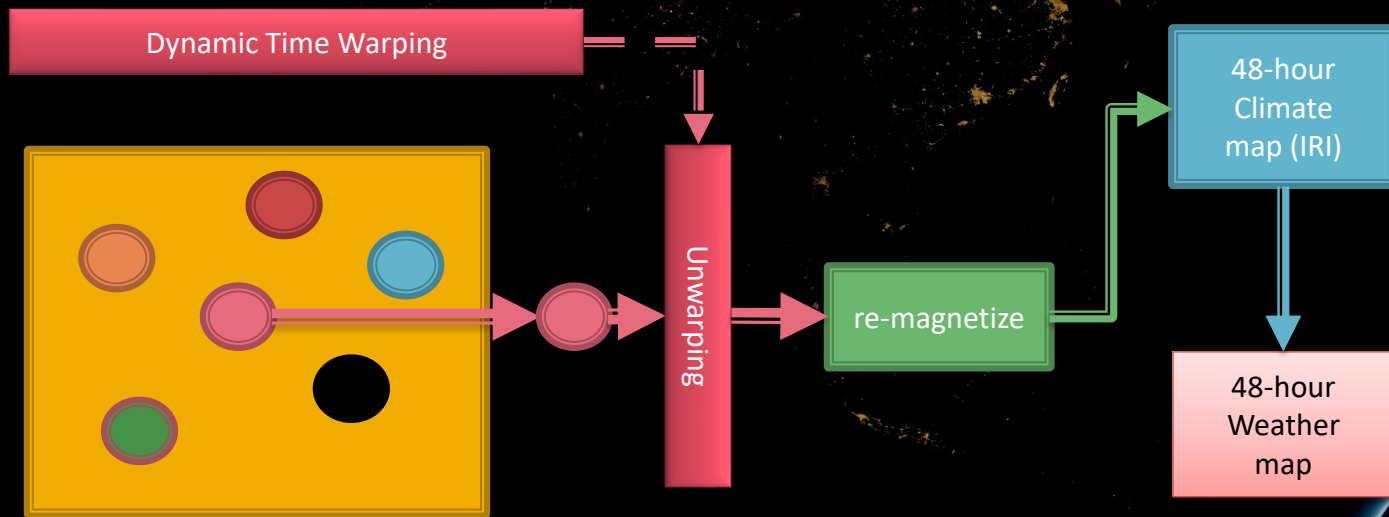
Map: NmF2, cm-3, $\times 10^6$

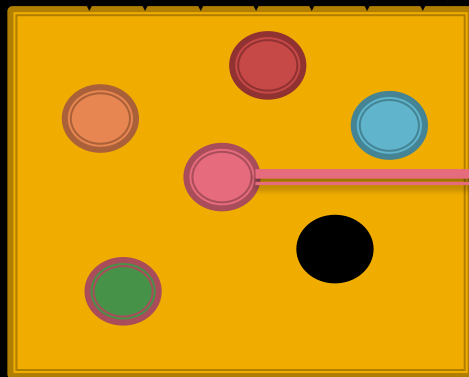


1 Day History to Store in Historical Database; this is still a grand challenge



1024



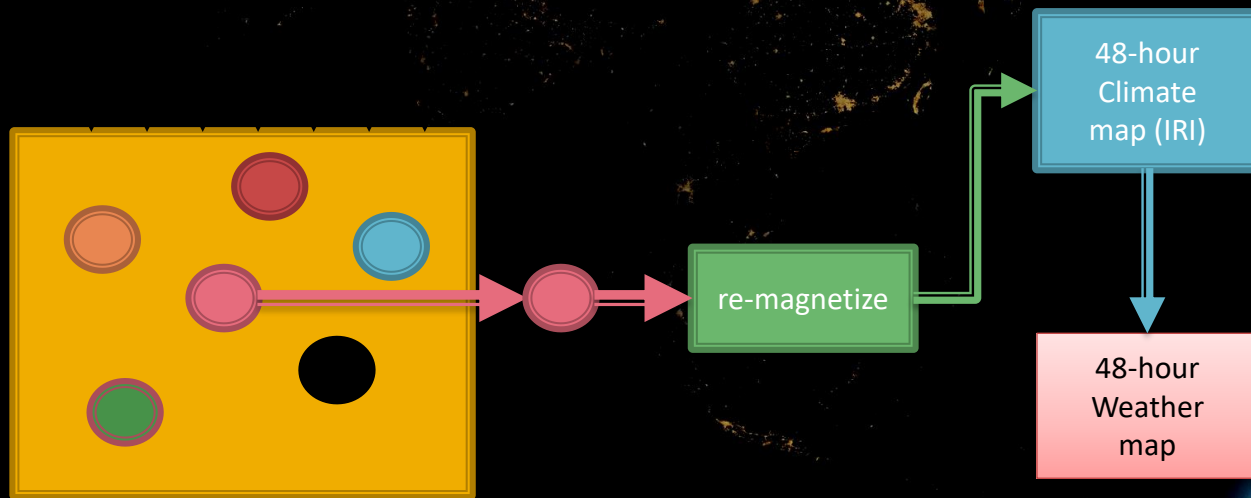


re-magnetize

24-hour
Climate
map (IRI)

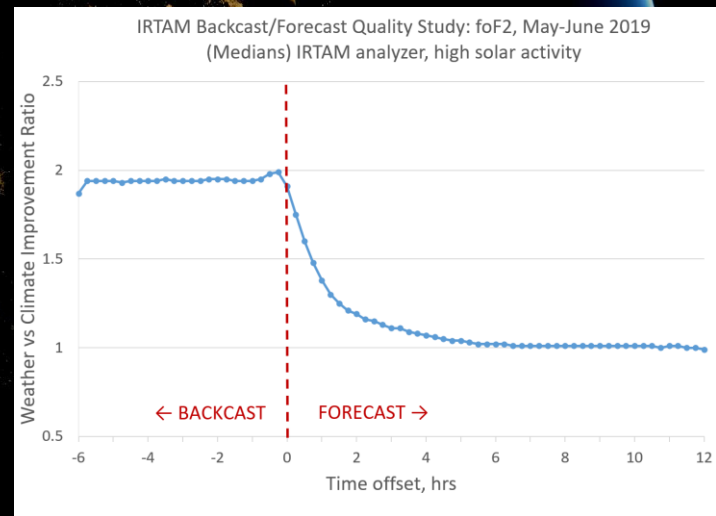
24-hour
Weather
map

Forecasting by context-driven memory (2)



Capturing Context of Ionospheric Dynamics

- Ionosphere: immediate response to external forcing
 - Thus its current conditions do not inform future states
- Need to use **timelines** of **all** external drivers as context
 - Cannot be just one instant driver (e.g., Kp=6)
 - Driver dynamics is matched (paired) to the ionospheric storm dynamics
 - Across complete forecast timeline from onset to stop
 - Important: which driver is relevant out of the set? (Deep Learning helps; *inductive bias*)
 - **Storm vocabulary:**
 - capture standard storm timelines
 - not 1024 variables, but much less
 - then detect their different timing realizations
 - Natural speech example
 - The same word said slowly or quickly
 - Dynamic time warping



Natural Language Processing as DTW example

- Analogous to Sound/Syllable recognition
- Custom Language to describe storm progression

