



GNSS Space Application in Turkey

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- Orbit Estimation
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Mission Flow

Application

Mission Flow

Use Cases

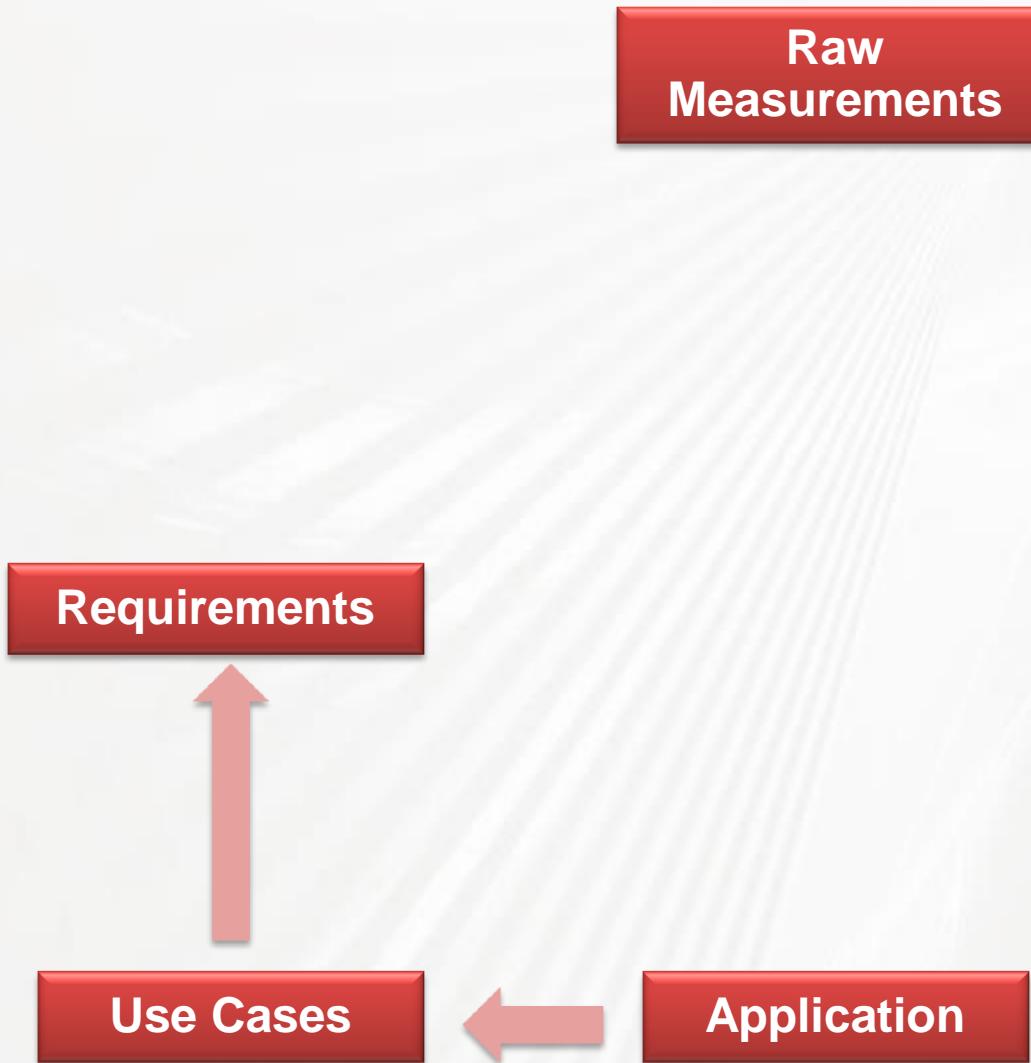
Application



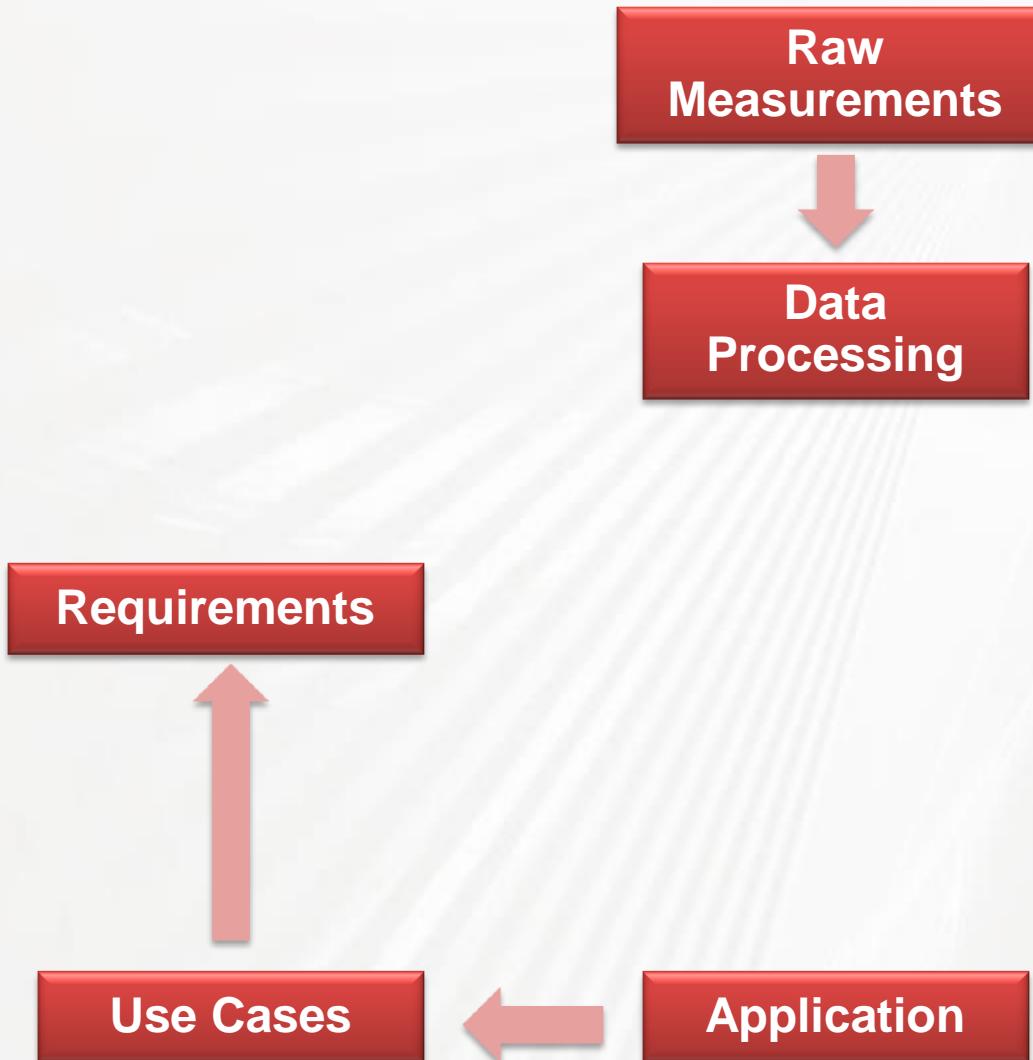
Mission Flow



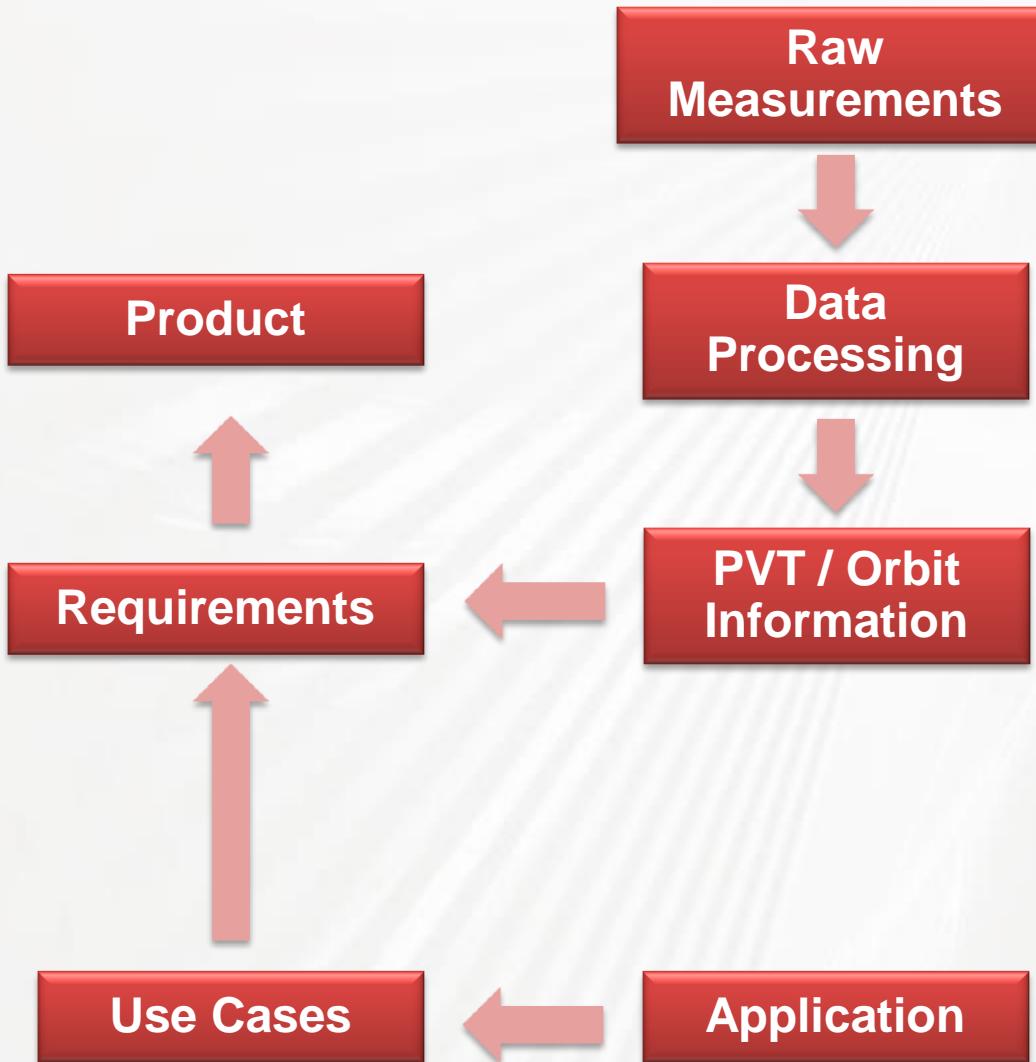
Mission Flow



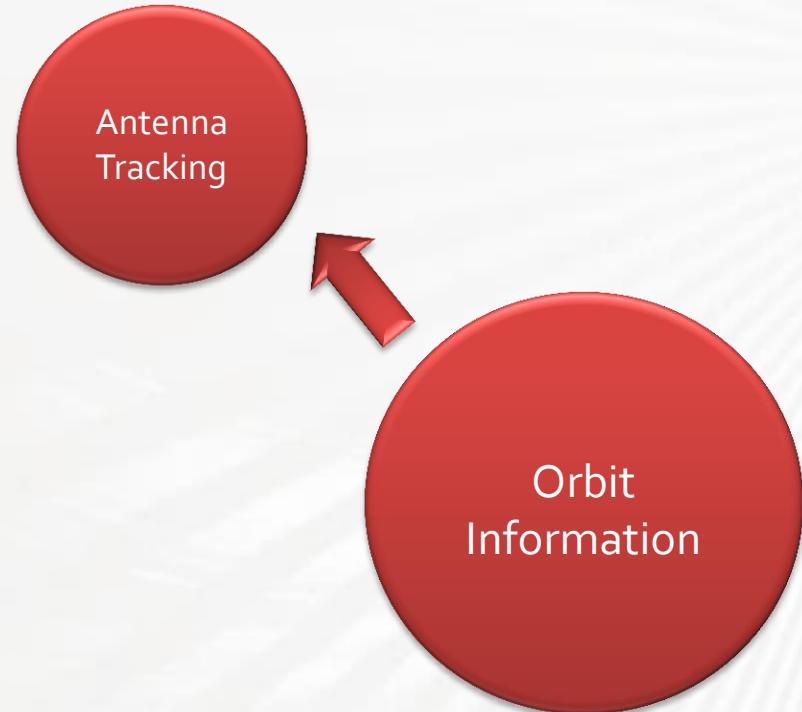
Mission Flow



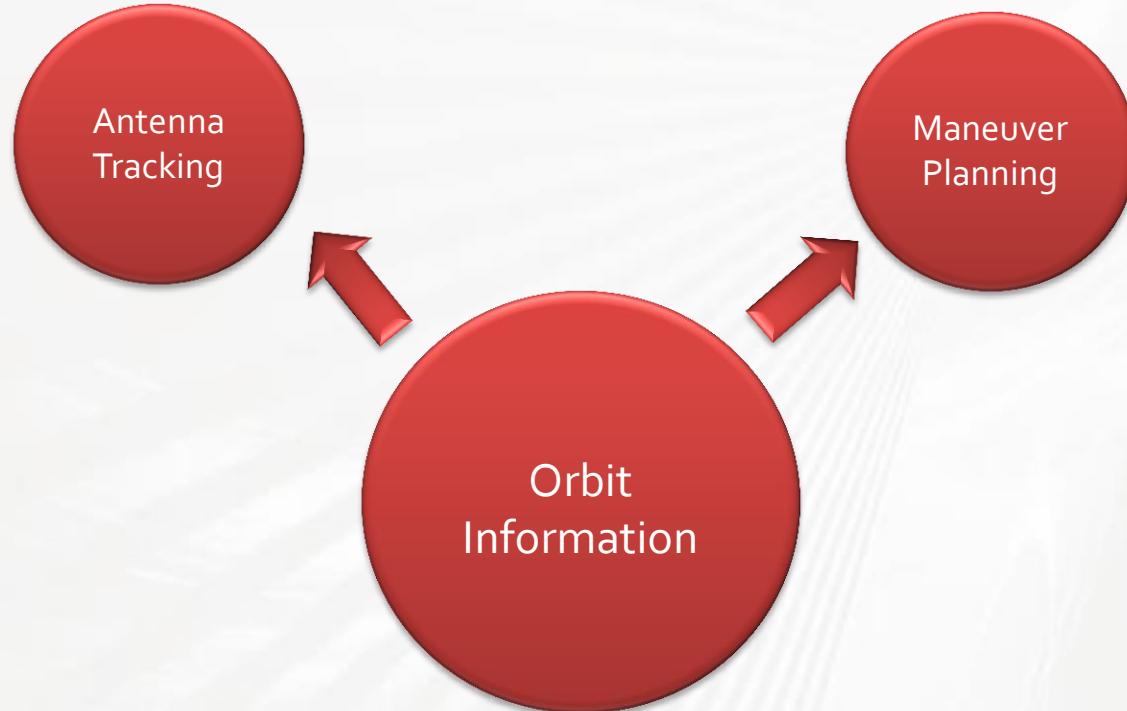
Mission Flow



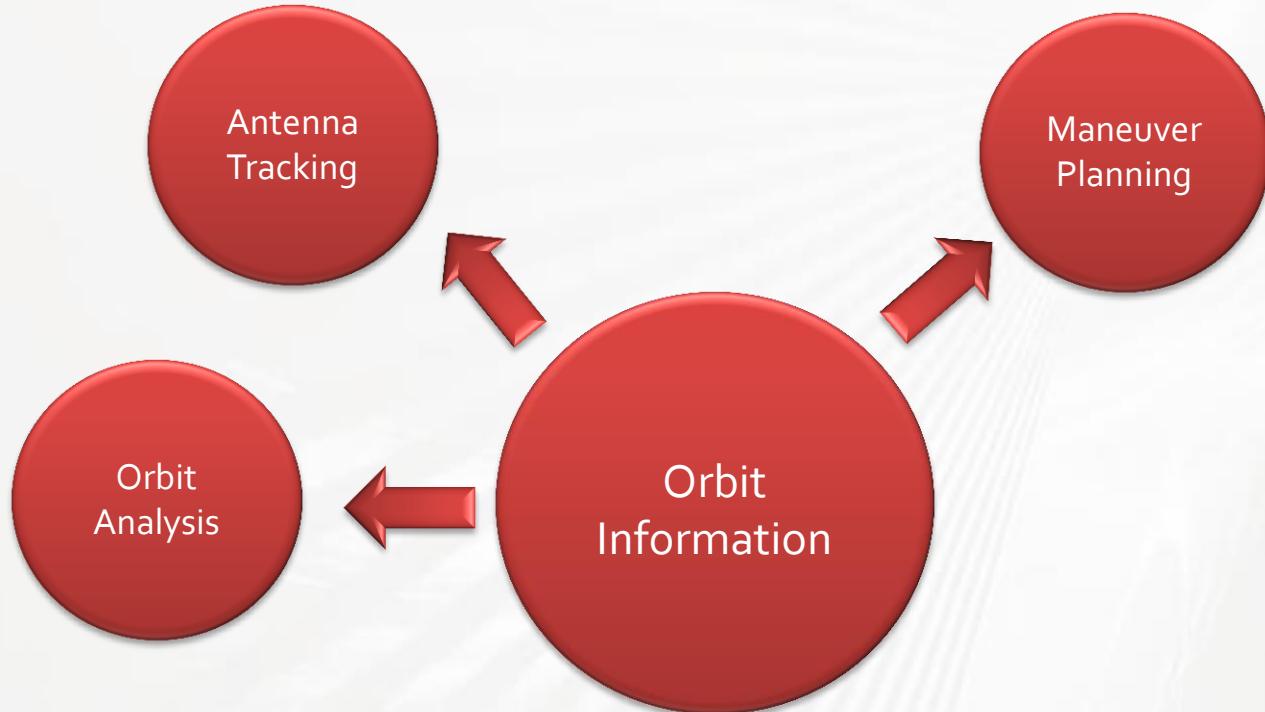
Use-Cases



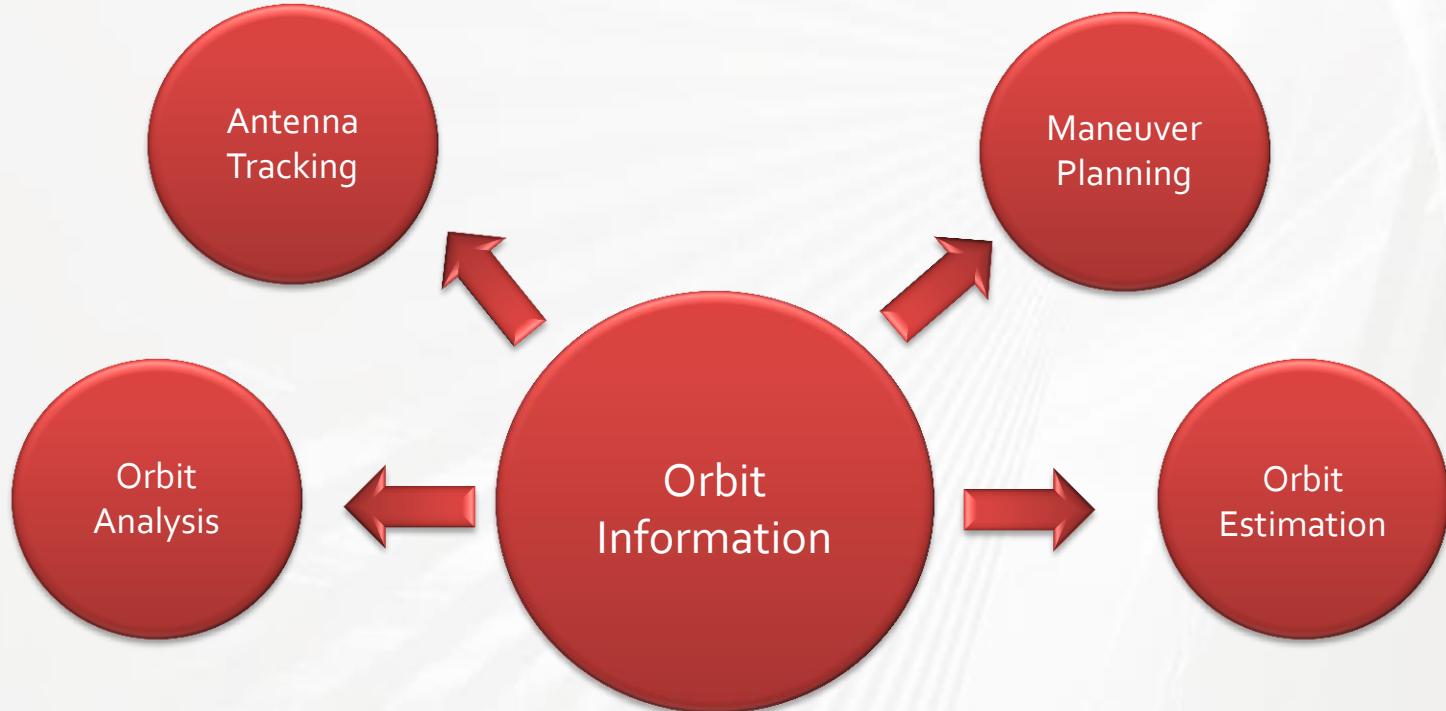
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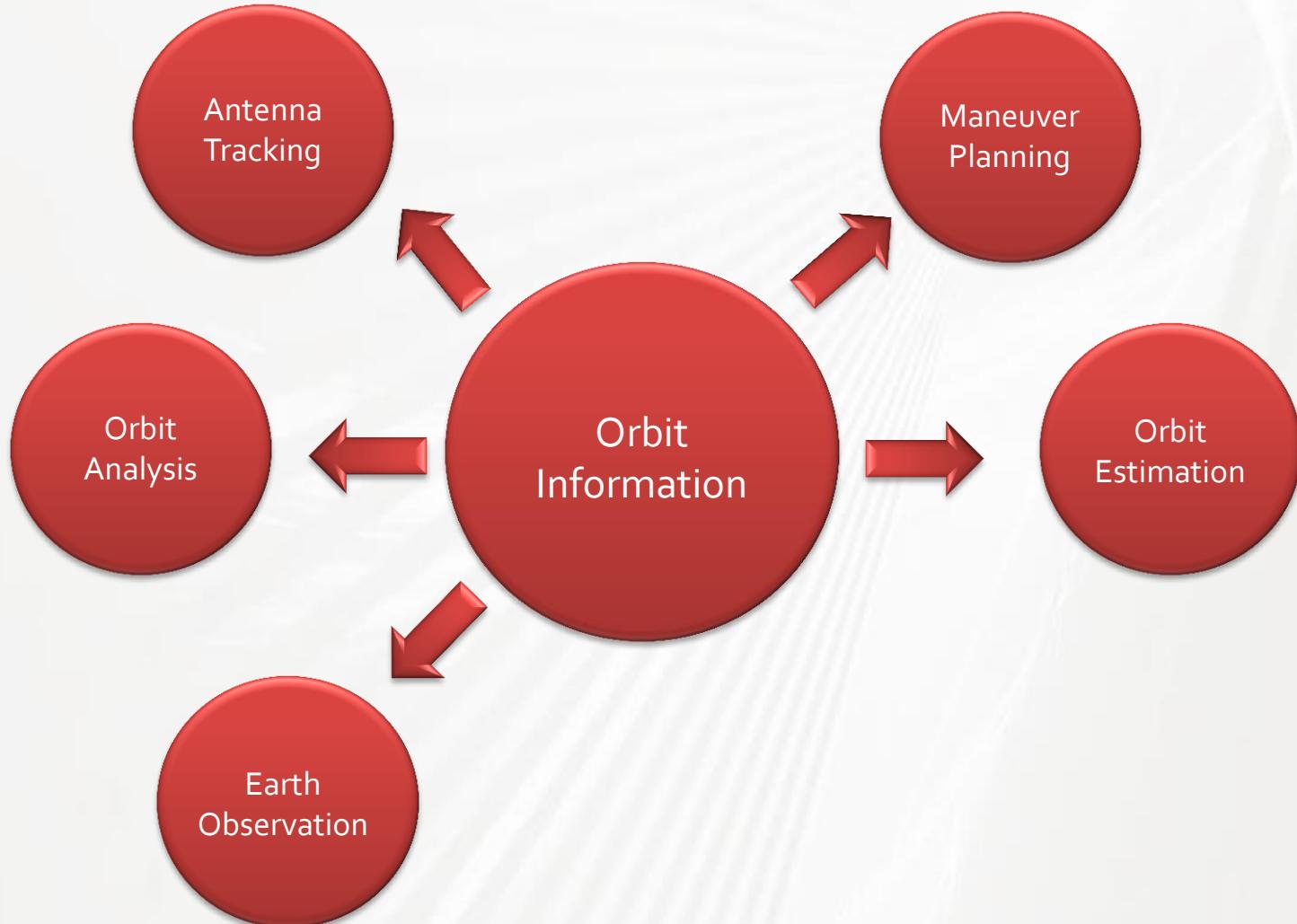
Use-Cases



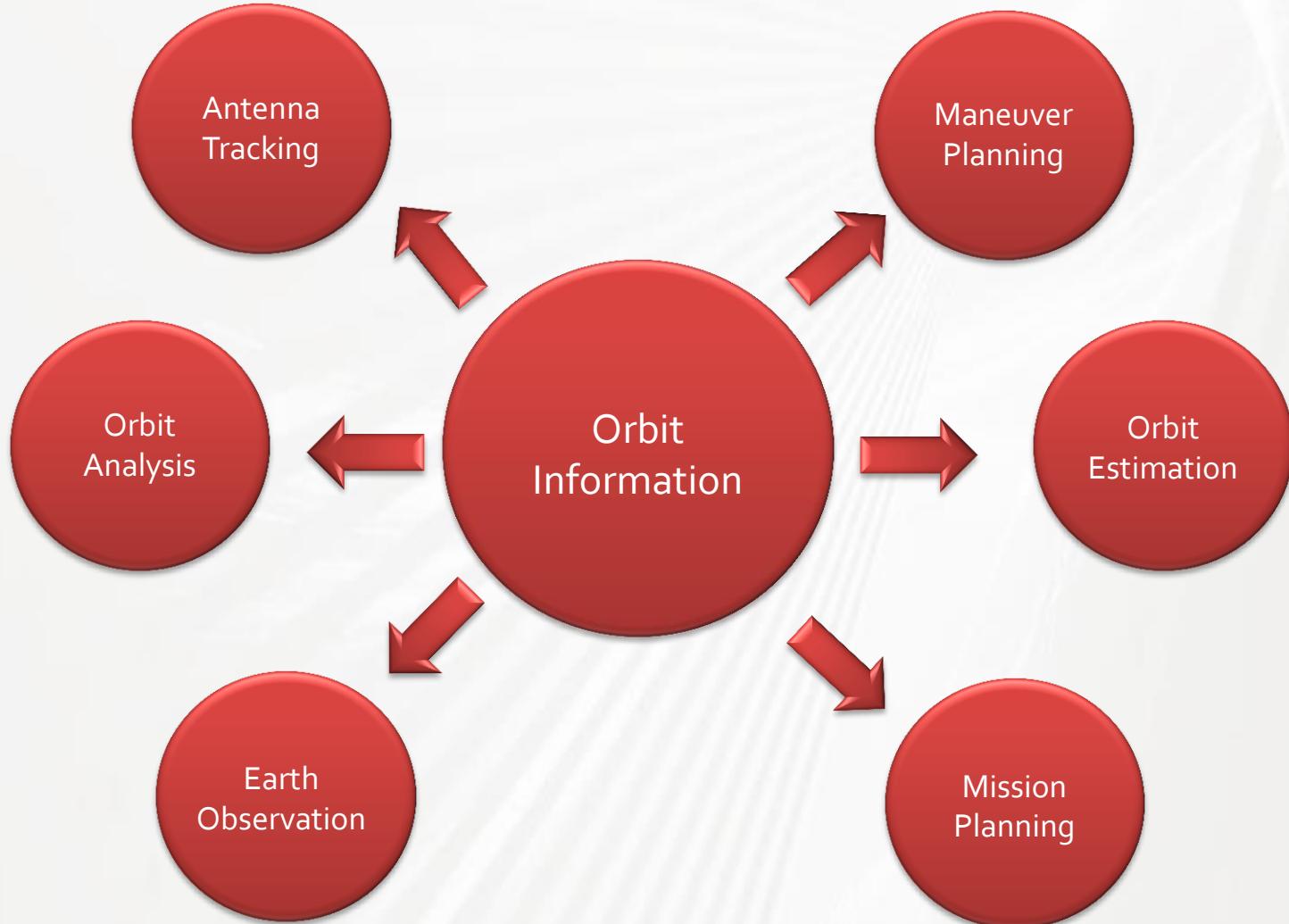
Use-Cases



Use-Cases



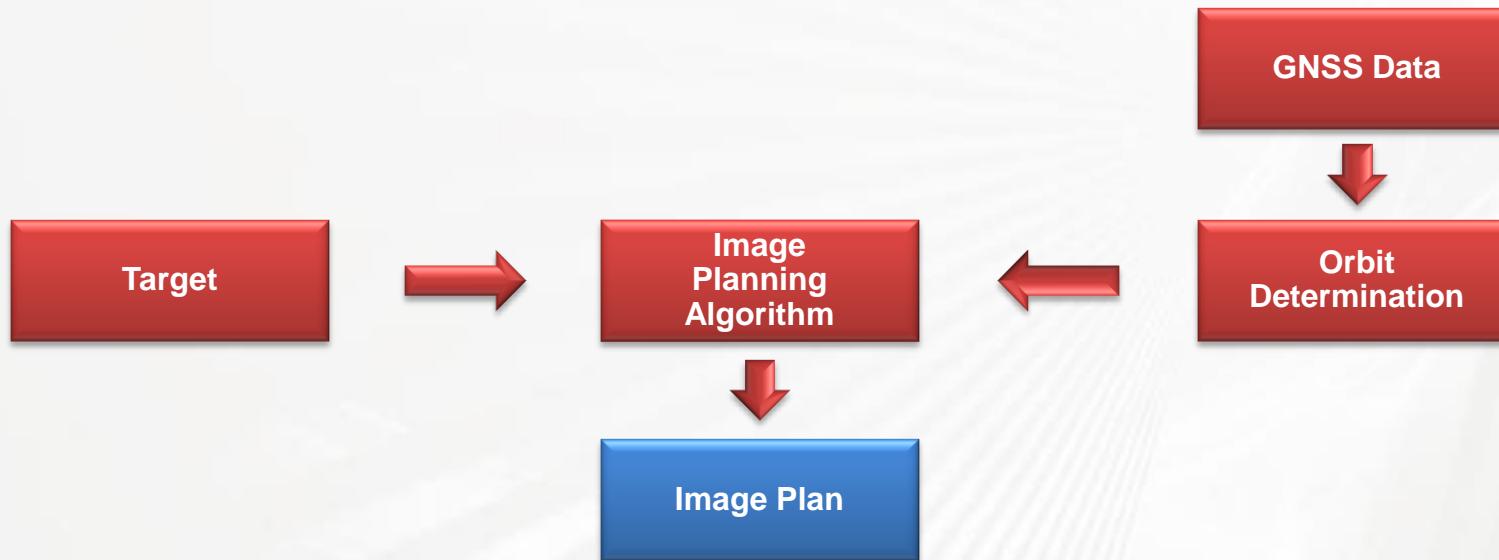
Use-Cases



Earth Observation



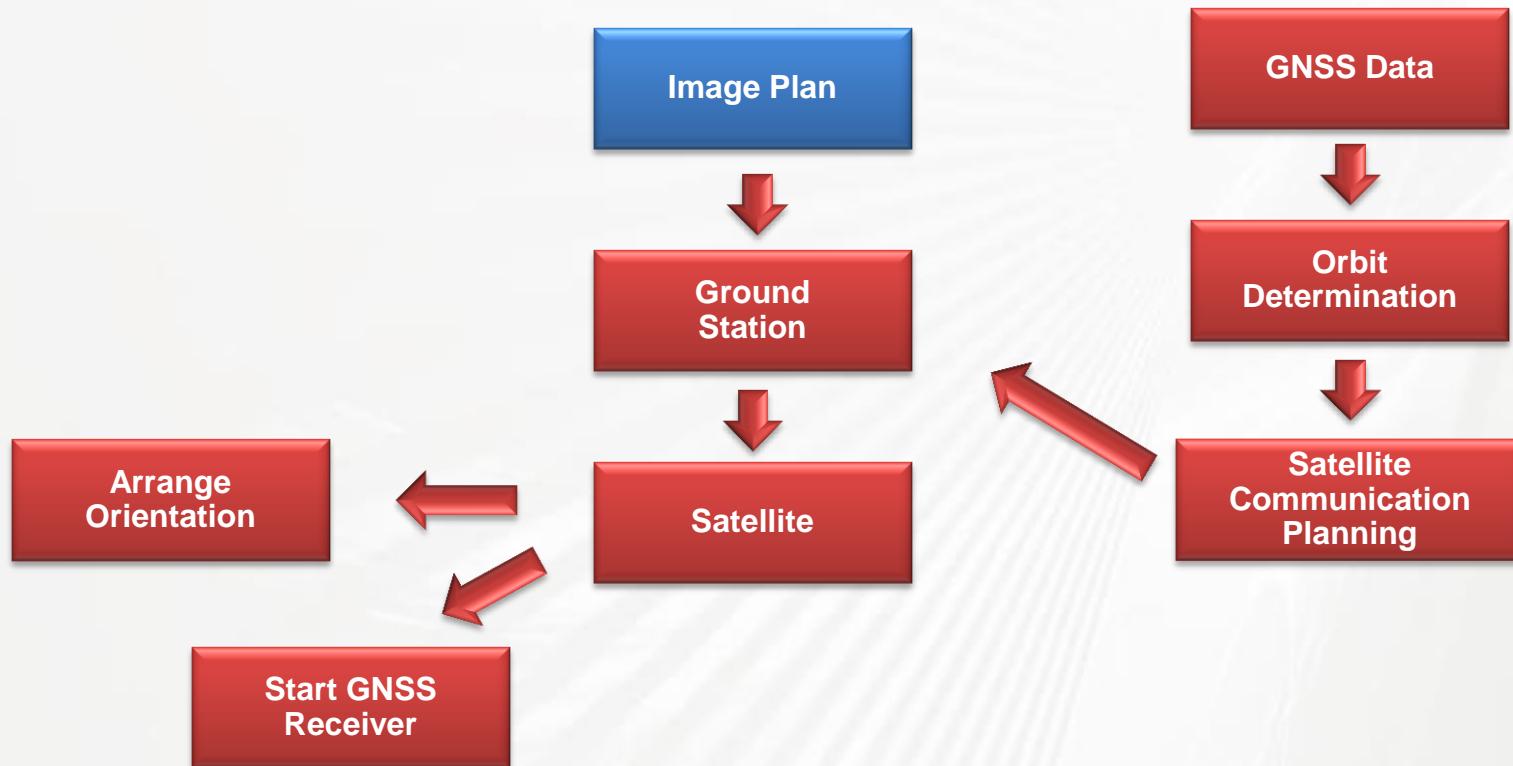
Earth Observation



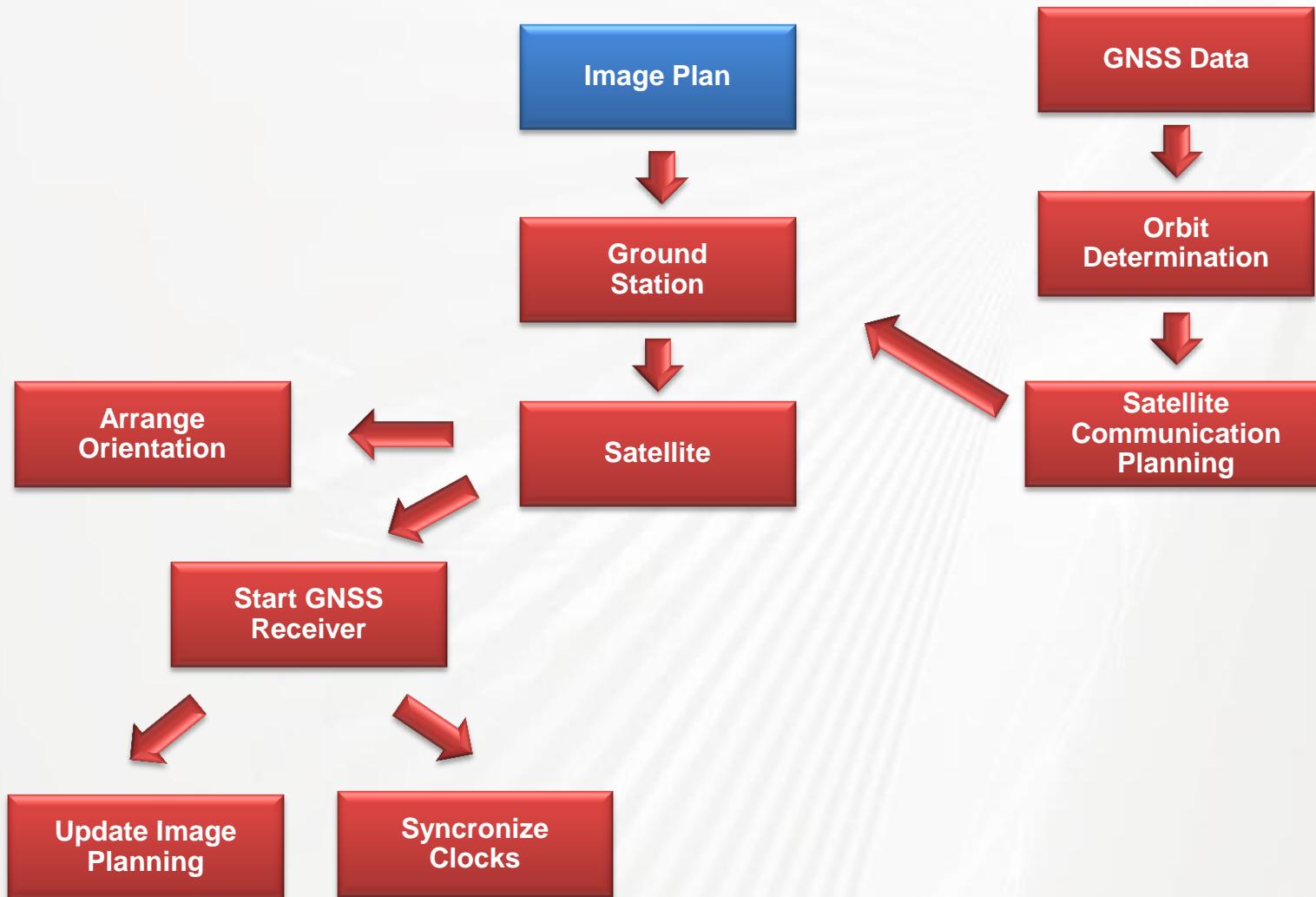
Earth Observation



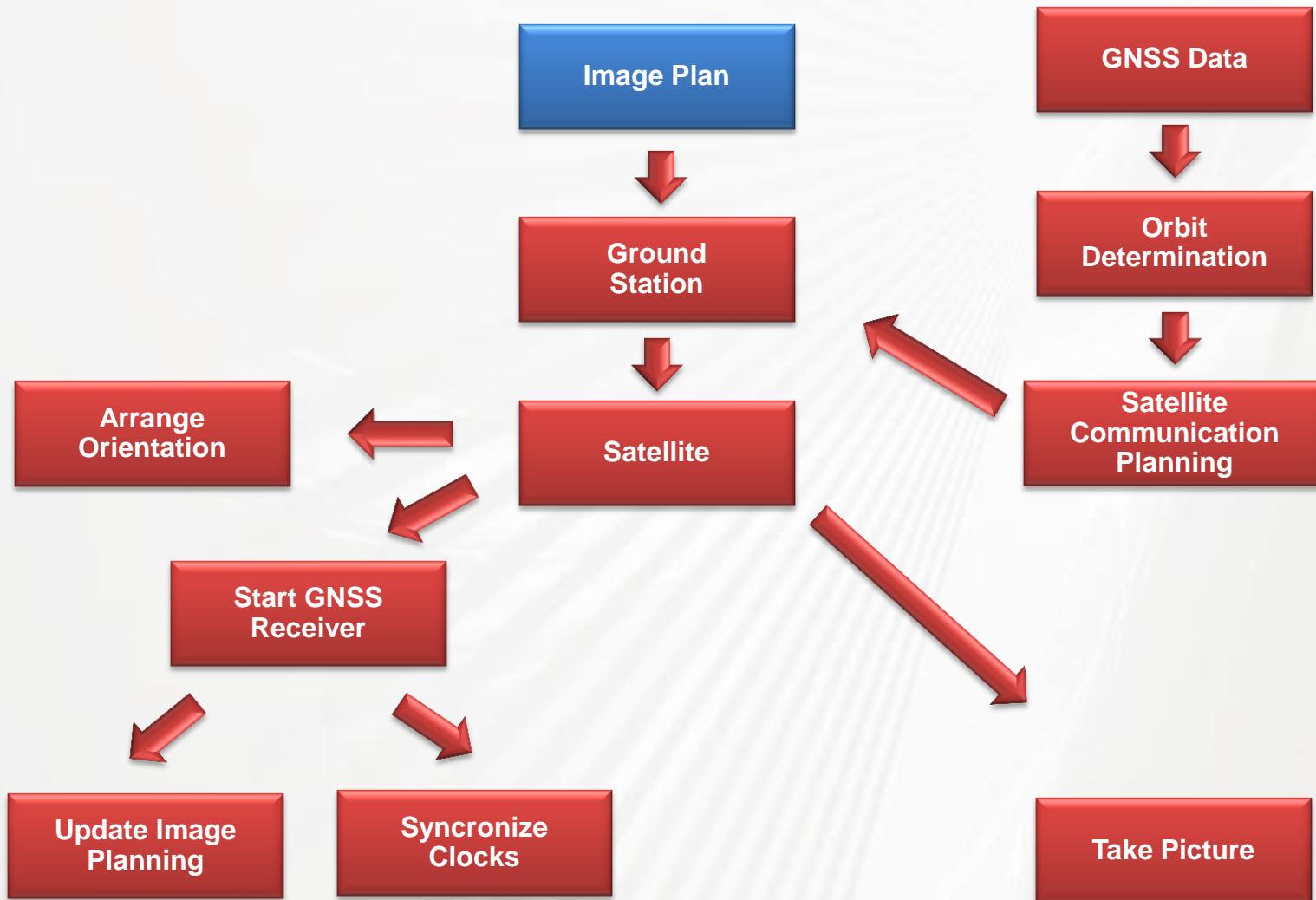
Earth Observation



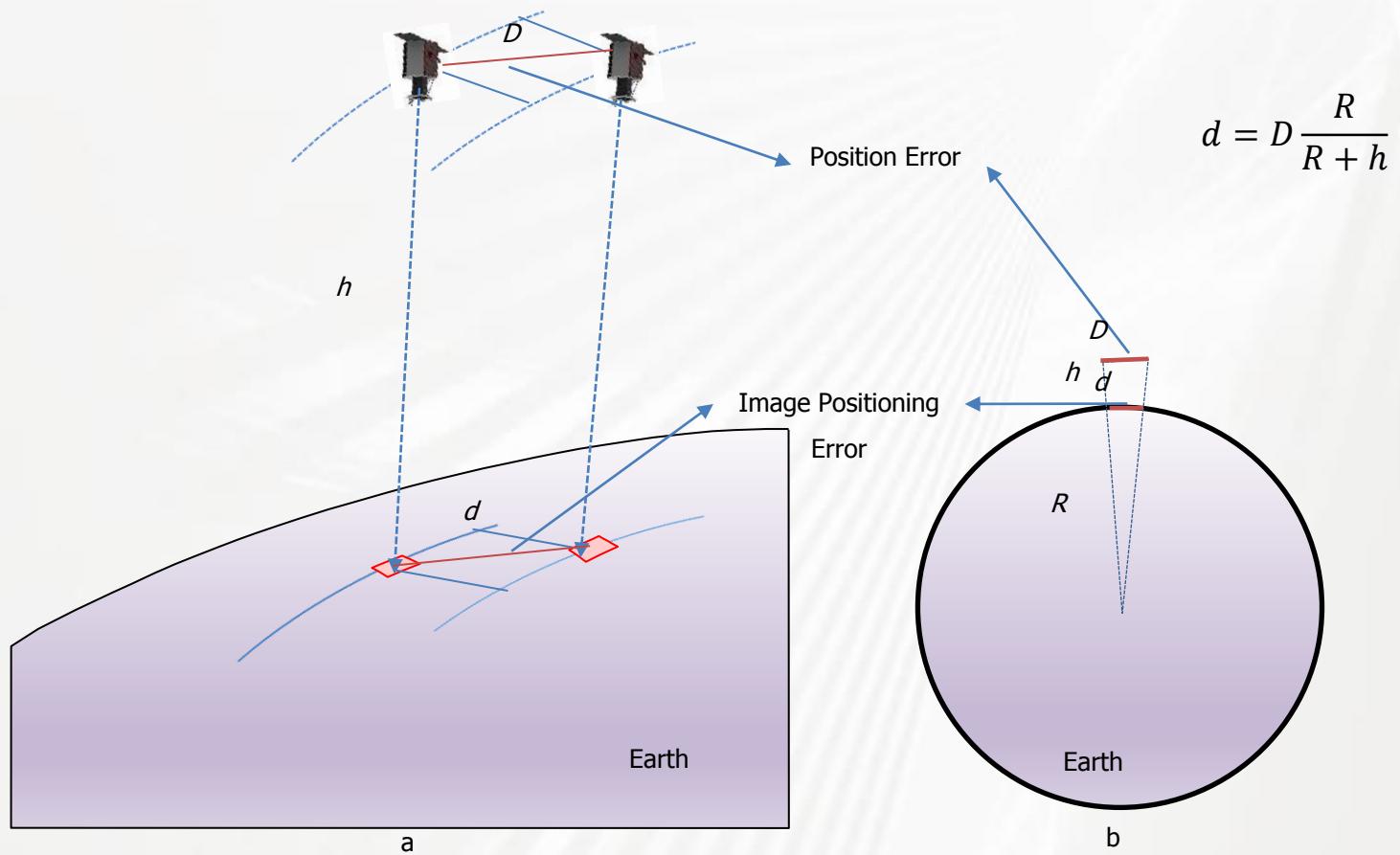
Earth Observation



Earth Observation



Performance Needs – Earth Observation



Performance Needs – Earth Observation

5m along
track
position
error



4.94m
image
positioning
error

1 microsecond
time error



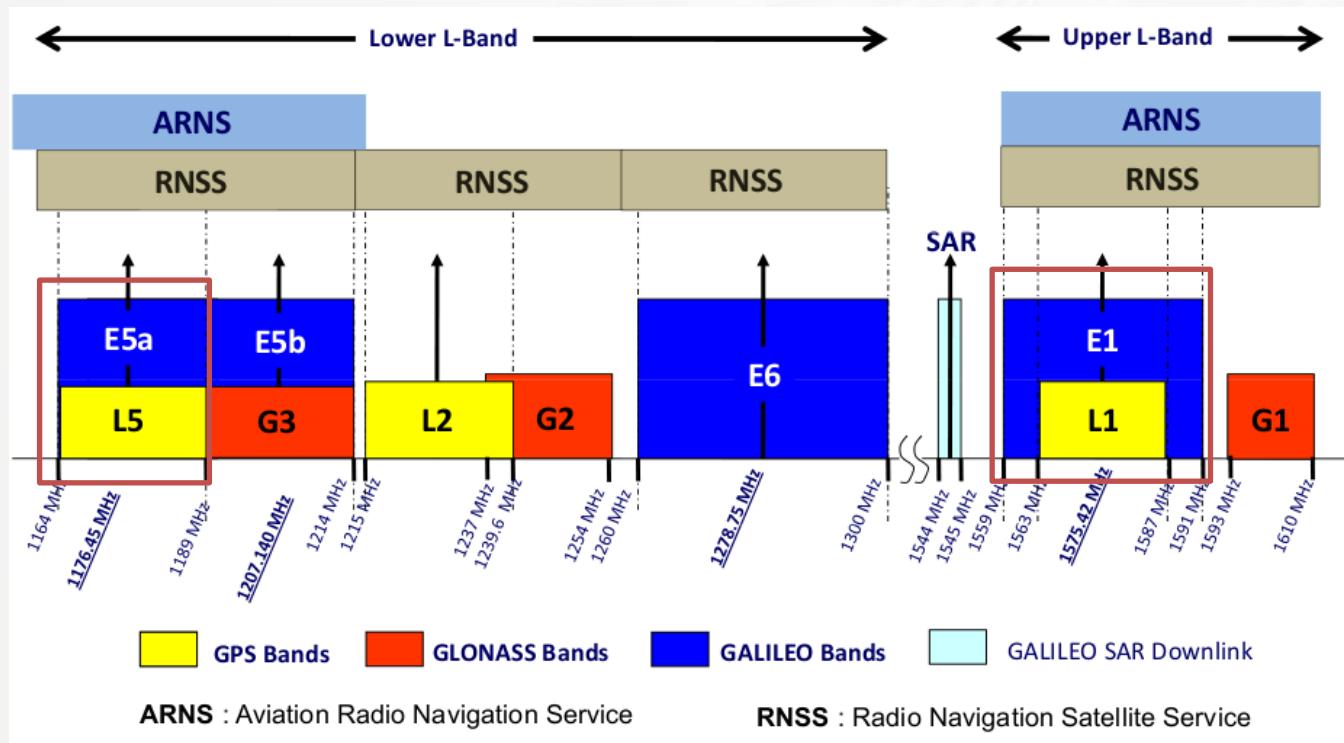
6.95m
image
positioning
error

Orbit Estimation

- On board Orbit Estimation
 - Computationally efficient
 - Low memory usage
 - No external information
 - Real-time and moderate accuracy
- On ground Orbit Estimation
 - No restriction on computation
 - No restriction on memory
 - External Information (Ionosphere and Ephemeris Correction)
 - Post processing and high accuracy

GNSS Receiver

- Multi Frequency and Multi Constellation
 - GPS & Galileo



GNSS Receiver

- For Low Earth Orbit Satellite

	L1, L5, E1, E5a	L1, E1
Position (3D - RMS)	1 m	10 m
Velocity	0.001 m/s	0.01 m/s
Time	60 ns	60 ns

Conclusion

GNSS

USER

DEVELOPER