

Enabling Multi-Constellation Advanced Receiver Autonomous Integrity Monitoring (ARAIM)

**International Committee
on GNSS (ICG-5)**

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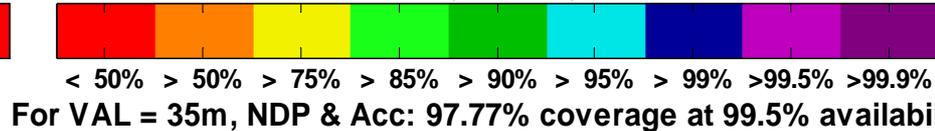
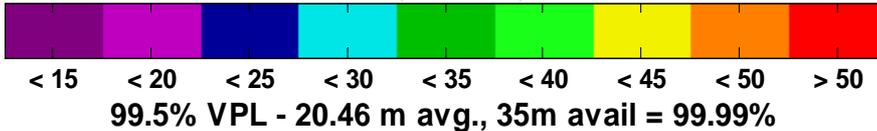
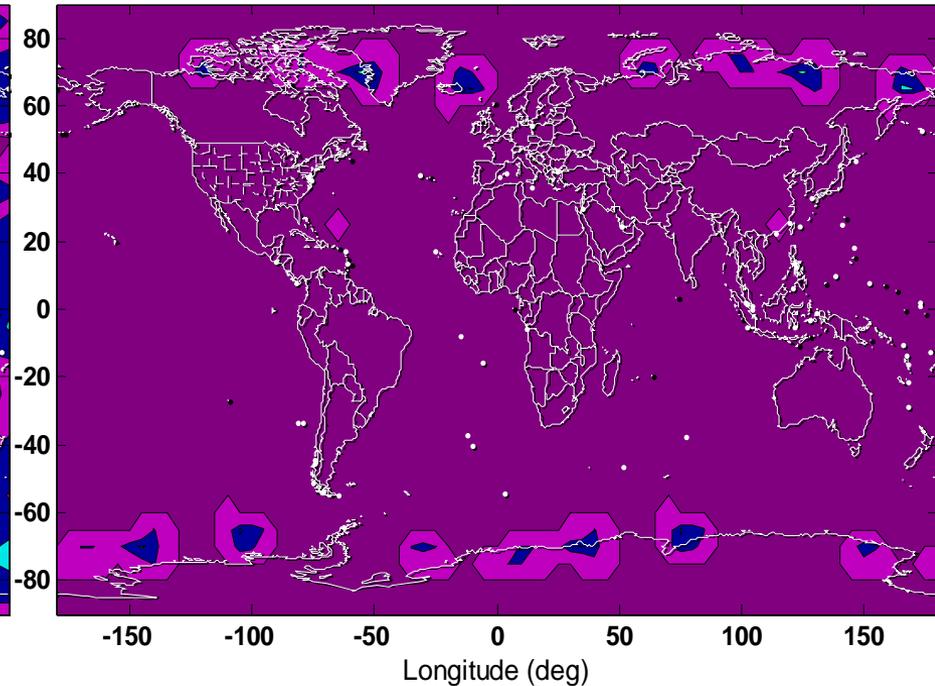
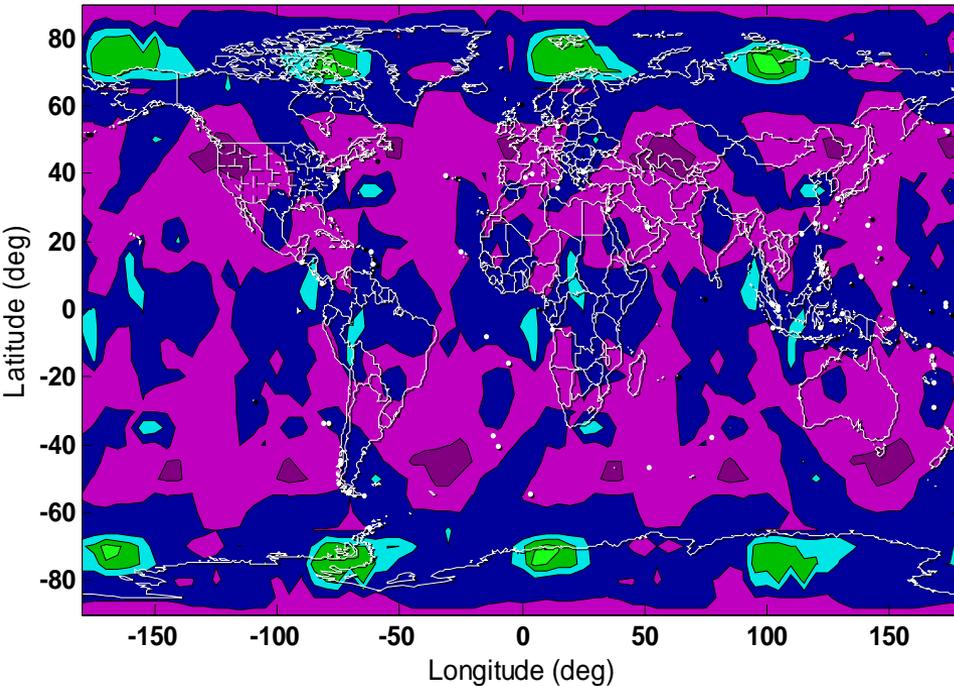
ARAIM Overview

- **GNSS Evolutionary Architecture Study (GEAS) Phase II Report Recommendations**
 - Development of dual frequency SBAS
 - Development of architectures and algorithms for Advanced Receiver Autonomous Integrity Monitoring (ARAIM), based on
 - Dual frequency ARNS (L1 and L5) signals
 - At least two independent GNSS core constellations for civil aviation.
- **GEAS determined ARAIM could enable worldwide LPV-200 performance, provided:**
 - Measurement redundancy and geometric diversity was assured
 - Results based on assumed knowledge of specific “parameters” for the core GNSS constellations

ARAIM Results for 30 SVs & URA = .5 m

URA = 0.5m, Bias = 0.5m

URA = 0.5m, Bias = 0.5m, URE = 0.25m, rBias = 0.1m

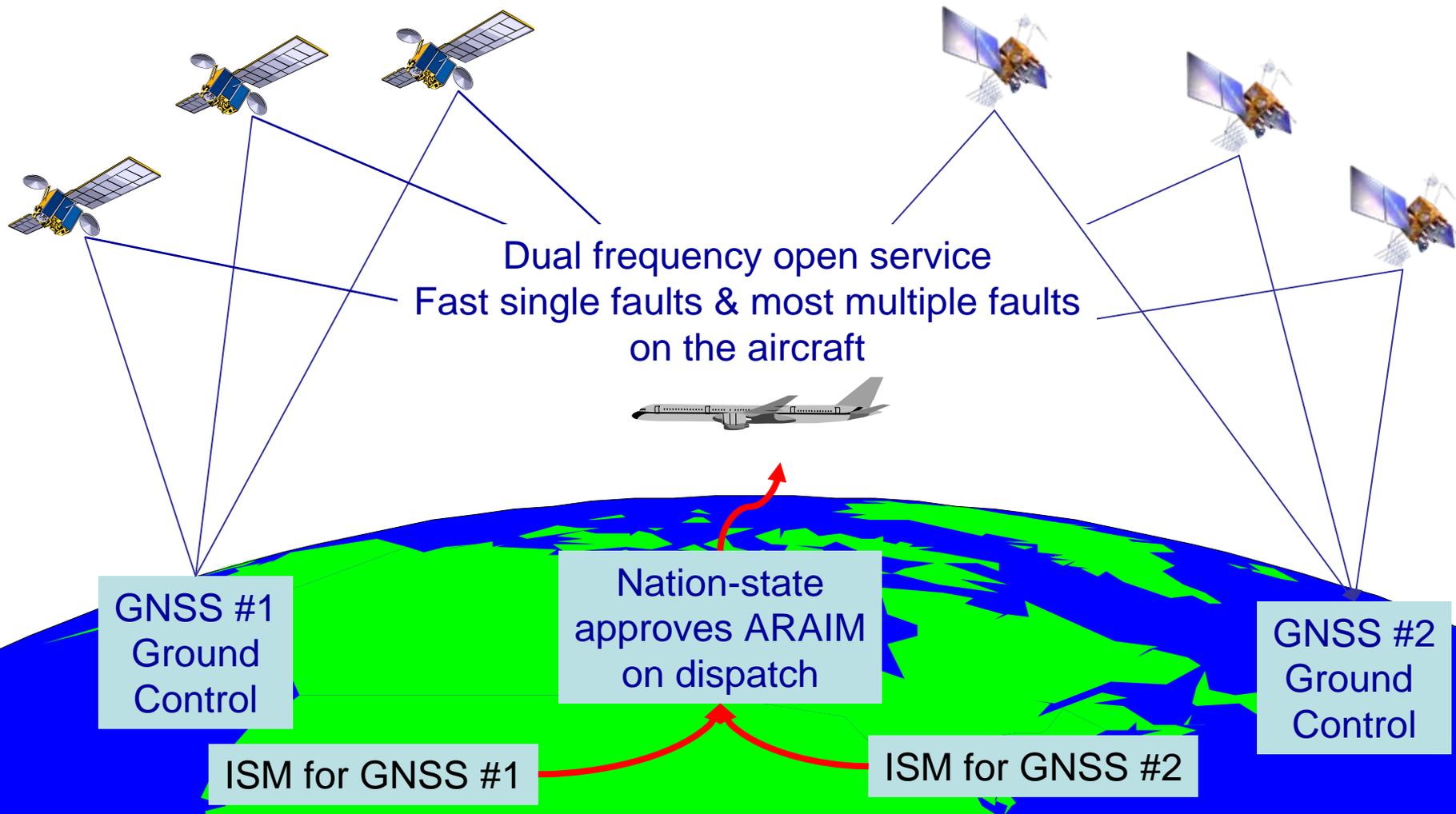


ARAIM currently predicated upon a user update rate of ~ 1hour

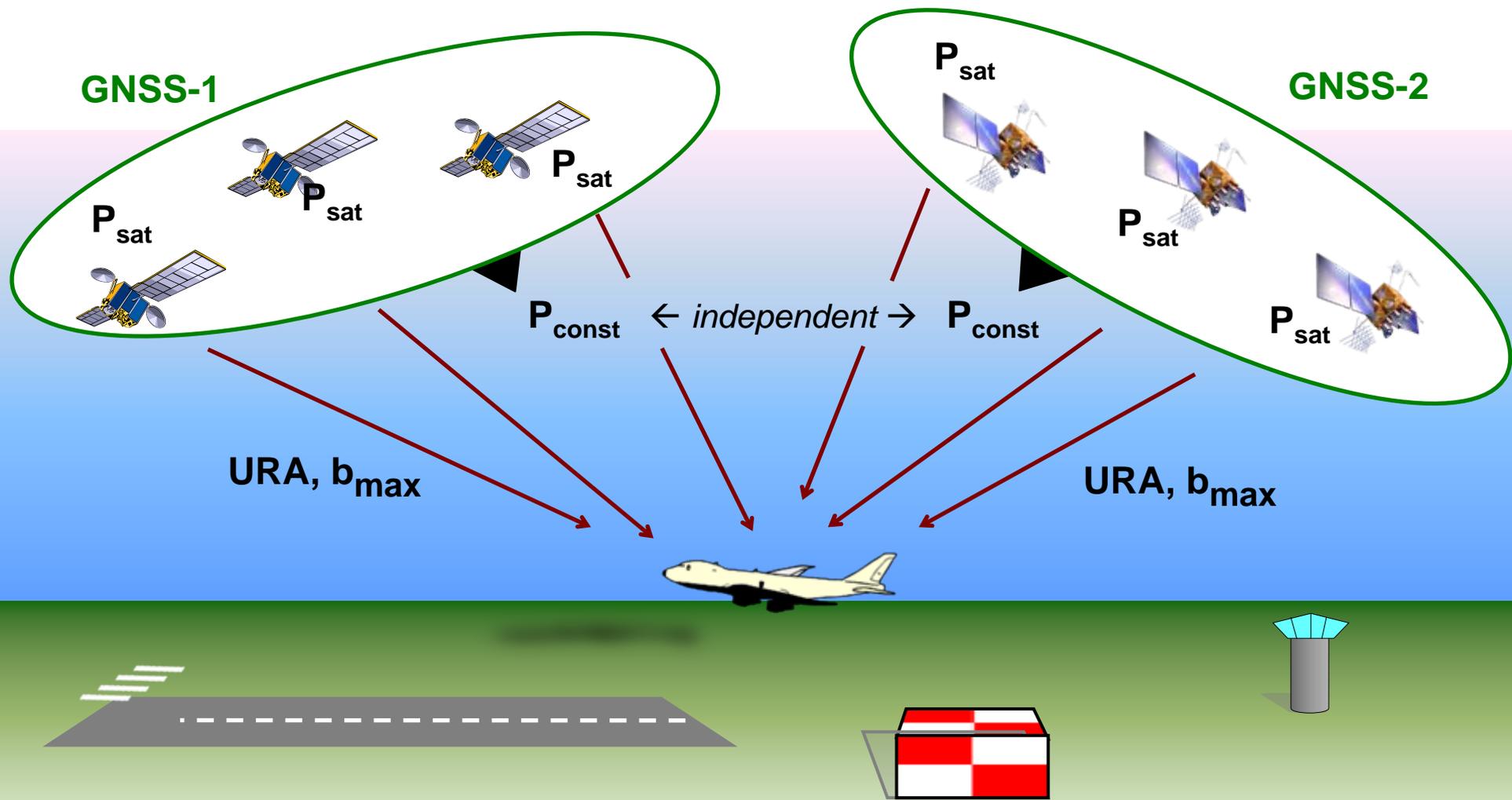
Performance Parameters for ARAIM

- **ARAIM depends on GNSS specific constellation performance parameters:**
 - ① Bounding of fault-free clock and ephemeris error distributions
 - ② Prior probability of SV faults
 - ③ Independence of faults between core constellations.
- **ARAIM users receive an integrity support message (ISM)**
 - GNSS service provider provides ISM to aviation users directly
 - ARAIM ISM generated by civil aviation authority with independent monitoring capability and broadcast to users

Integrity Support Message (ISM)



ARAIM Parameters



Example: Worldwide coverage results

less accuracy (URA) →

Less constellation reliability

Less satellite reliability ↓

P_{sat}/URA	.5 m	1 m	1.5m	2 m	3 m	3.5 m	4 m
10^{-5}	100%	100%	100%	100%	100%	42.9%	3.4%
10^{-4}	100%	100%	100%	100%	100%	0	0
10^{-3}	100%	100%	100%	99.6%	6.6%	0	0
10^{-5}	100%	100%	95.0%	51.5%	0	0	0
10^{-4}	100%	100%	95.0%	51.5%	0	0	0
10^{-3}	100%	100%	95.0%	51.3%	0	0	0
10^{-5}	100%	98.5%	79.2%	.1%	0	0	0
10^{-4}	100%	98.5%	79.2%	.1%	0	0	0
10^{-3}	100%	98.5%	79.2%	.1%	0	0	0

$P_{const} < 10^{-8}$

$P_{const} = 10^{-6}$

$P_{const} = 10^{-4}$

GPS 27 + Galileo 27

P_{sat} = Prob. of satellite fault

P_{const} = Prob. of constellation fault

$b_{max} = 0.75$ m

Parameters Needed From GNSS Provider

- **User Range Accuracy** → ‘URA’
 - Standard deviation of the overbounding Normal distribution for clock and ephemeris errors
- **Bias parameter** → ‘ b_{\max} ’
 - May be needed to bound potential non-zero mean error distributions
- **Fault state probability (fault-rate × time-to-notify)** → ‘ P_{sat} ’
 - Needed for faults that are independent between satellites
- **Probability of constellation-wide fault** → ‘ P_{const} ’
 - For multiple faults that are not independent between satellites
 - Example is Earth Orientation Parameter (EOP) fault undetected by GNSS ground system

Summary

- **Four basic parameters are needed to enable ARAIM integrity:**
 - URA and b_{\max} to describe nominal performance of clock and ephemeris
 - Prior probability of satellite fault
 - Prior probability of constellation failure
- **A common understanding of these parameters must be developed and agreed upon by the service providers for interoperability**
- **ISM is a mechanism to deliver these parameters to users**
- **Delivery of ISM could be from multiple sources**
- **GNSS service providers need to include these parameters in Performance Standards**