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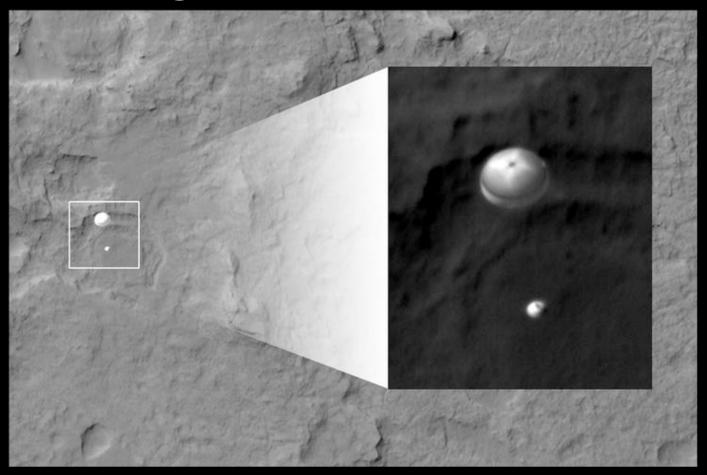
NASA/JPL-Caltech/MSSS



Noah Warner Tactical Uplink Lead

Jet Propulsion Laboratory California Institute of Technology February 12, 2013

Curiosity landed on Mars August 5, 2012 (PDT)



The HiRISE camera on the Mars Reconnaissance Orbiter took this action shot of Curiosity descending on the parachute!

Touchdown with the Sky Crane Landing System

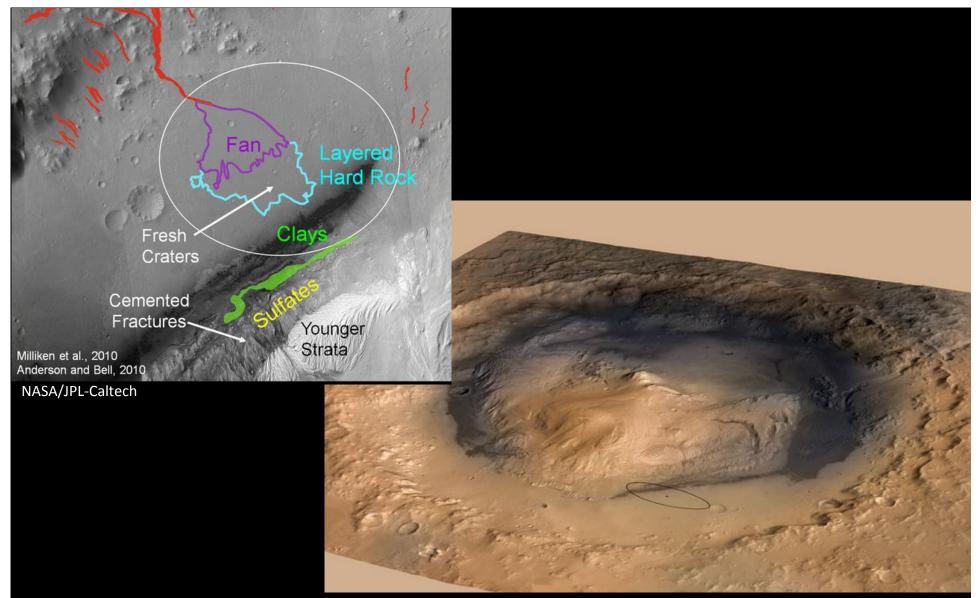
Curiosity's primary scientific goal is to explore and quantitatively assess a local region on Mars' surface as a potential habitat for life, past or present

- Biological potential
- Geology and geochemistry
- Role of water
- Surface radiation



Curiosity's Science Objectives

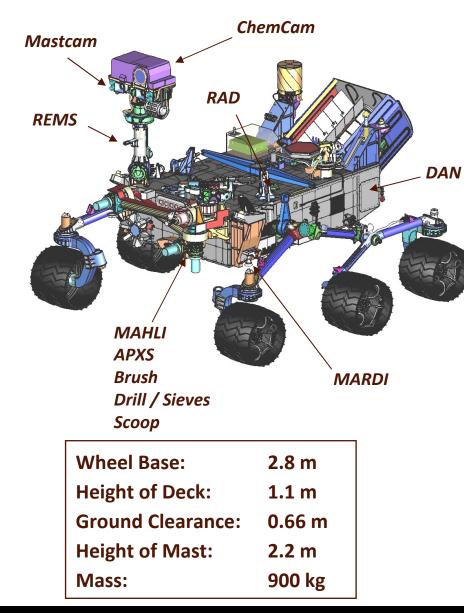
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Target: Gale Crater and Mount Sharp



REMOTE SENSING

Mastcam (M. Malin, MSSS) - Color and telephoto imaging, video, atmospheric opacity

ChemCam (R. Wiens, LANL/CNES) – Chemical composition; remote micro-imaging

CONTACT INSTRUMENTS (ARM)

MAHLI (K. Edgett, MSSS) – Hand-lens color imaging

APXS (R. Gellert, U. Guelph, Canada) - Chemical composition

ANALYTICAL LABORATORY (ROVER BODY)

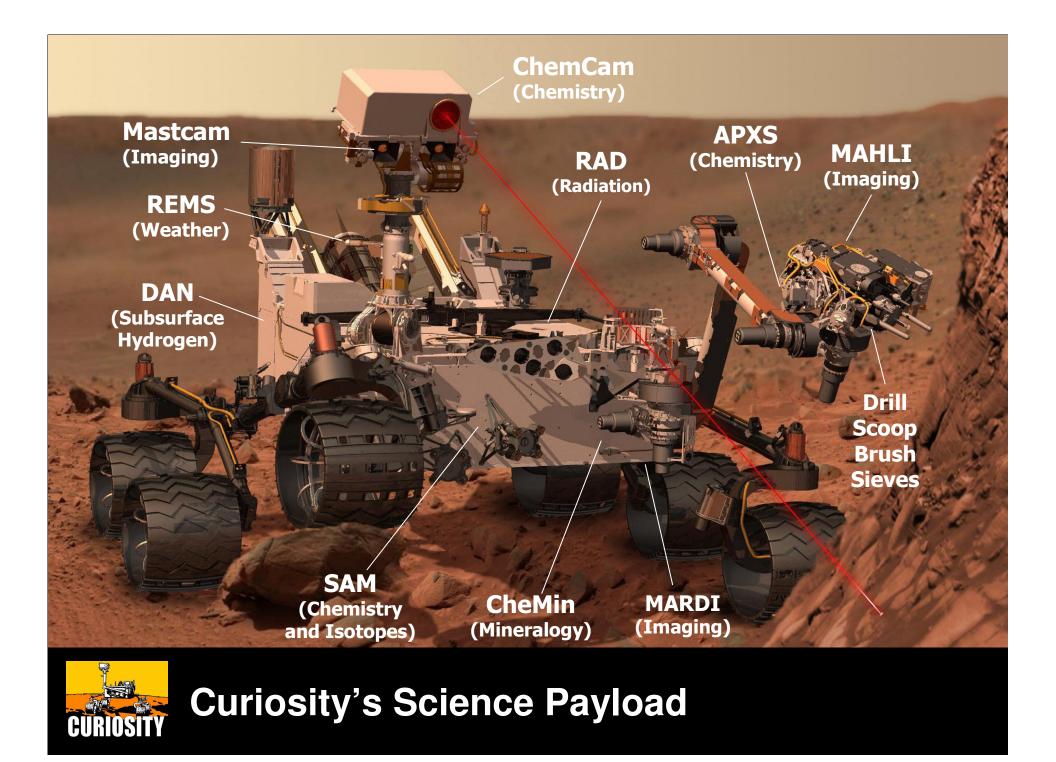
SAM (P. Mahaffy, GSFC/CNES/JPL-Caltech) - Chemical and isotopic composition, including organics **CheMin** (D. Blake, ARC) - Mineralogy

ENVIRONMENTAL CHARACTERIZATION

MARDI (M. Malin, MSSS) - Descent imaging
REMS (J. Gómez-Elvira, CAB, Spain) - Meteorology / UV
RAD (D. Hassler, SwRI) - High-energy radiation
DAN (I. Mitrofanov, IKI, Russia) - Subsurface hydrogen



Curiosity's Investigation Teams



First Observations at Bradbury Landing



NASA/JPL-Caltech/MSSS



Mastcam-34 mosaic of Mount Sharp, descent rocket scours, and rover shadow





Navigation camera panorama of Bradbury Landing



The Multi-Mission Radioisotope Thermoelectric Generator (MMRTG) on Curiosity was selected to:

•maintain rover electronics and science instruments within their specific thermal limits

The MMRTG waste heat is used by the rover's thermal subsystem

•allow operations of the rover at any latitude, enabling the consideration of the largest set of landing sites possible

•enables the greatest number of science samples from all possible landing sites considered by the Mars Program

•enable operations during the day or night

•enable navigation through challenging terrain without considering the view to the Sun

•enable science operations throughout the Martian year



Curiosity on Mars with a Nuclear Power Source (NPS)

Stretching Out the Arm

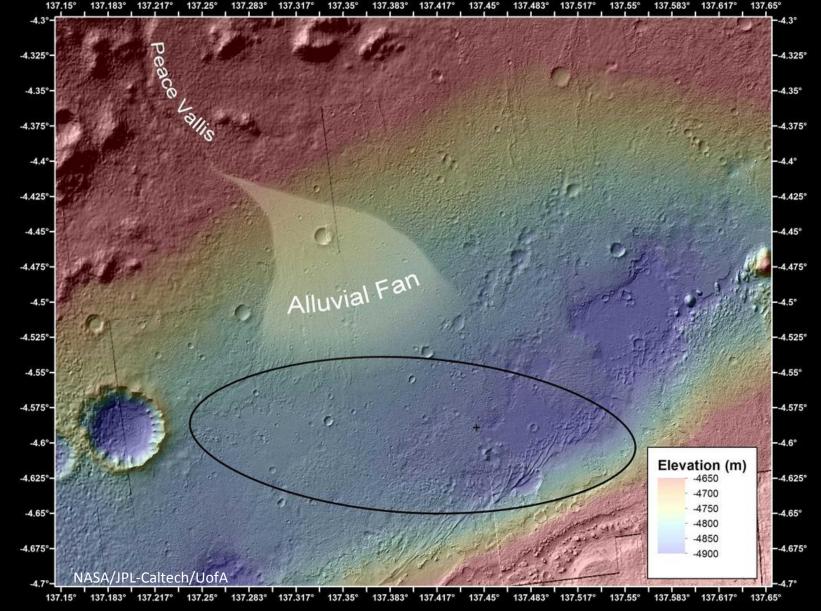


Driving!





Science results thus far reveals an ancient streambed, likely originating at the northern crater rim

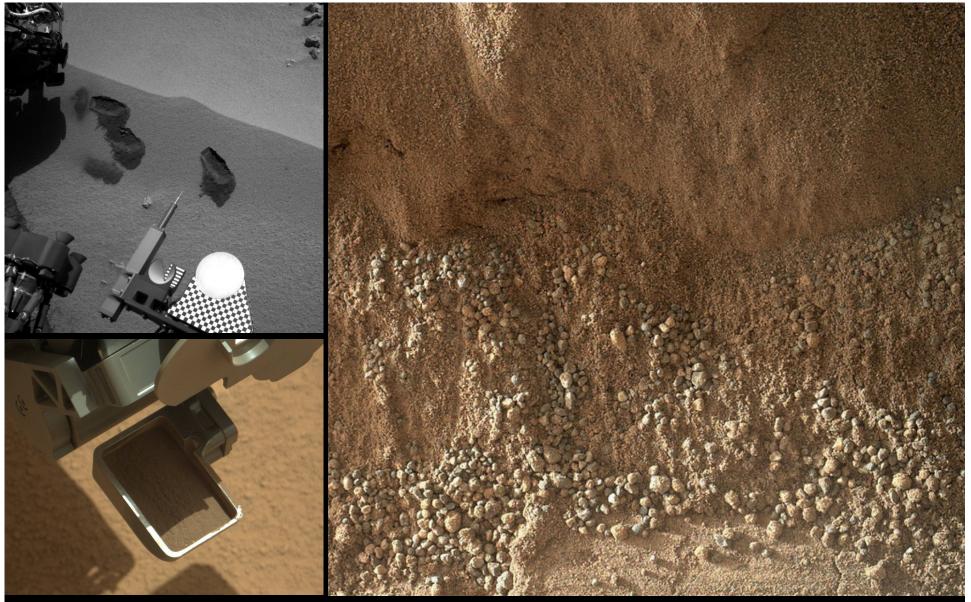


Rocknest Scooping Campaign

Wheel scuff to prepare for safe scooping







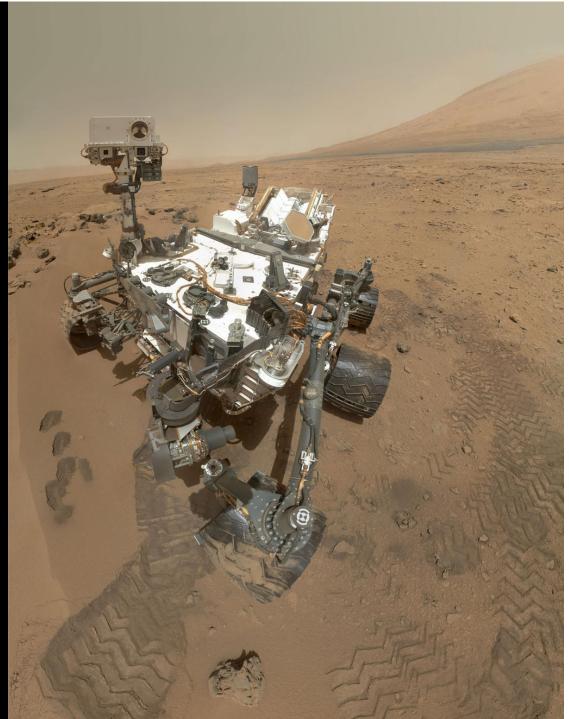
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MAHLI view of coarse (0.5 to 1.5 mm) sand from the ripple's surface, and fine (< 0.25 mm) sand on wall and floor of trench Curiosity self-portrait at Rocknest

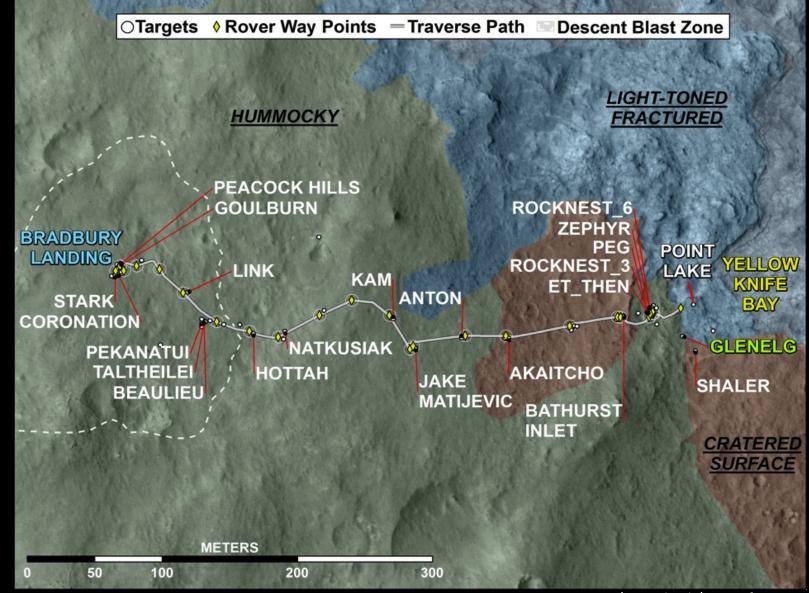
Assembled from 55 MAHLI images

Shows four scoop trenches and wheel scuff





The Glenelg Region and Yellowknife Bay



NASA/JPL-Caltech/Univ. of Arizona



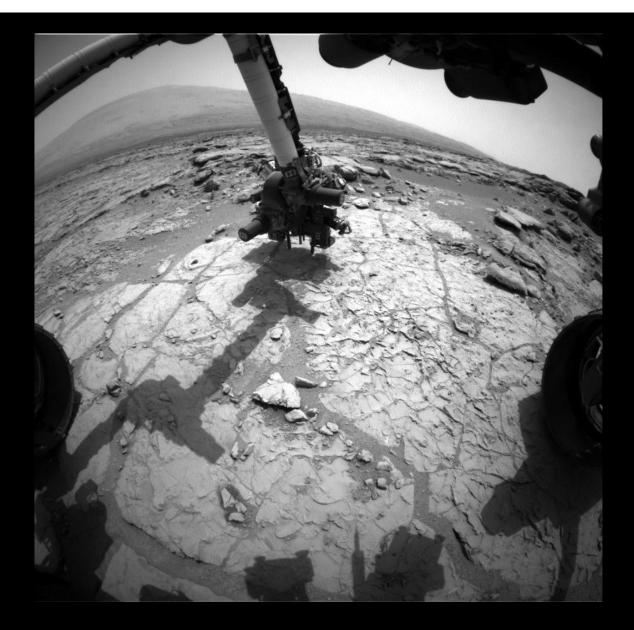
Curiosity is currently exploring Yellowknife Bay, a basin within the Glenelg region

NASA/JPL-Caltech/MSSS

Postcards from Yellowknife Bay showing a diversity of rock types, fractures, and veins









Curiosity's first surface contact with the drill on Mars was in Yellowknife Bay





Curiosity then went on to make her first drill holes on Mars!

Mount Sharp, The Ultimate Destination



NASA/JPL-Caltech/Univ. of Arizona



Curiosity's ultimate goal is to explore the lower reaches of the 5-km high Mount Sharp





This boulder is the size of Curiosity

NASA/JPL-Caltech/MSSS



Layers, Canyons, and Buttes of Mount Sharp

Follow Curiosity as She Explores Gale Crater



Mission Website: mars.jpl.nasa.gov/msl

Twitter: @MarsCuriosity Facebook: MarsCuriosity

Be A Martian! beamartian.jpl.nasa.gov

www.nasa.gov/msl



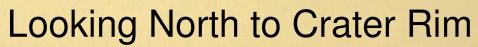
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Backup Slides





"Touchdown confirmed." "Let's see where Curiosity will take us."





Cheers break out in mission control!



NASA/JPL-Caltech





First use of dust-removing brush





The first drill contact was a divot test using our percussive capabilities